

# Optimality of Random Regular Graphs for Sparse Network Designs

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Duke University

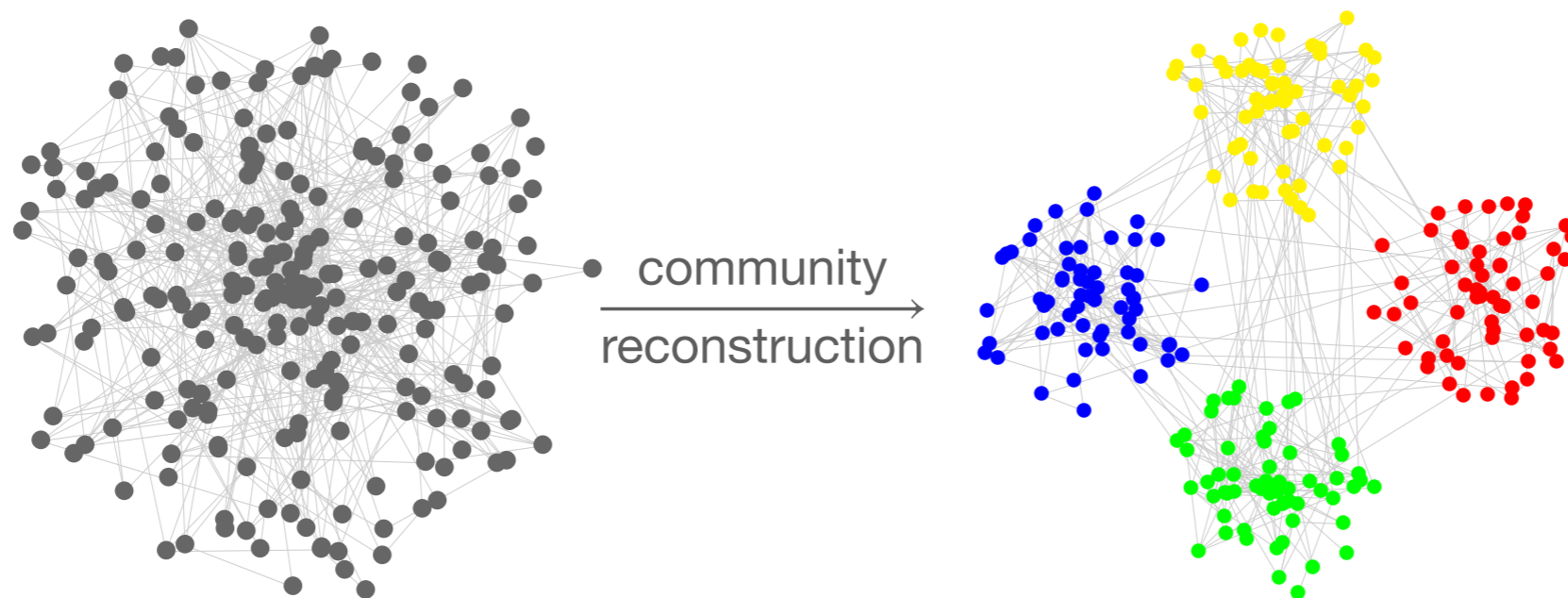
Joint work with

Weijia Li (Tsinghua), Xiaochun (Nora) Niu (Duke), and Yehua Wei (Duke)



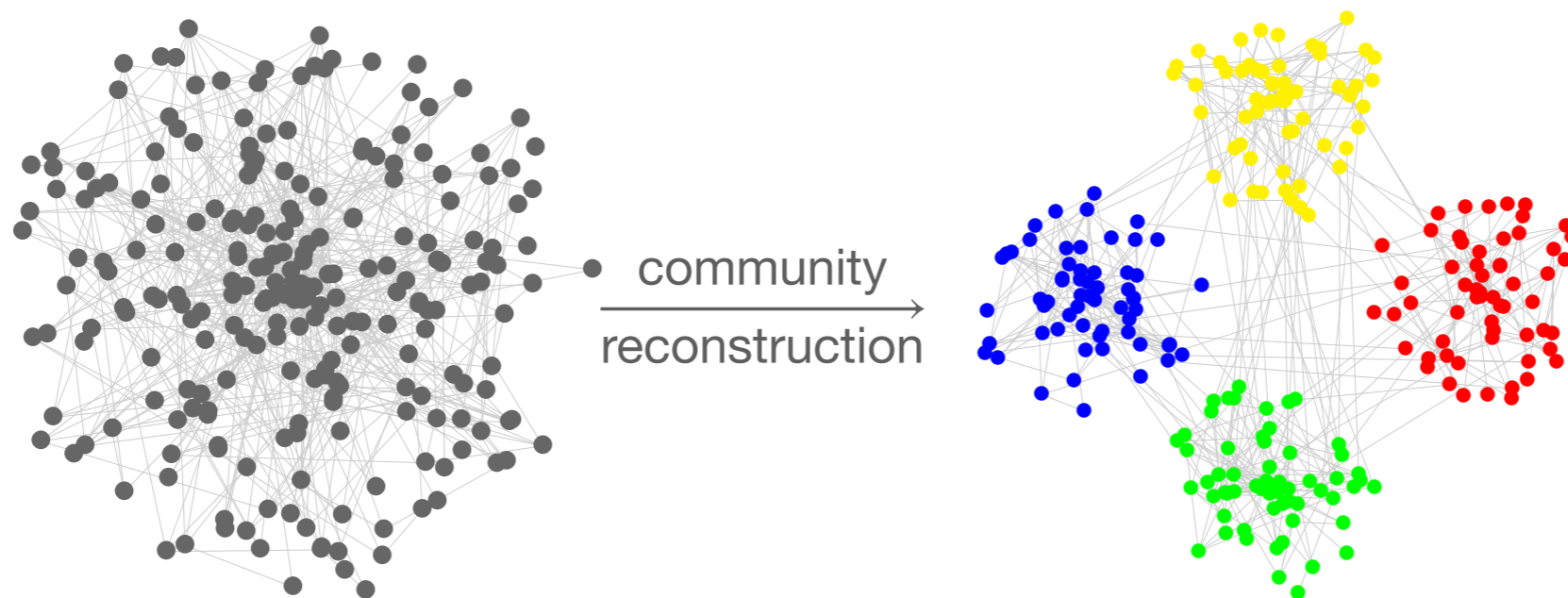
# Network Theory

- Networked systems and network data are everywhere
  - Statistical network analysis: Observe network data  $\longrightarrow$  Infer hidden structures



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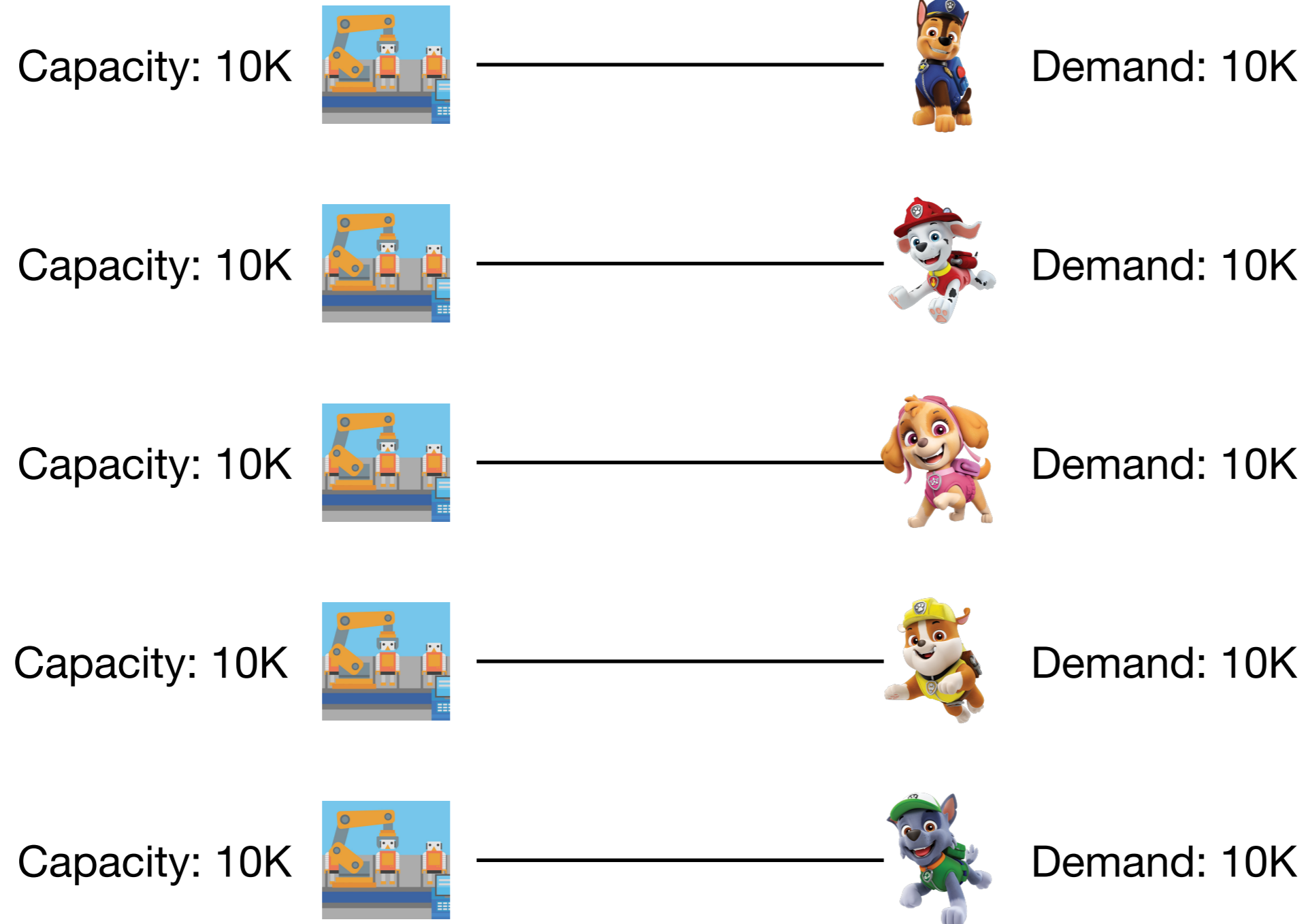
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  - Statistical network analysis: Observe network data  $\longrightarrow$  Infer hidden structures



- Network design: Design network structure  $\longrightarrow$  Enable efficient operations  
(This Talk)

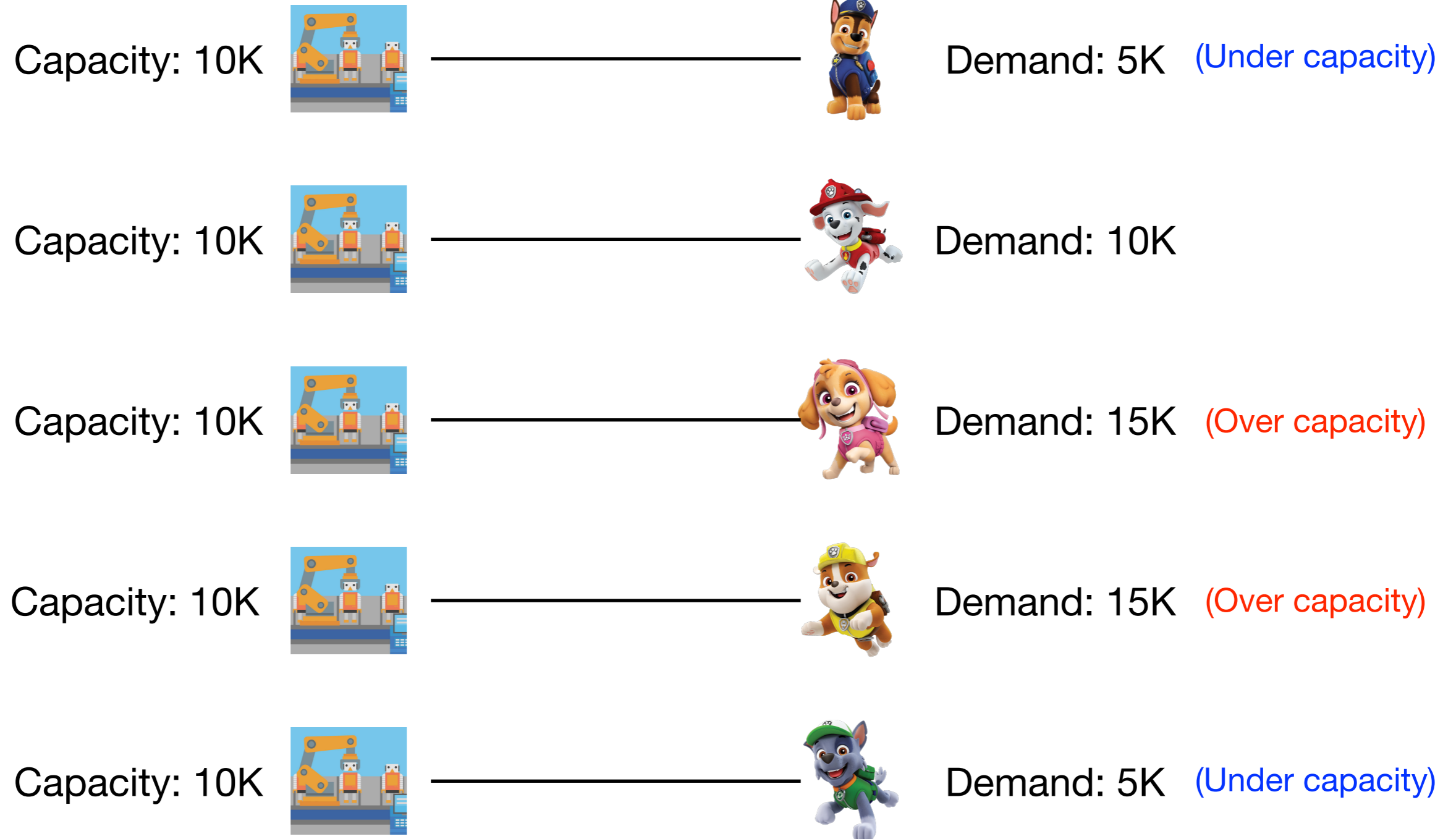
# Flexibility Network Design Under Uncertainty

