ME 627/CEE 627 : Linear Systems Theory
11:45am-1:00pm, Tuesdays and Thursdays, Room TBA
Fall 2015

Michael M. Zavlanos
Department of Mechanical Engineering & Materials Science
Duke University
E-mail: michael.zavlanos@duke.edu

Course Description: This graduate level course focuses on linear system theory in the time domain. The course introduces the fundamental mathematics of linear spaces, linear operator theory, and then proceeds with existence and uniqueness of solutions of differential equations, structural properties of linear systems, and design of linear controllers. The focus is on linear time invariant systems in continuous and discrete time. Topics covered include:

- Introduction: State-space representation, linearization, existence and uniqueness of solutions of linear differential equations
- Review: Linear spaces, eigenvalues, eigenvectors, change of basis, diagonalization, Jordan forms, Cayley-Hamilton theorem, matrix exponential
- Stability: Uniform, asymptotic, and exponential stability, Lyapunov stability theorems
- Controllability and observability: Kalman rank test, PBH test
- State feedback and estimation: Canonical forms, pole placement, observer design
- Optimal control: Riccati equation, Hamiltonian matrix, stability

Prerequisites: Basic knowledge of linear algebra, differential equations, and signals and systems. Undergraduates need permission.

Textbooks and References:

Grading Policy:
Homeworks: 50%
Project: 50%