A Toy Example: Ideal setting



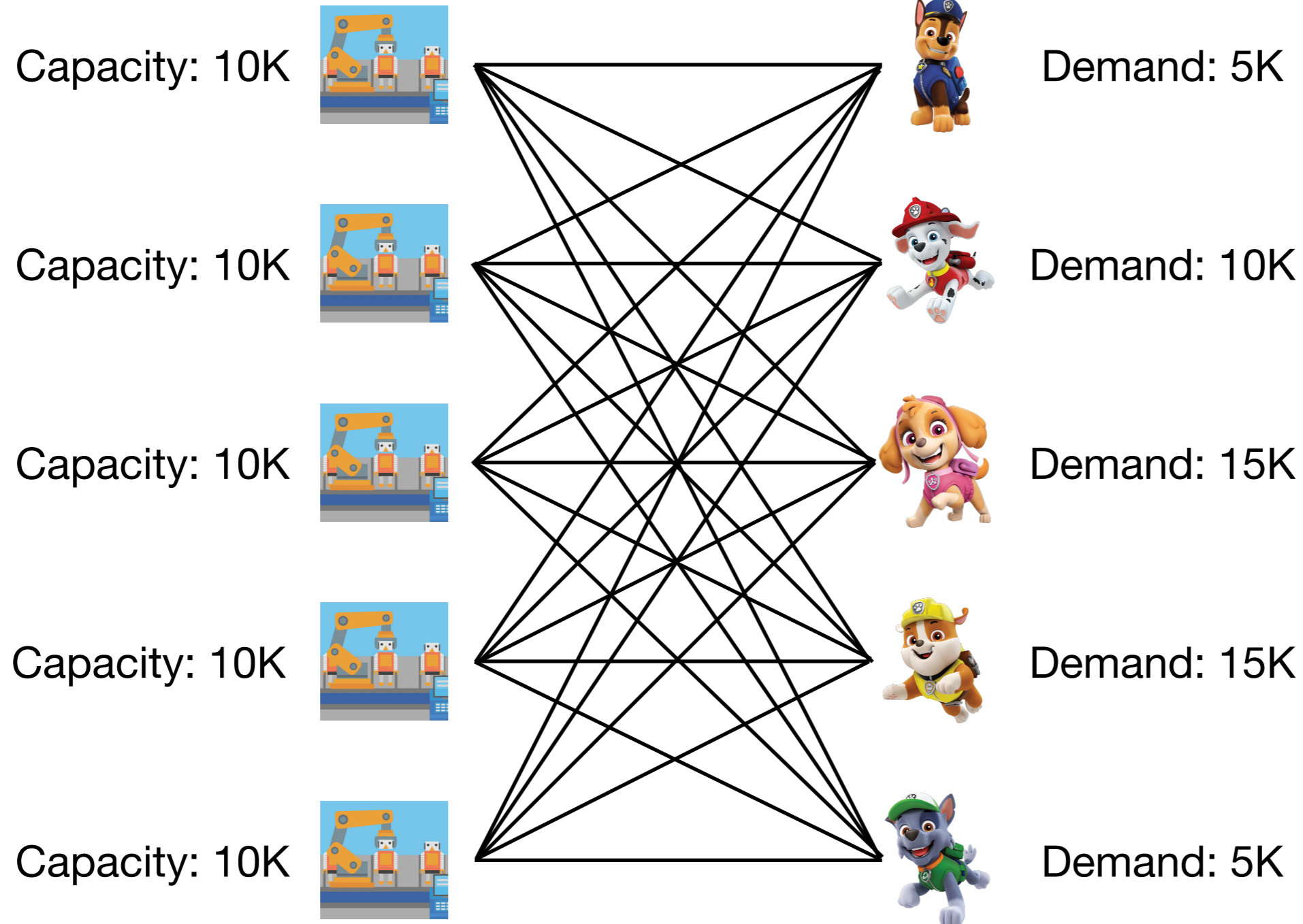
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A Toy Example: Actual demand may change dramatically depending on popularity



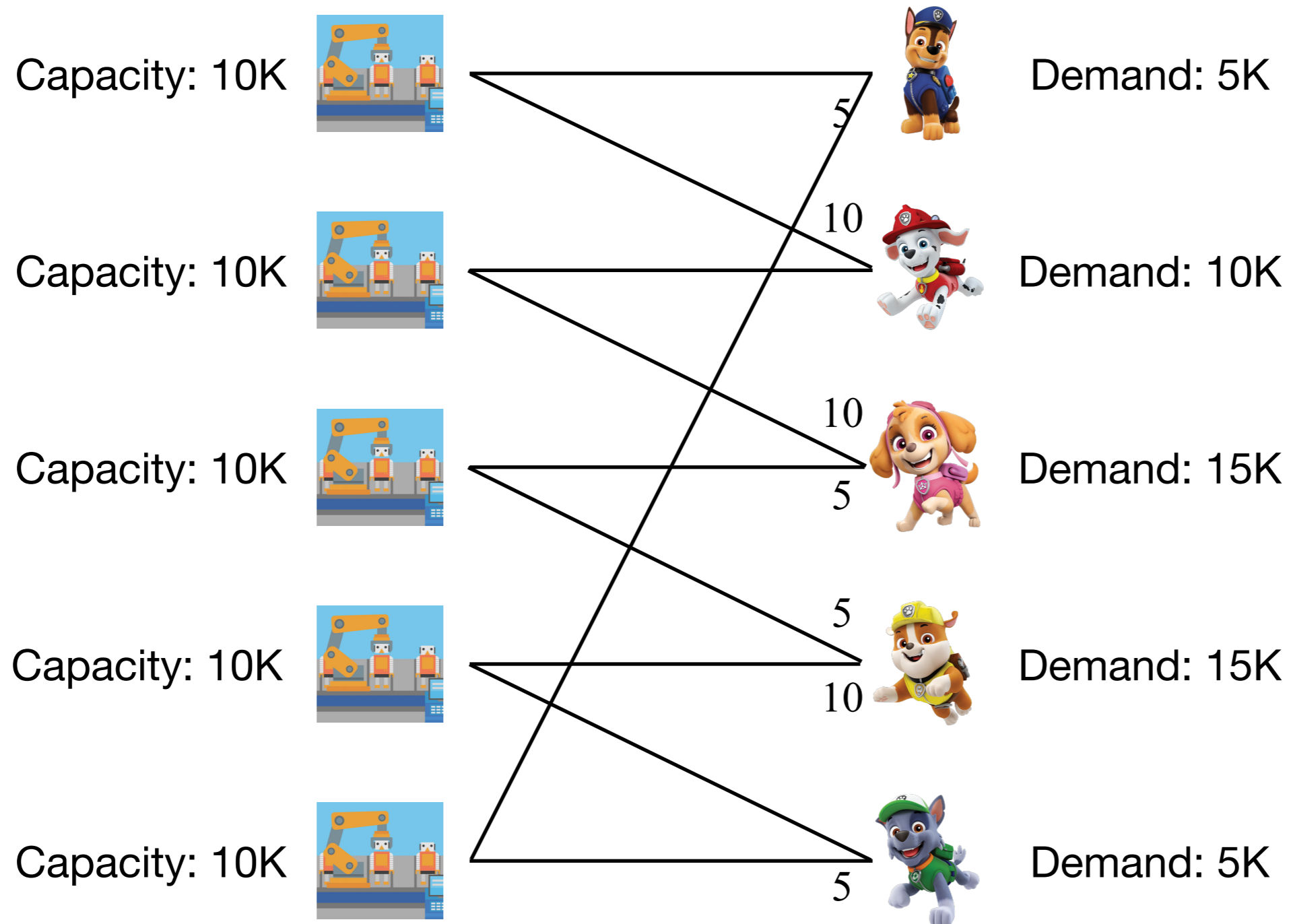
# Flexibility Network Design Under Uncertainty

A Toy Example: Configure all production lines to be fully flexible, but too costly



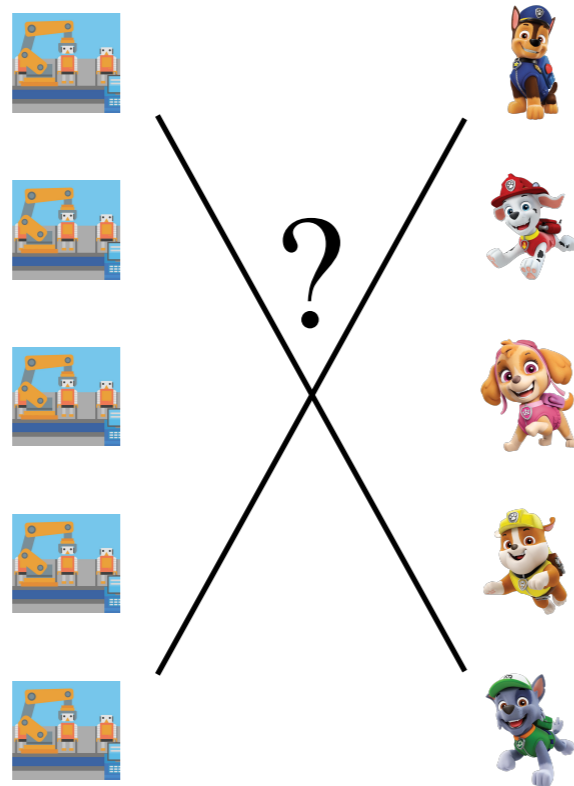
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A Toy Example: Add a few flexible edges (long-chain design)



# Flexibility Network Design Under Uncertainty

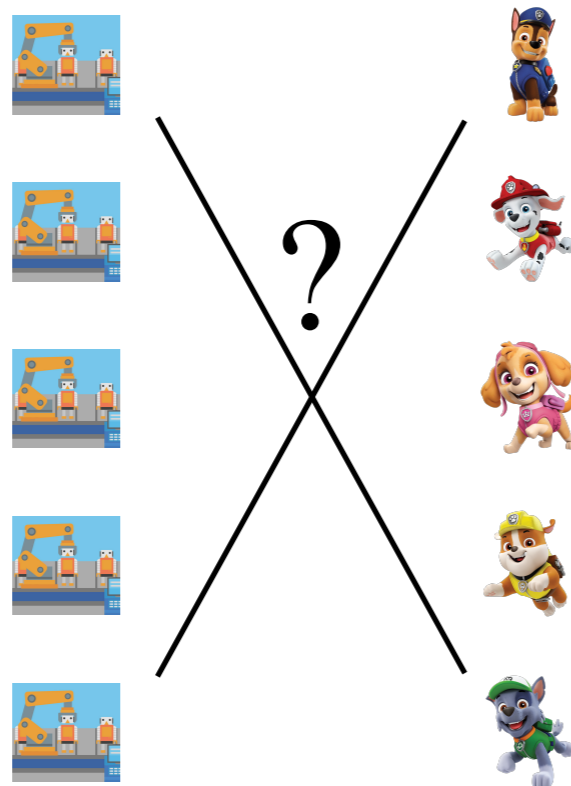
A Toy Example:



**Question:** How to design a sparse graph that achieves efficiency as close as the complete graph?

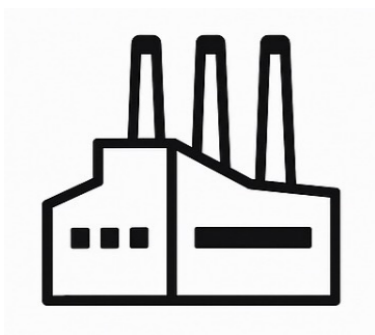
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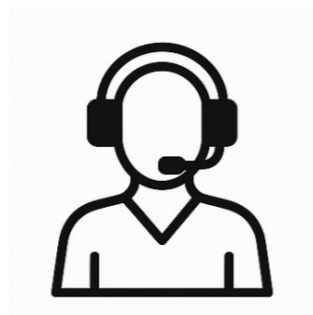


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Many real-world applications: match capacitated resources with uncertain demand



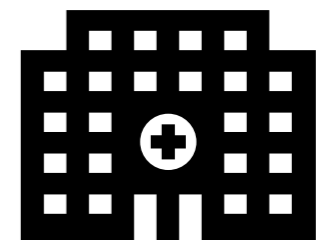
Manufacturing



Service operations



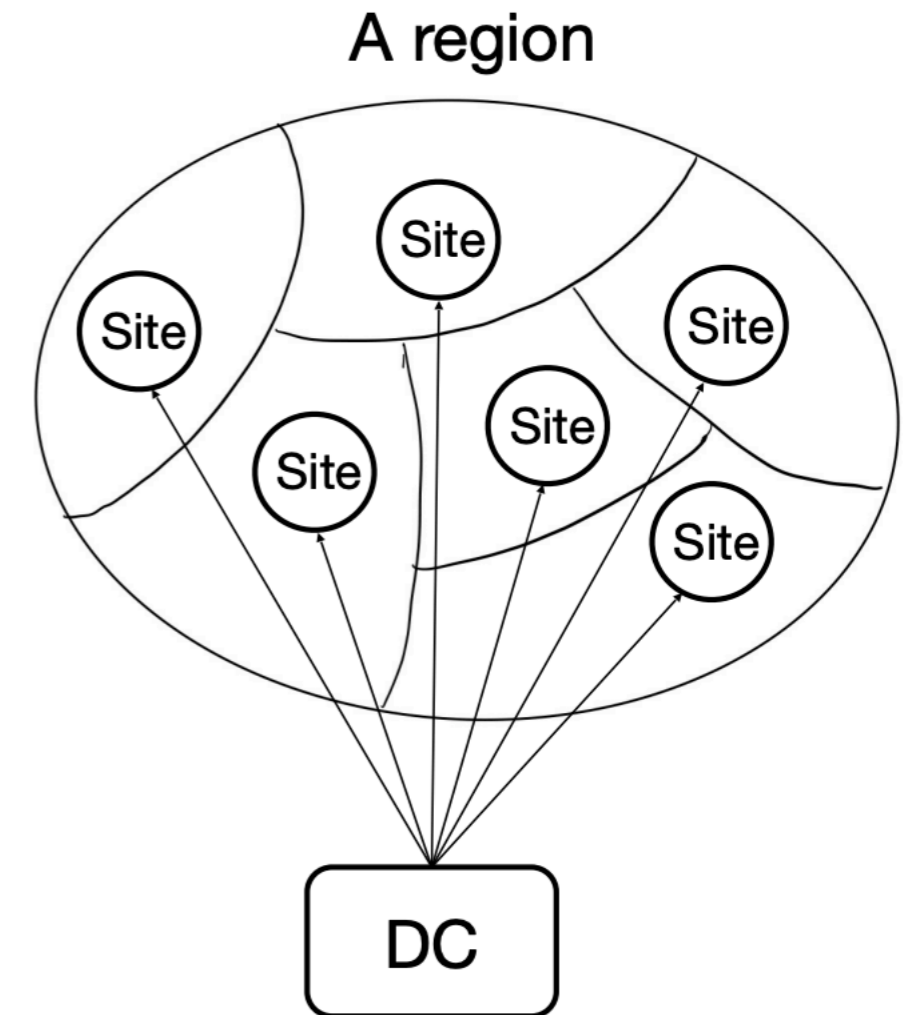
Transportation



Healthcare

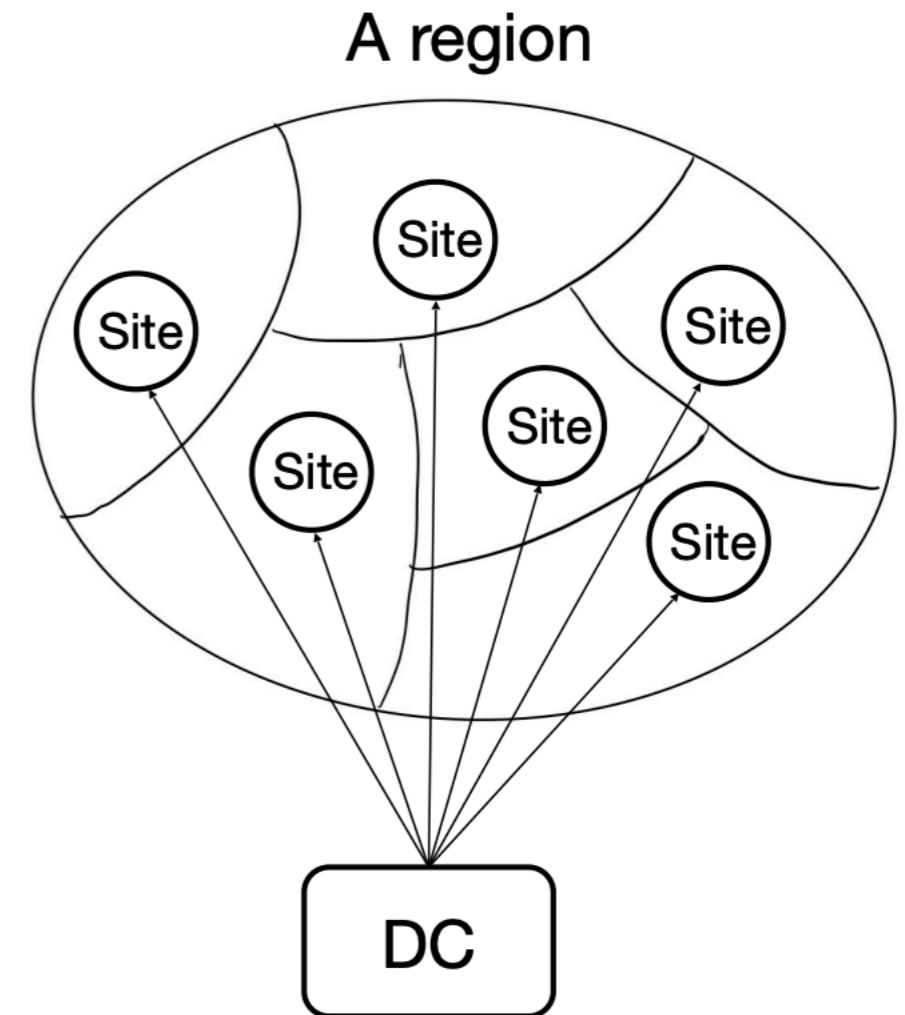
# Motivation: Transportation flexibility

- Proposed in [Feng-Caldentey-Xin-Zhong-Wang-Hu '24]
- Logistics networks are divided into regions
- With each region:
  - 1 distribution center (DC)
  - Multiple delivery stations (Sites)



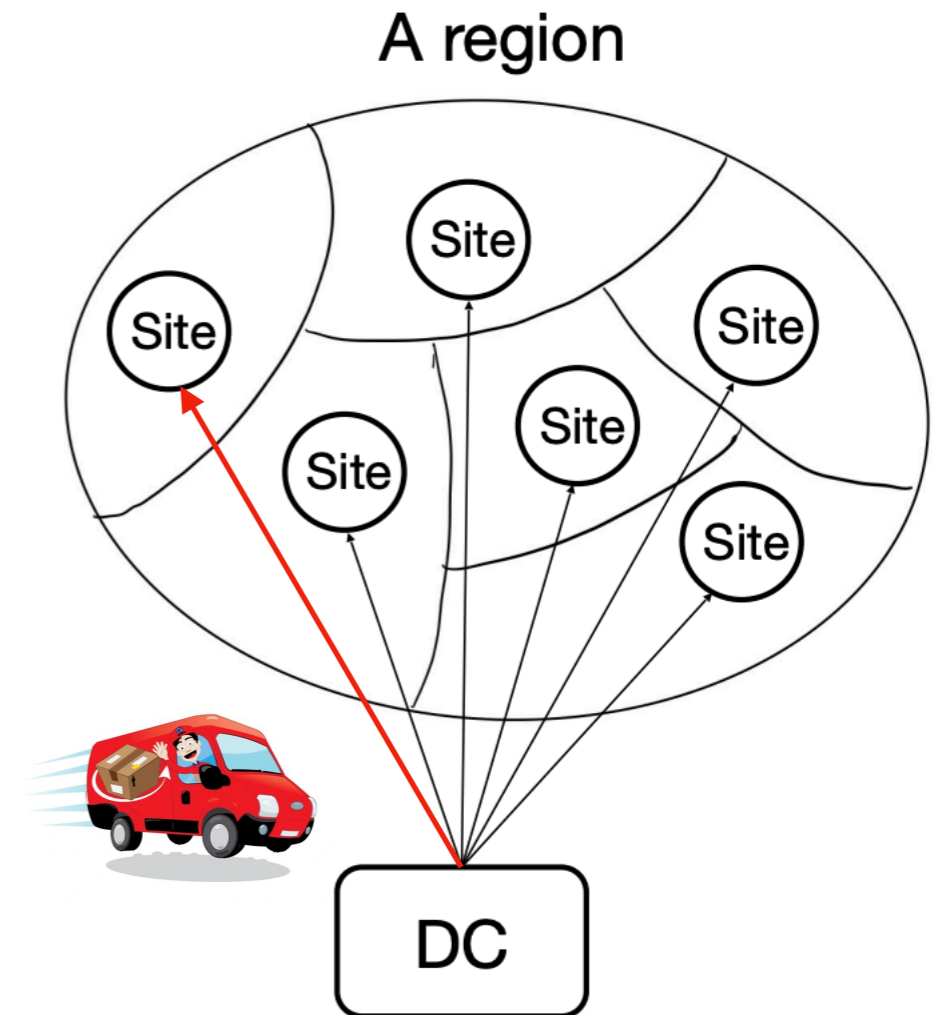
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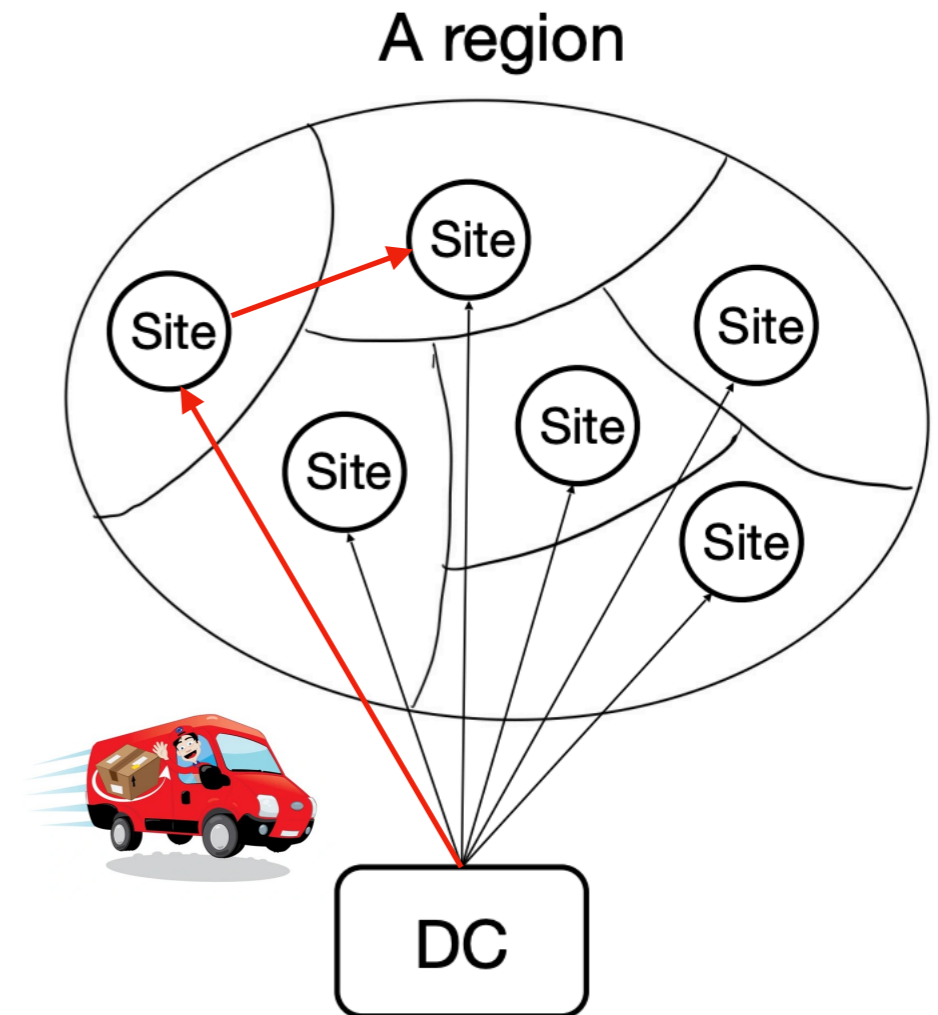
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  - **Direct shipping** (mostly): one truck one site



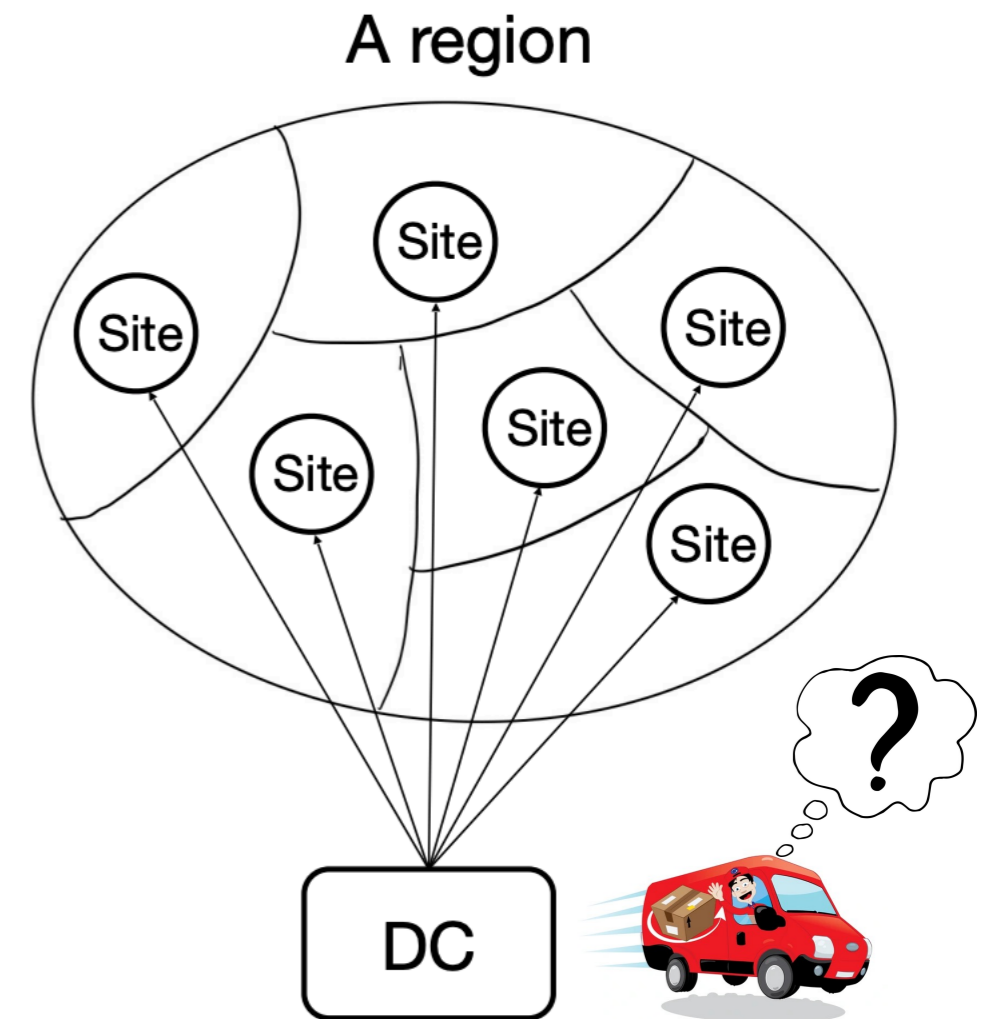
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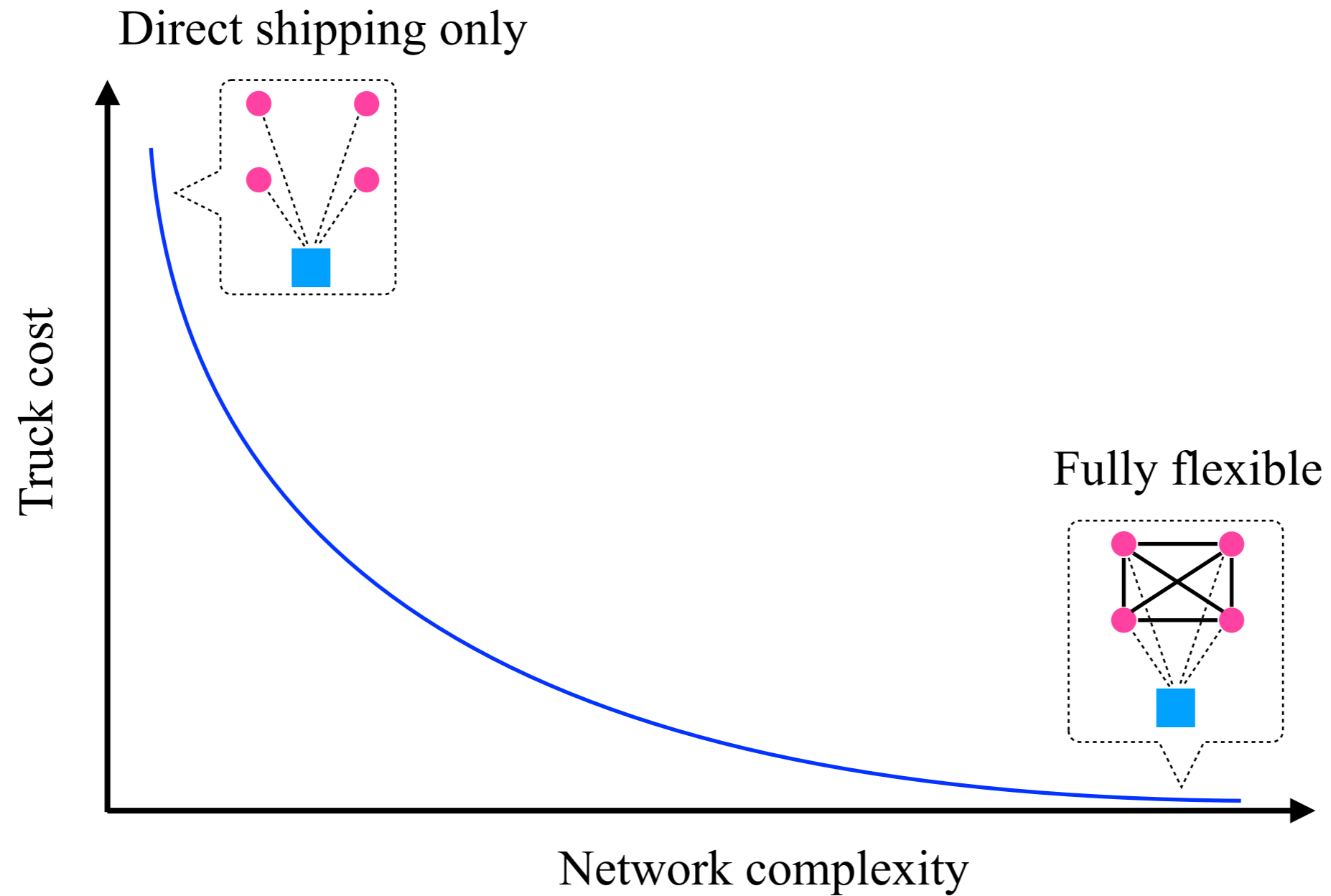


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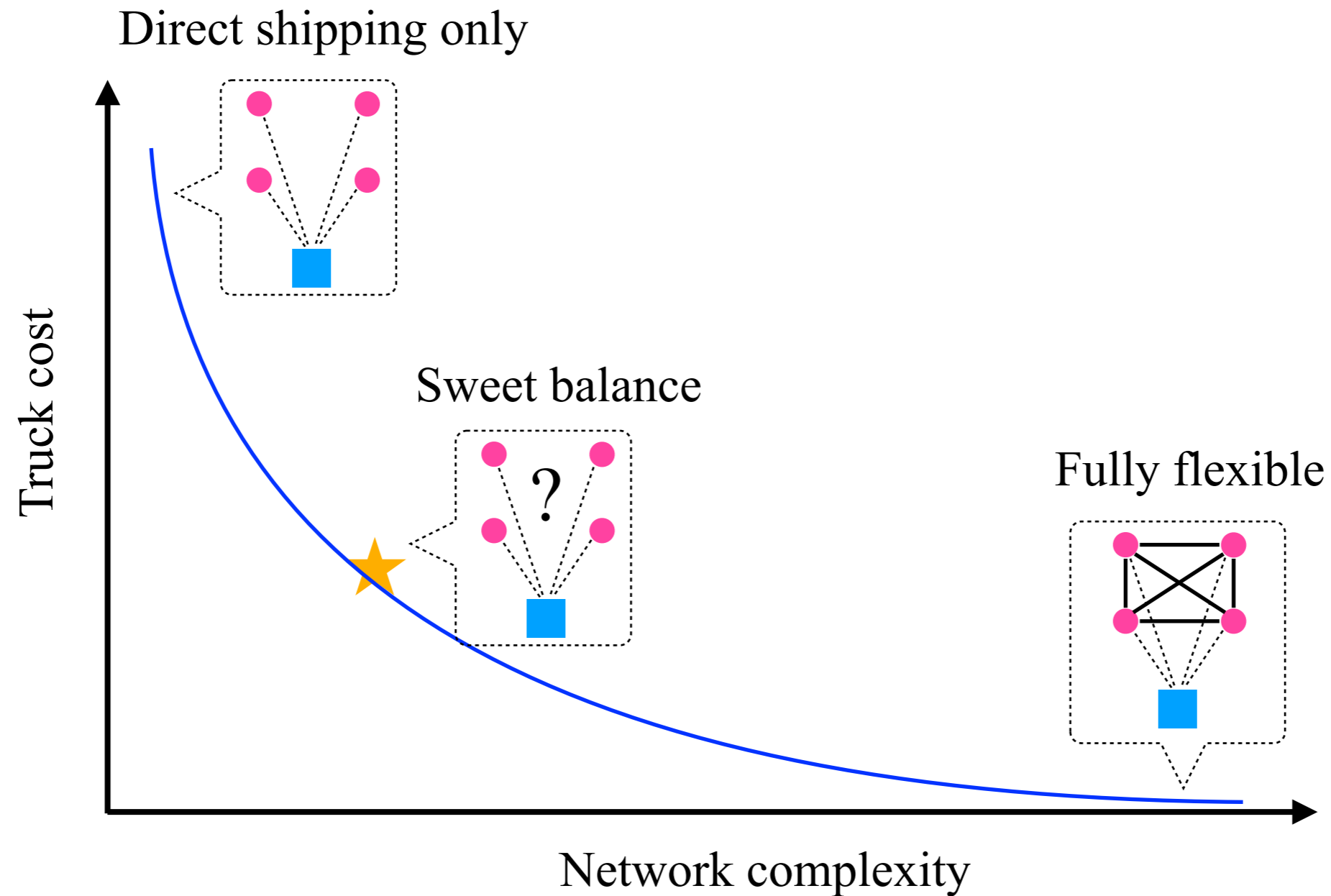
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- Question
  - How to design delivery routes for indirect shipping under uncertain demands?



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How to design a sparse network that achieves low truck cost?

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- Similar principle has been shown in many other related flexible systems: queueing systems [Tsitsiklis-Xu'17, Rutten-Mukherjee'23], dynamic resource allocation [Dong-Hu-Wang'24], online platforms [Freund-Martin-Zhao'24]

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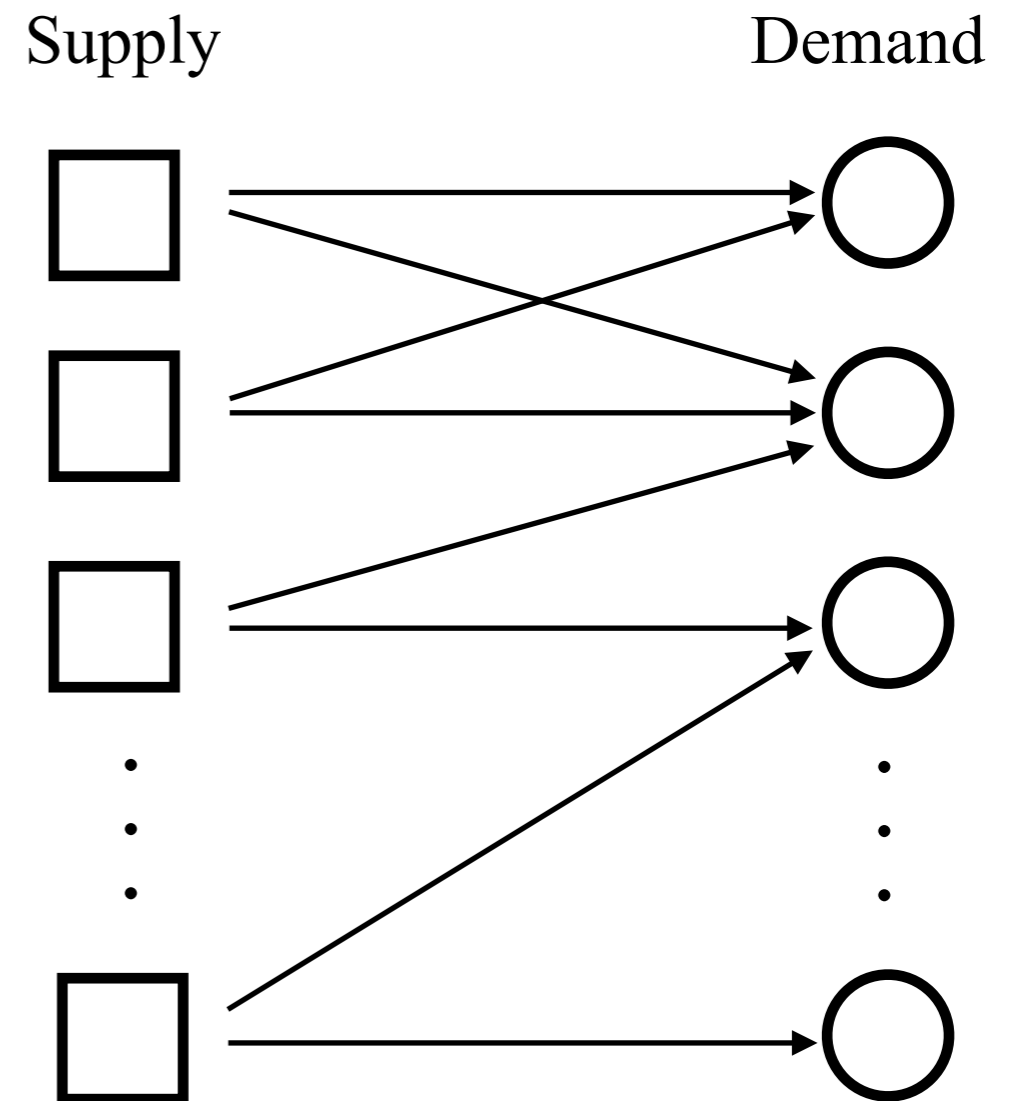
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**Open Question:** What is the precise limit of flexibility needed for achieving  $(1 - \epsilon)$  performance ratio?

Model

# Process Flexibility Model

- Bipartite graph  $G = ([n], [n], E)$



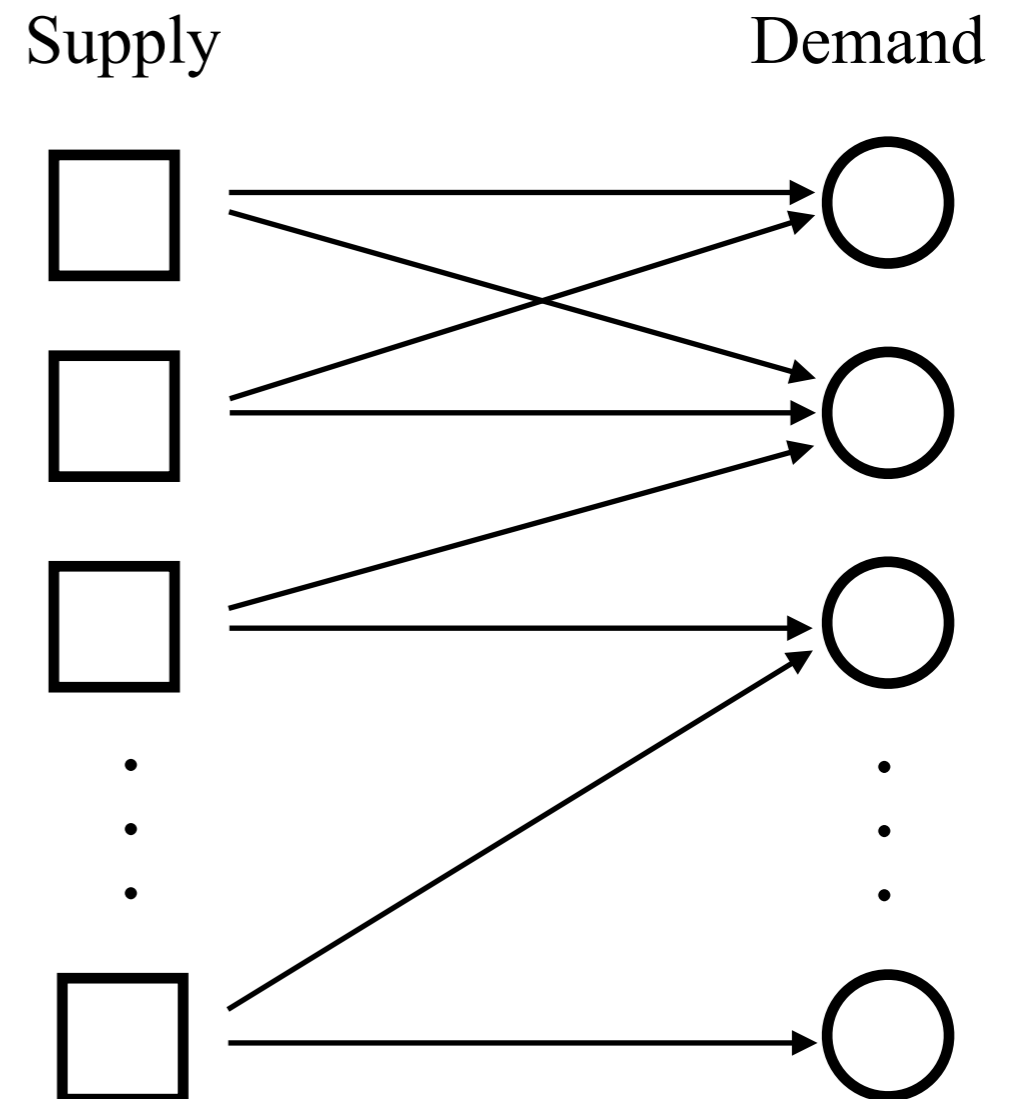
# Process Flexibility Model

- Bipartite graph  $G = ([n], [n], E)$
- The total fulfilled demand

$$z(G, D) = \max_{x_{ij} \geq 0} \sum_{(i,j) \in E} x_{ij}$$

s.t.  $\sum_{j: (i,j) \in E} x_{ij} \leq 1 \quad \forall i$

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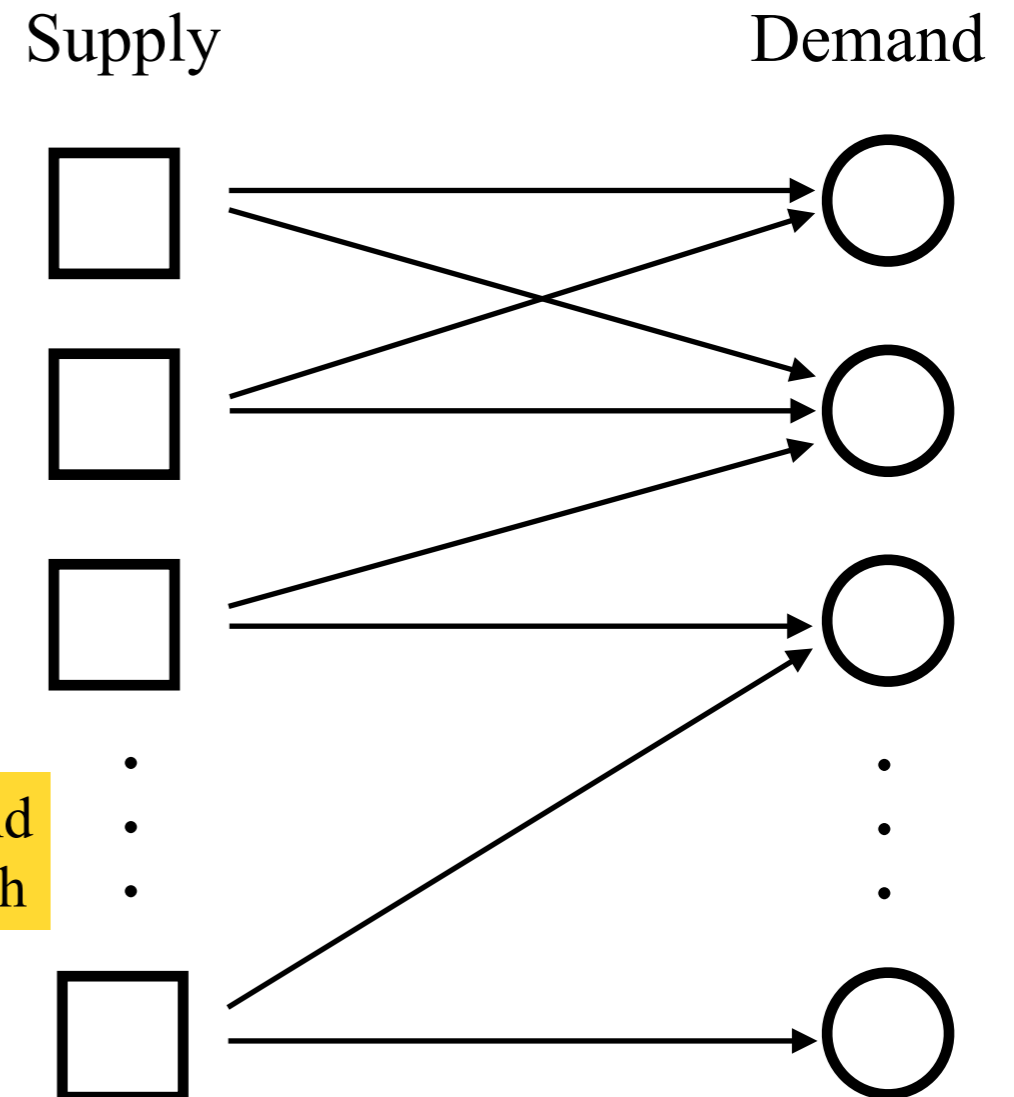
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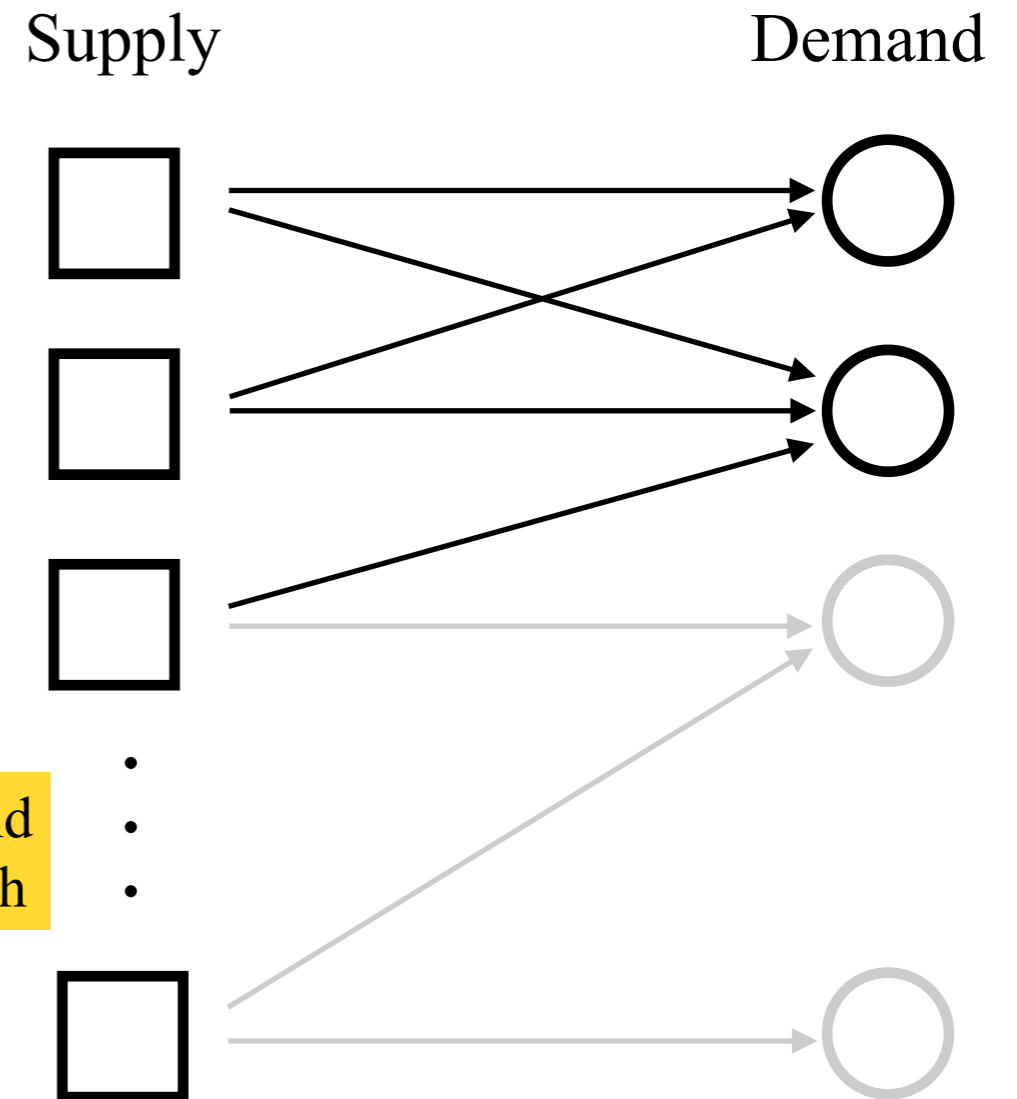
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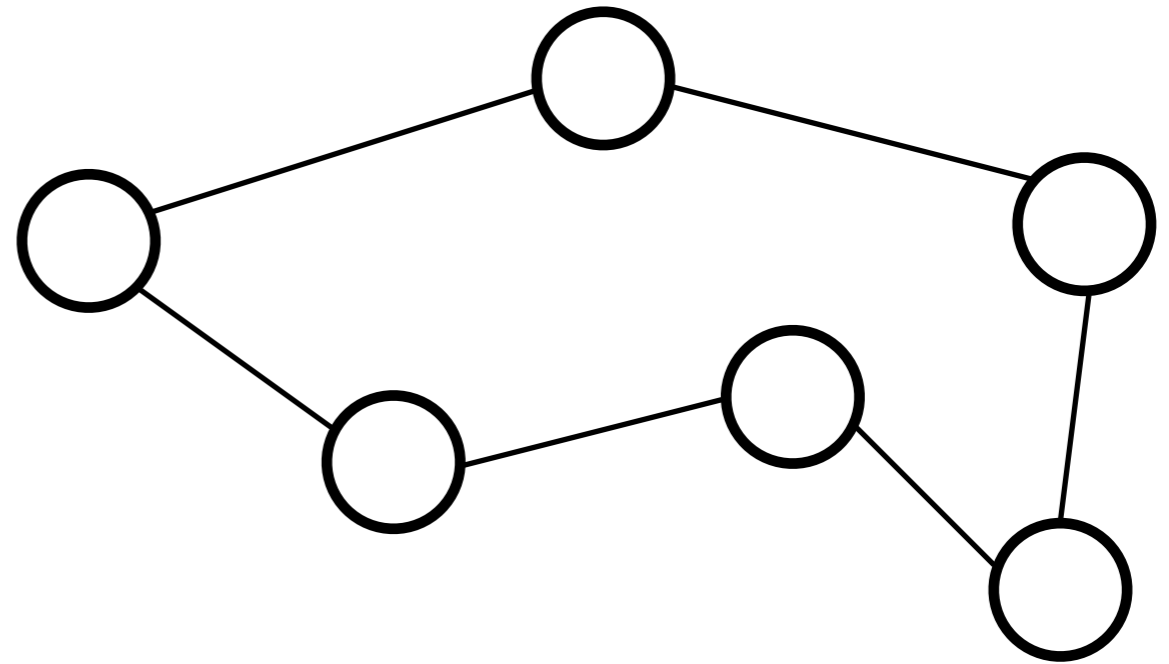


Total fulfilled demand under complete graph

Random demand node deletion with probability  $q$

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  - Vertices = sites
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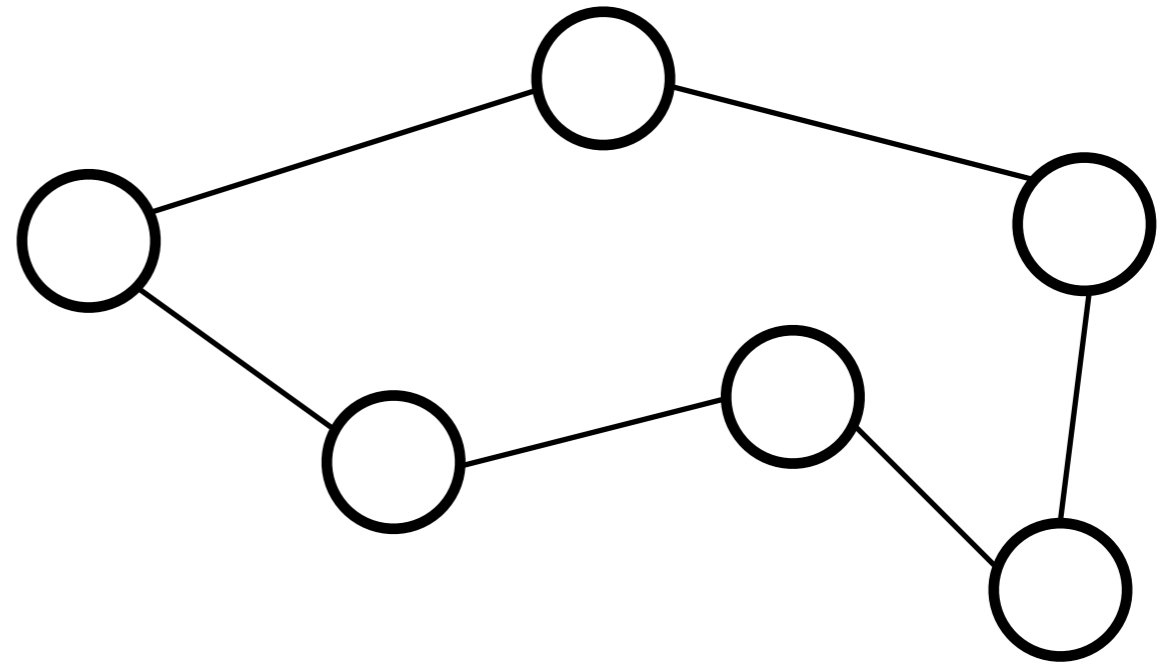
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Two connected sites can be served by a single truck if their total demand does not exceed the truck capacity

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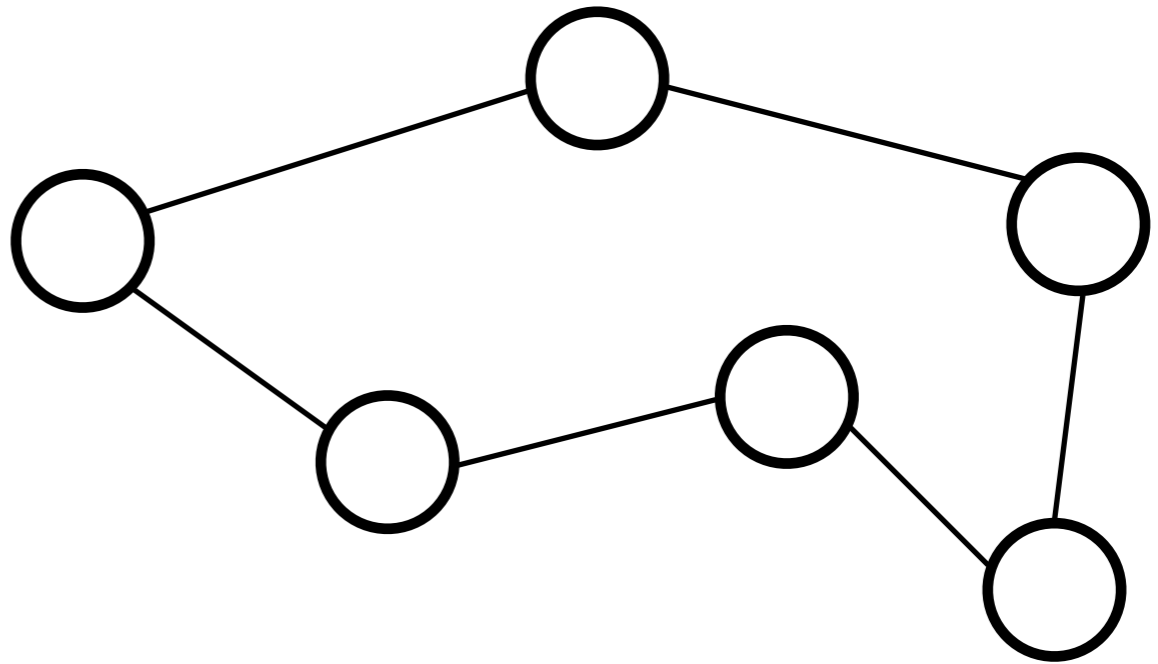
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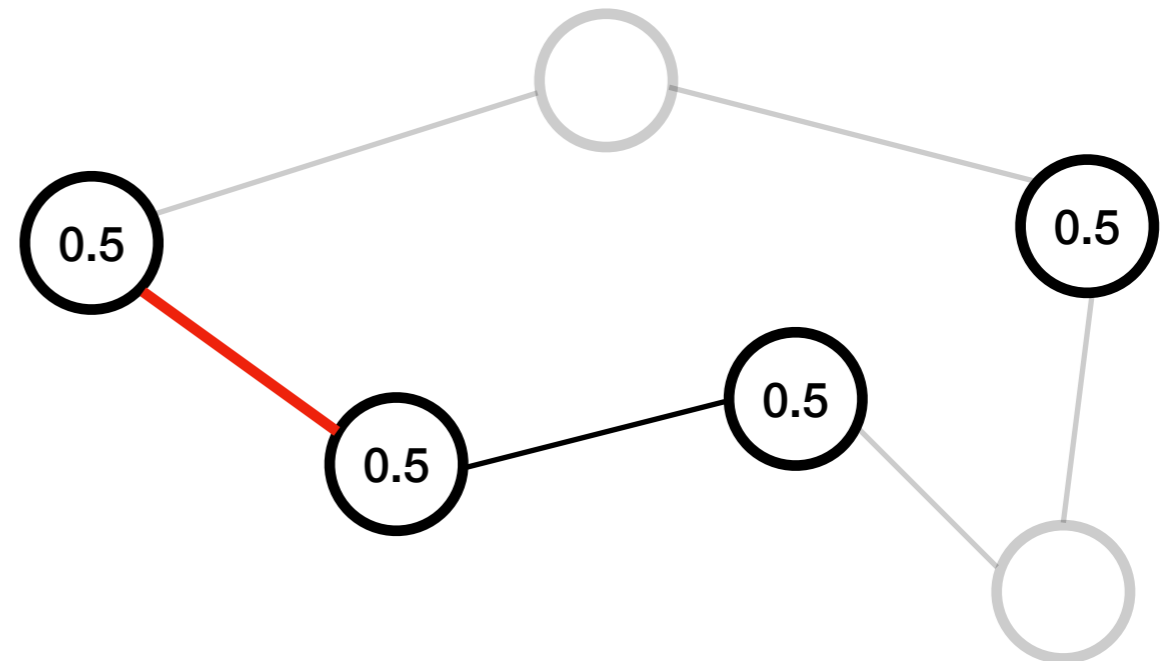
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Expected number of unmatched sites

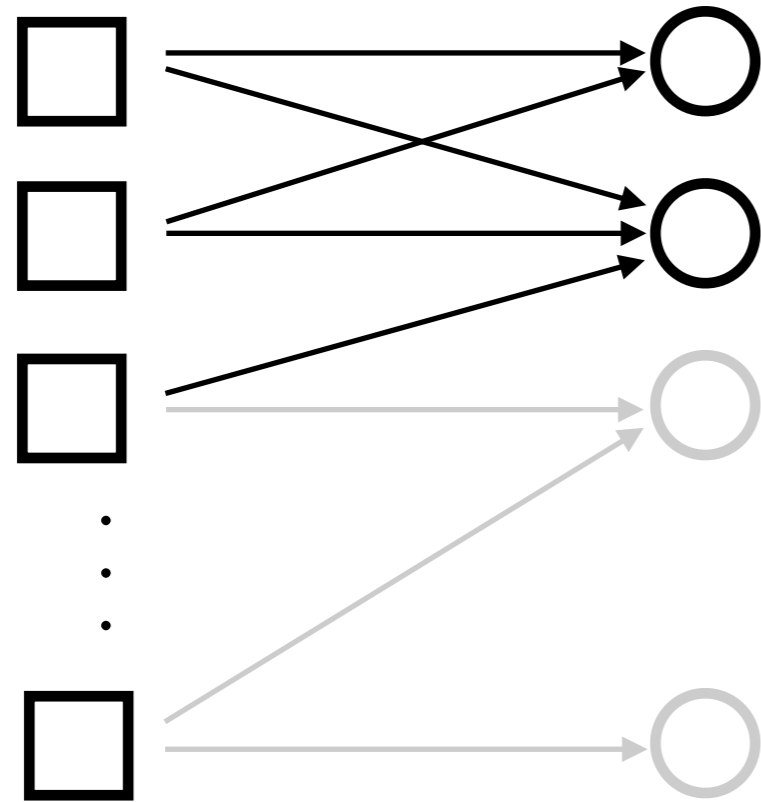
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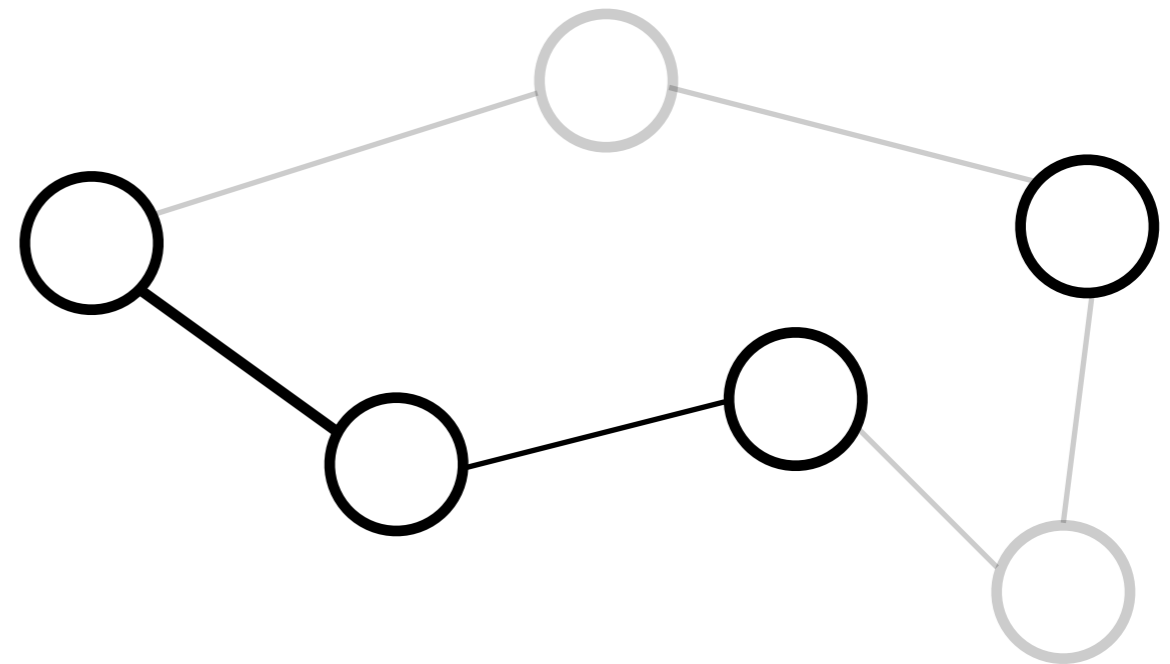
Random node deletion with probability  $q$



# Stochastic matching with random node deletion



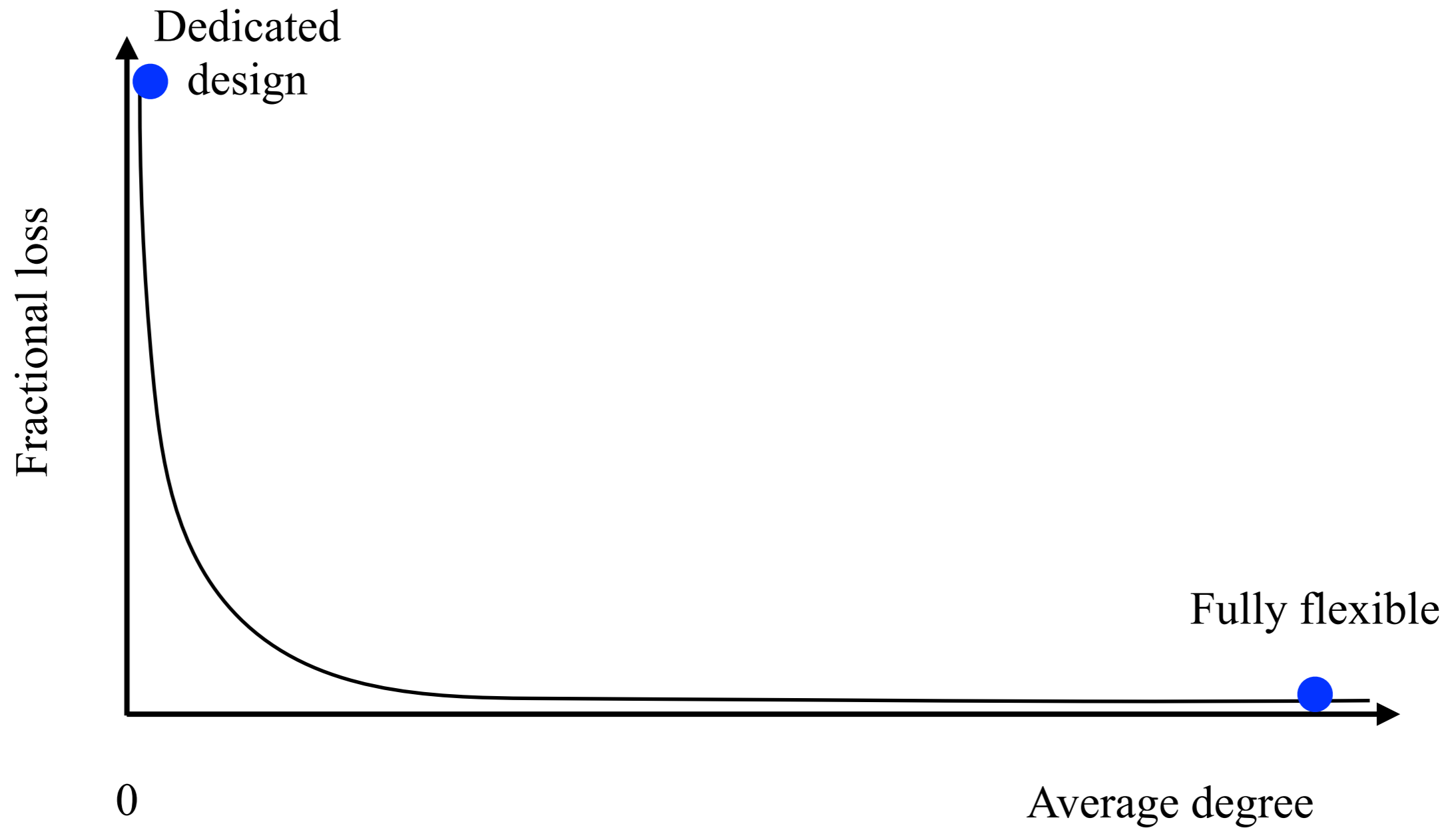
Process flexibility



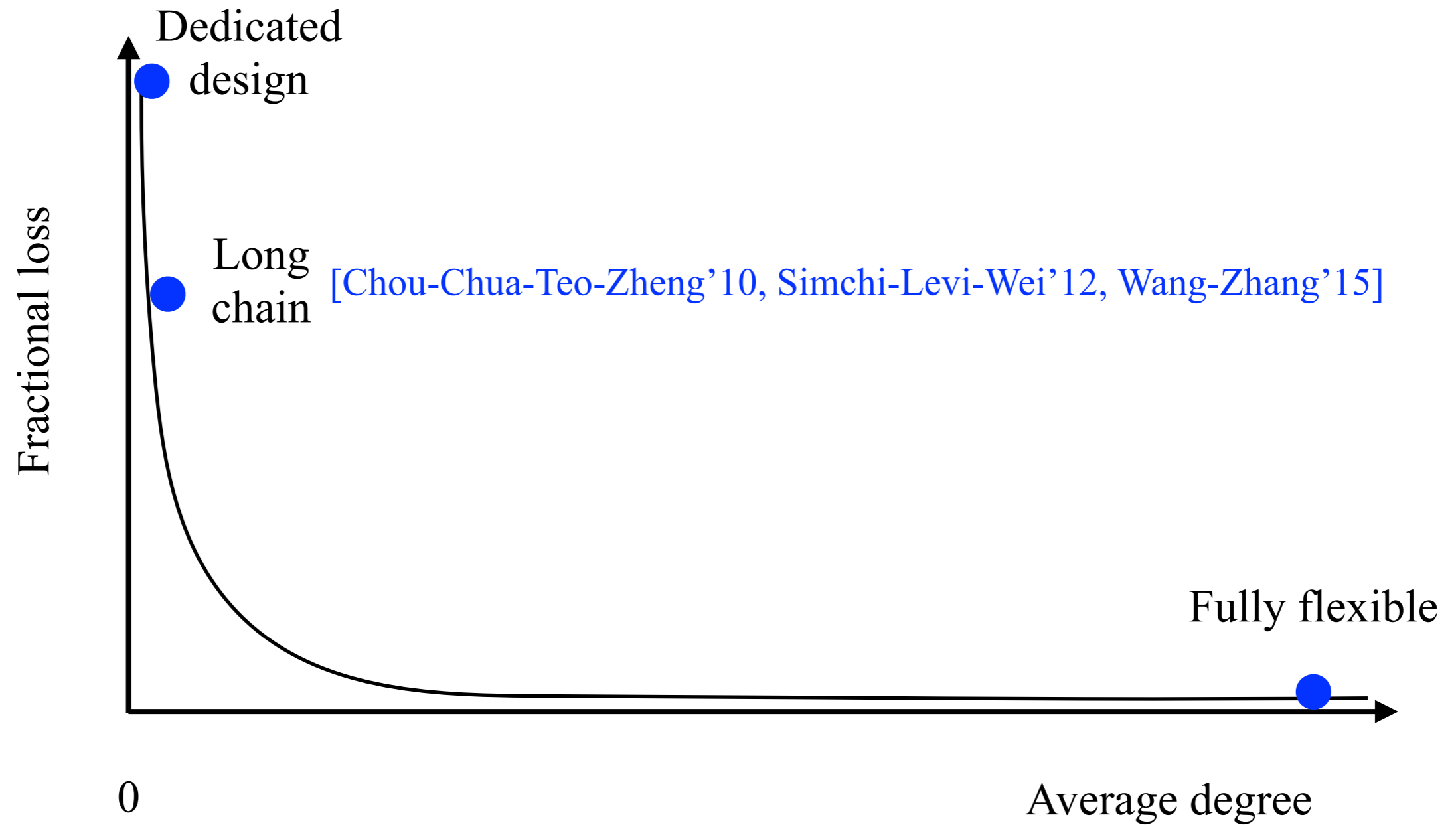
Transportation flexibility

- Both problems reduce to a “matching” problem in the residual graph  $G_{\text{res}}$  obtained after each demand node is independently deleted with probability  $q$
- **Goal:** Design a graph that sustains a large “matching” after random node deletions

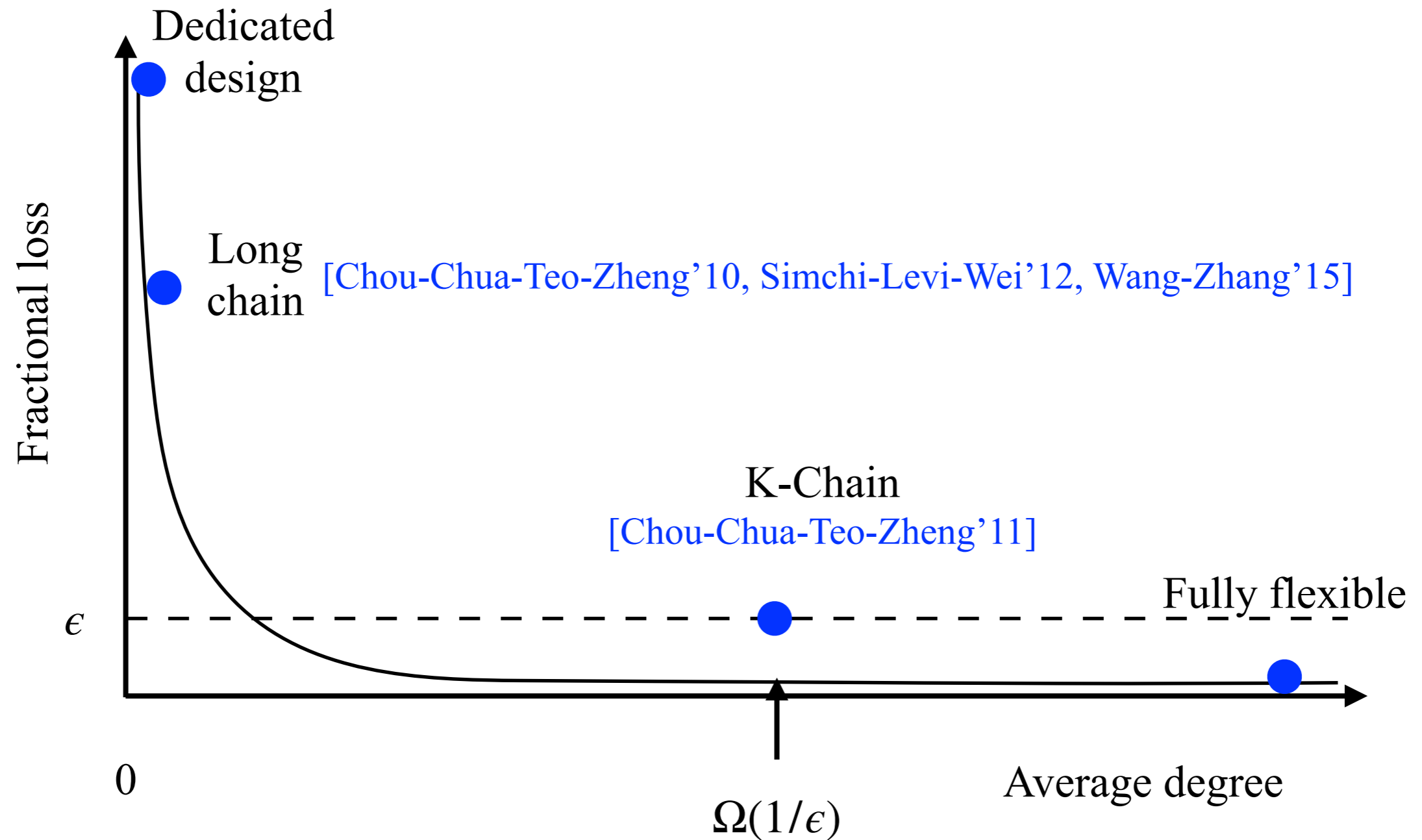
# Tradeoff: Demand Loss vs Network Complexity



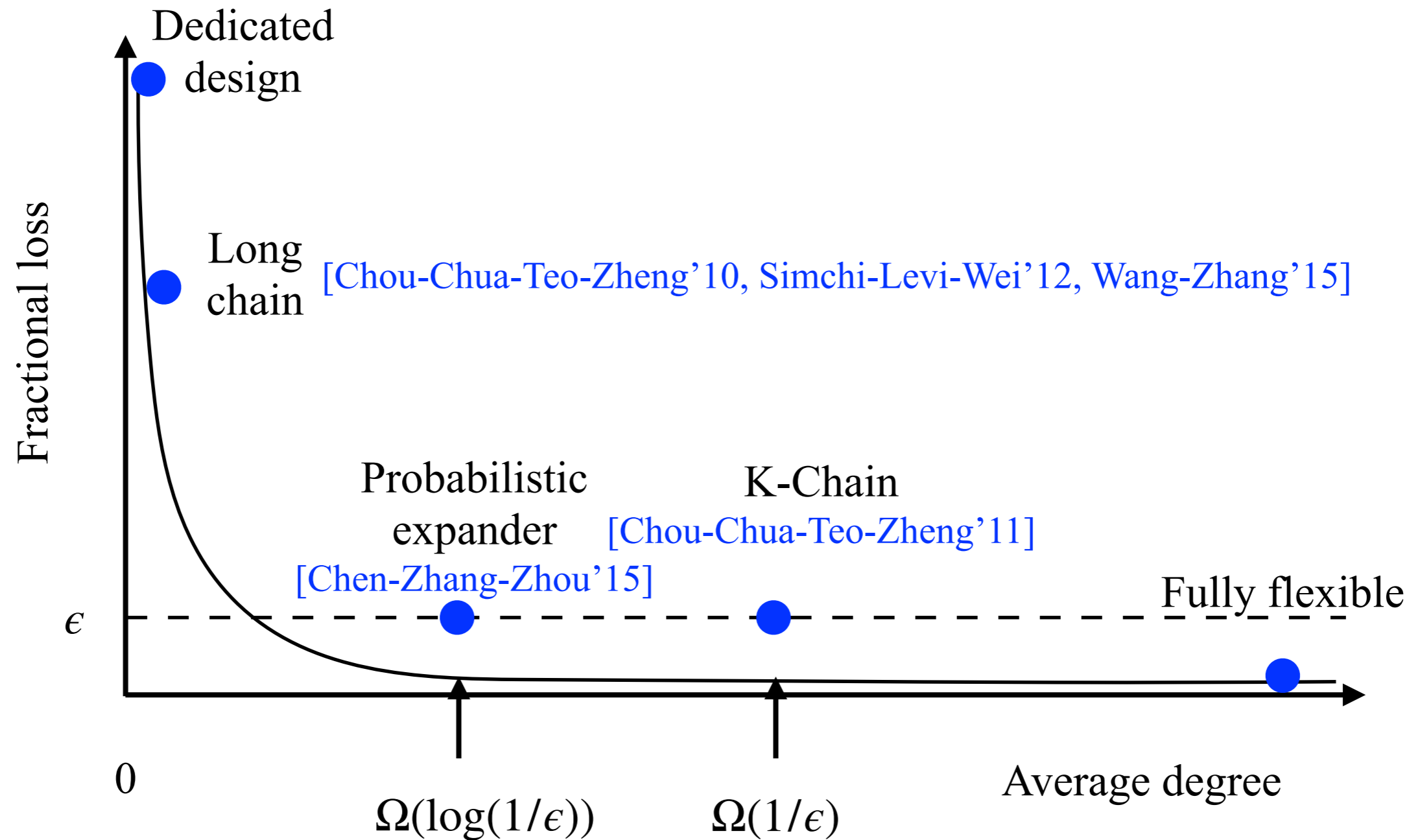
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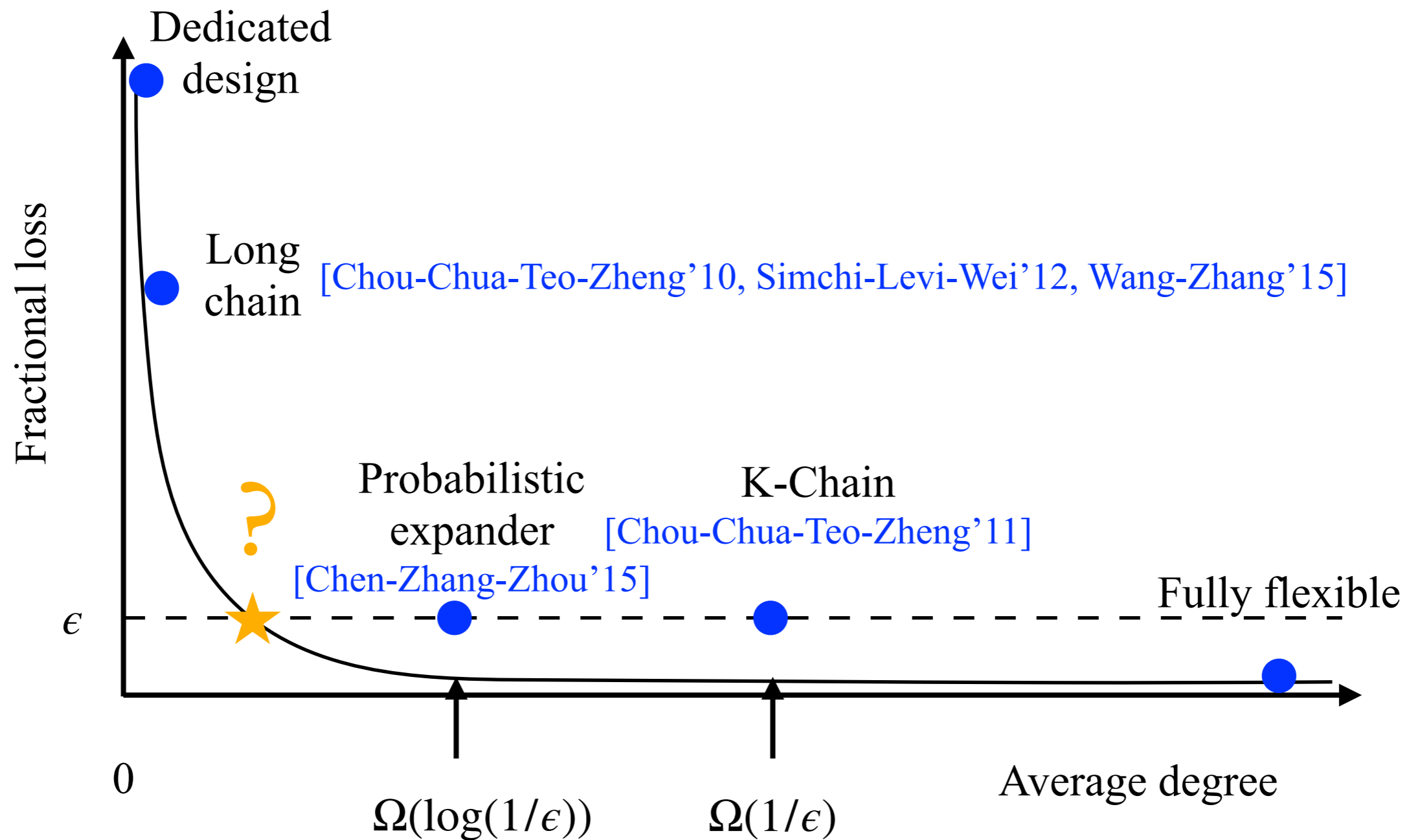
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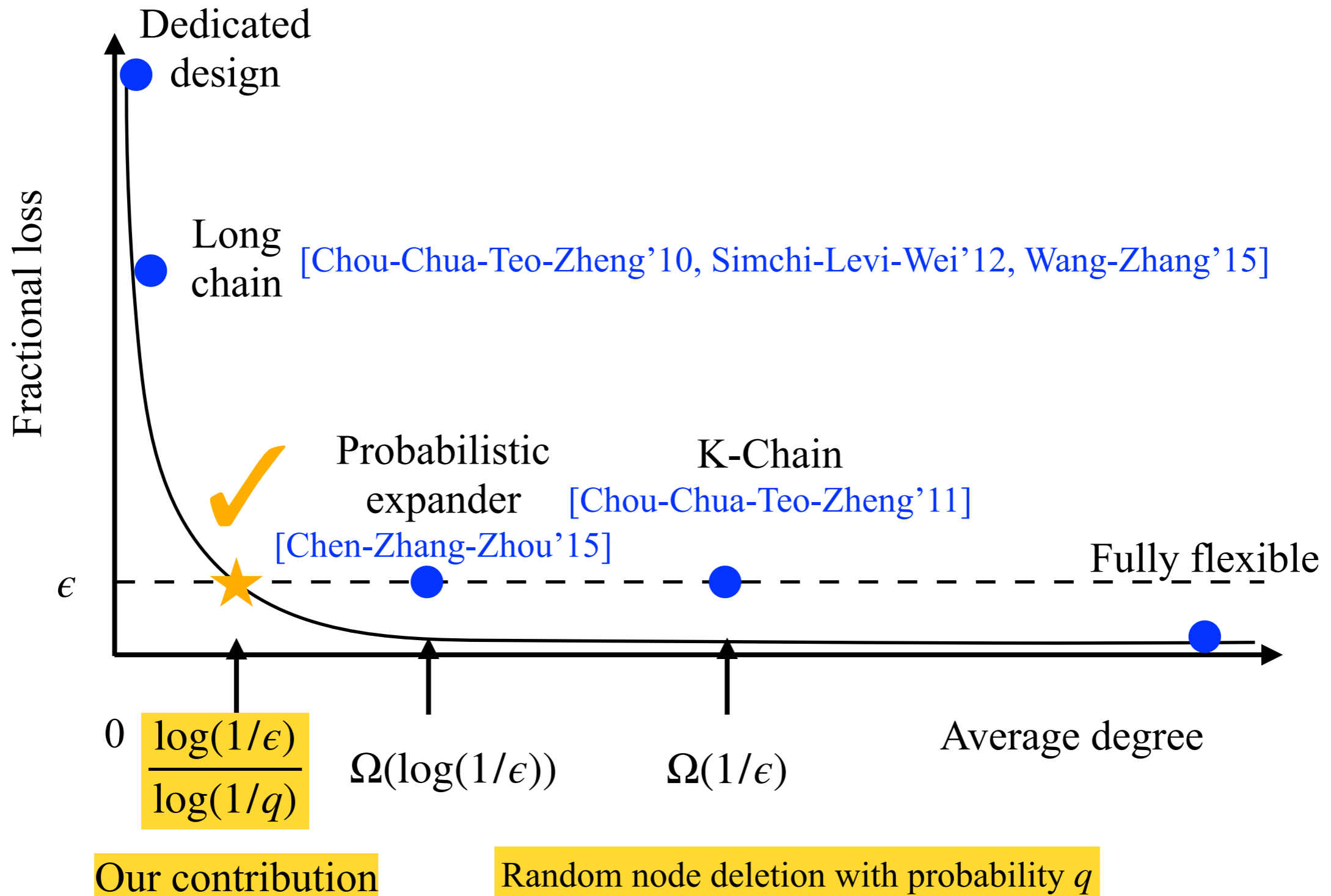
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Lower Bound

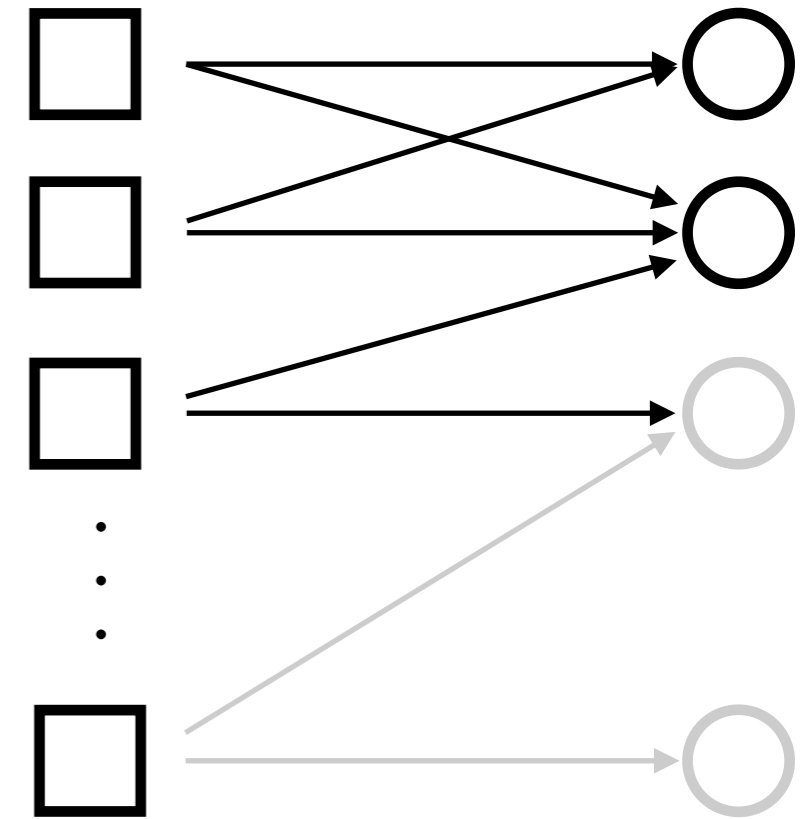
# Process Flexibility: A simple lower bound

## Theorem

For any bipartite graph  $G$  with an average degree  $d$ ,

$$\mathbb{E}_D[L(G, D)] \gtrsim nq^d.$$

Expected demand loss



Demand node deletion w.p.  $q$

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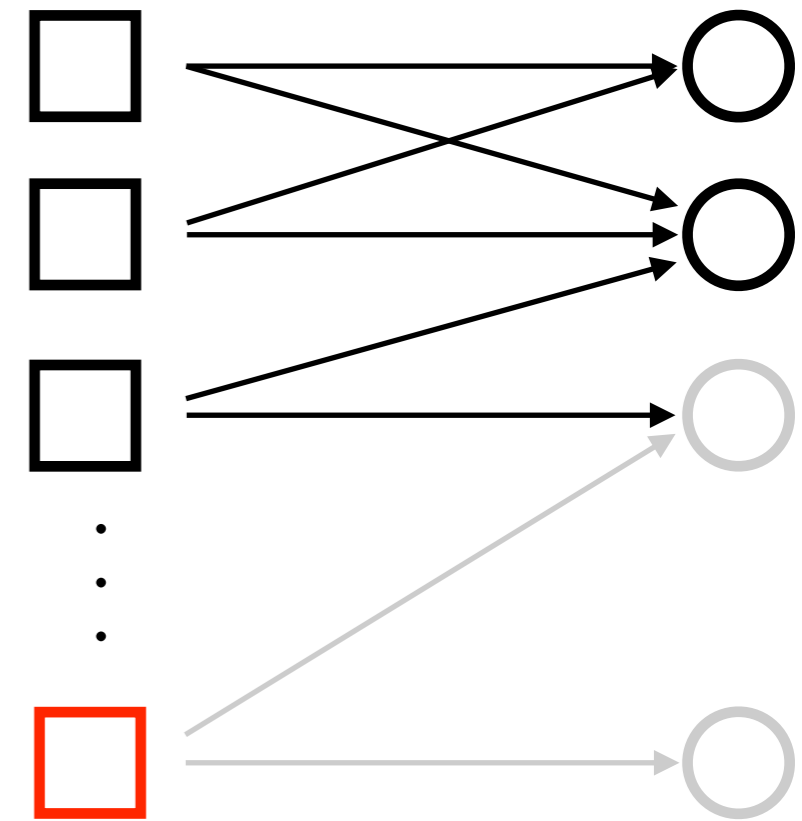
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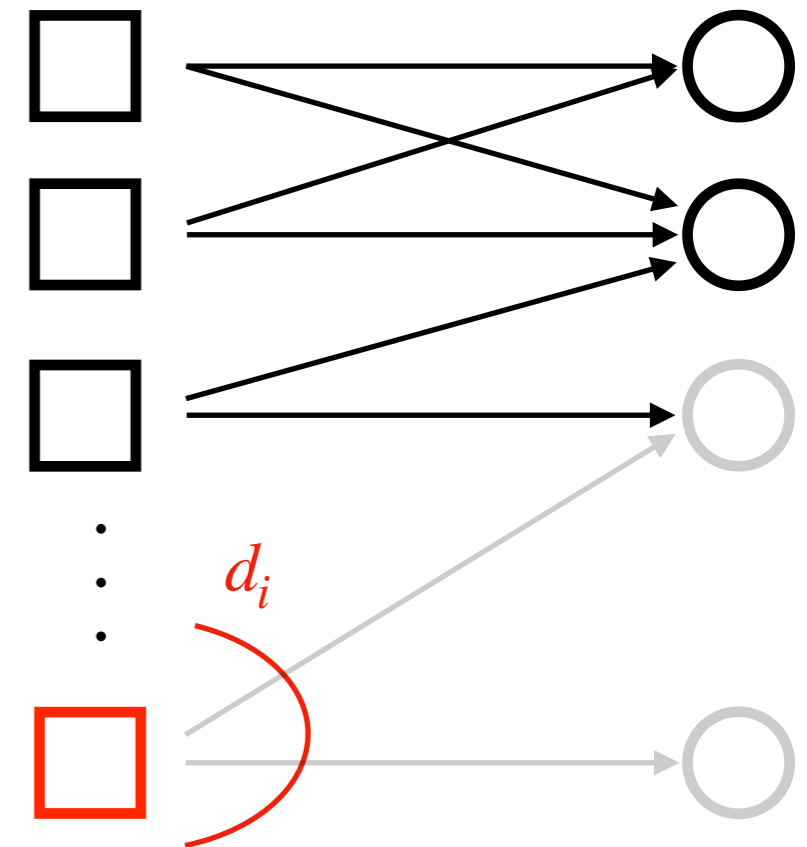
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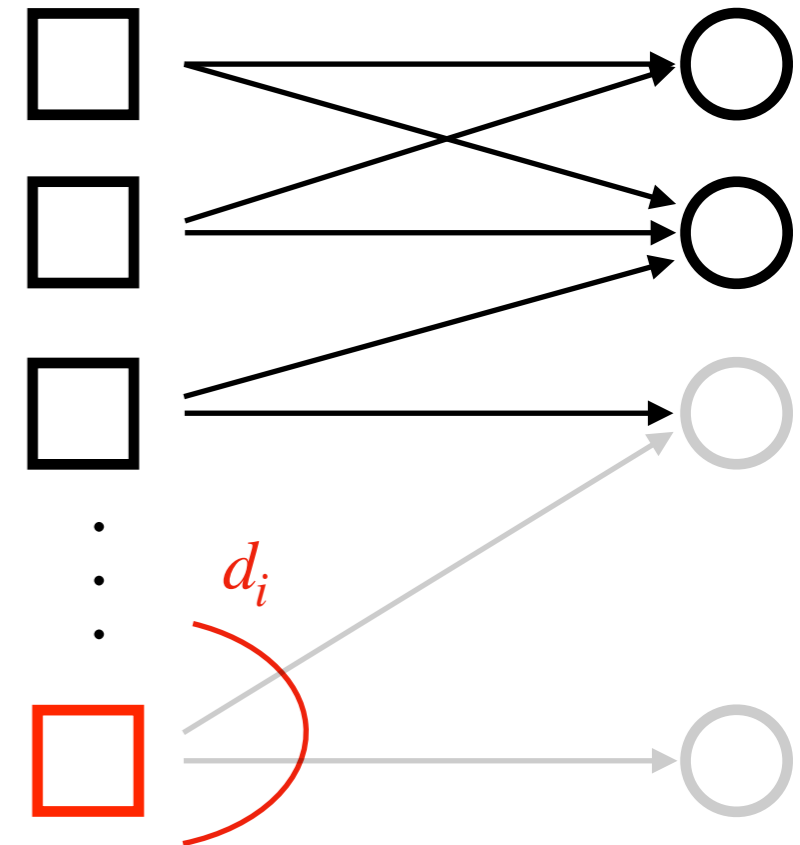
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Jensen's; Equality holds for regular graphs

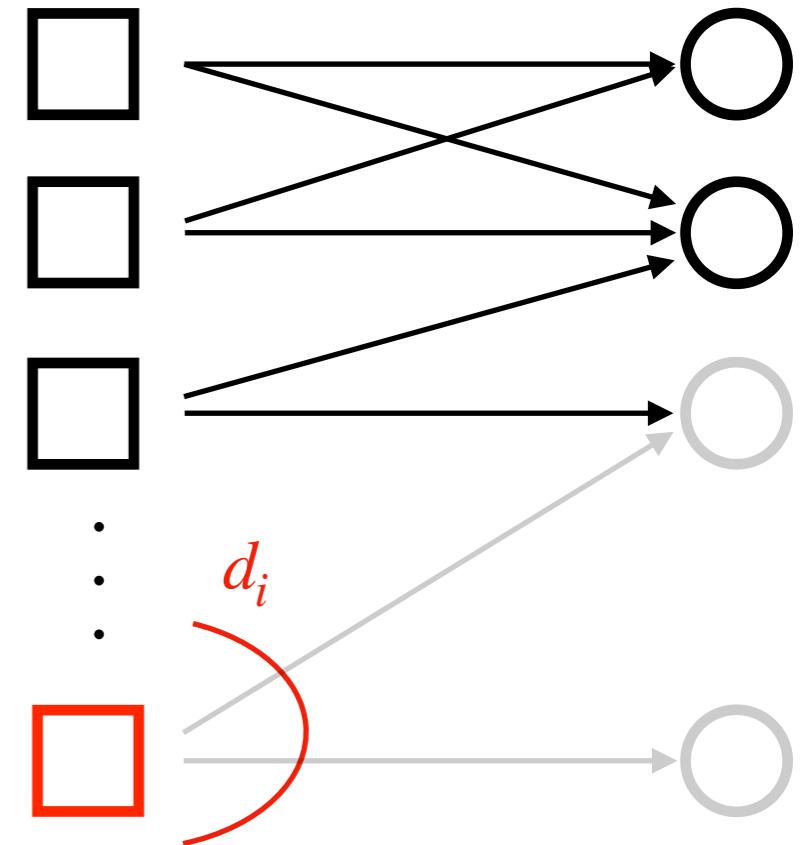


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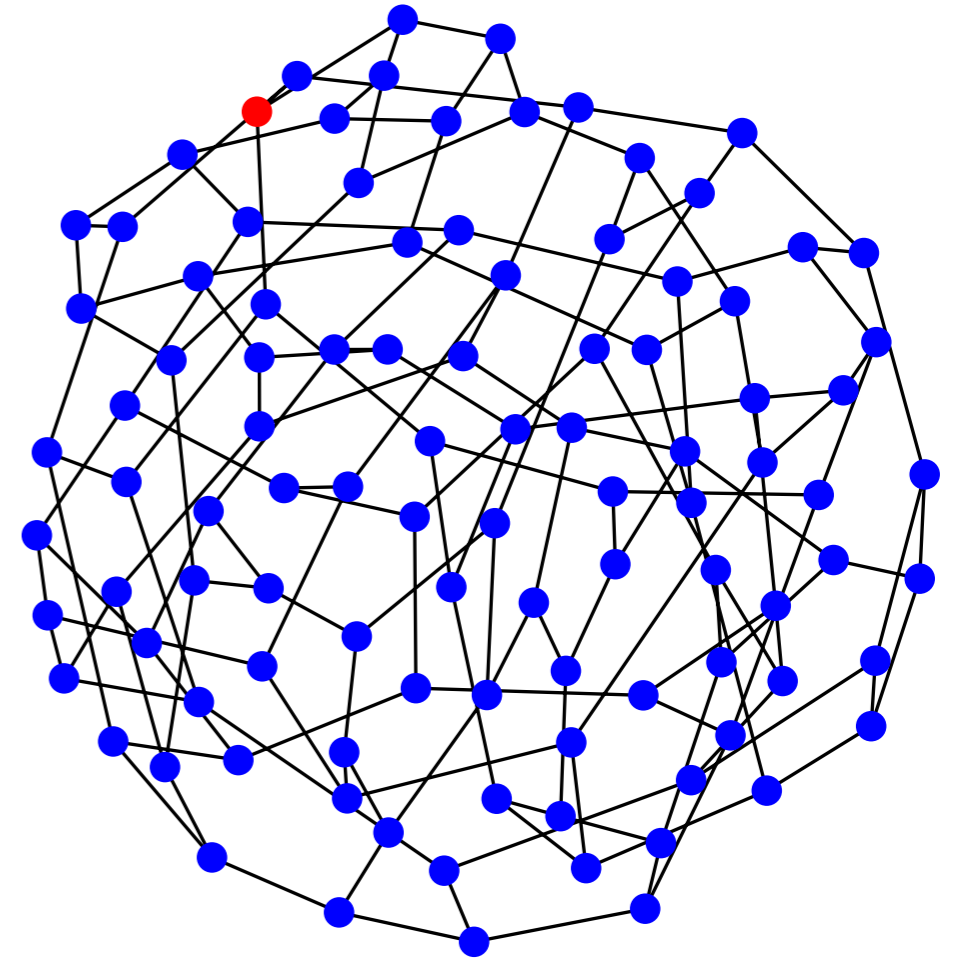
## • Implications:

- $\epsilon n$ -loss requires  $d \geq \log(1/\epsilon)/\log(1/q)$  for any graph;
- An optimal graph design needs to be **regular**
- K-Chain is also regular, but it still requires  $d \geq \Omega(1/\epsilon)$  [Chou-Chua-Teo-Zheng'11]

Our solution: Random regular graphs

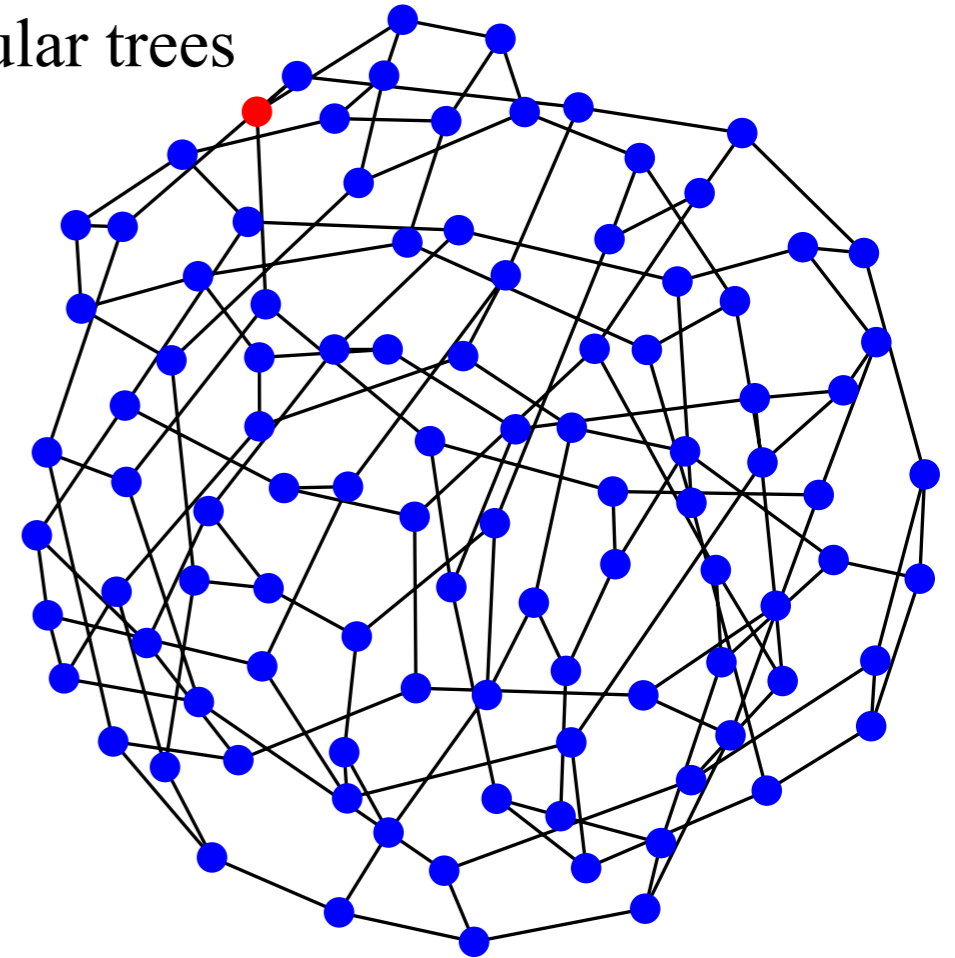
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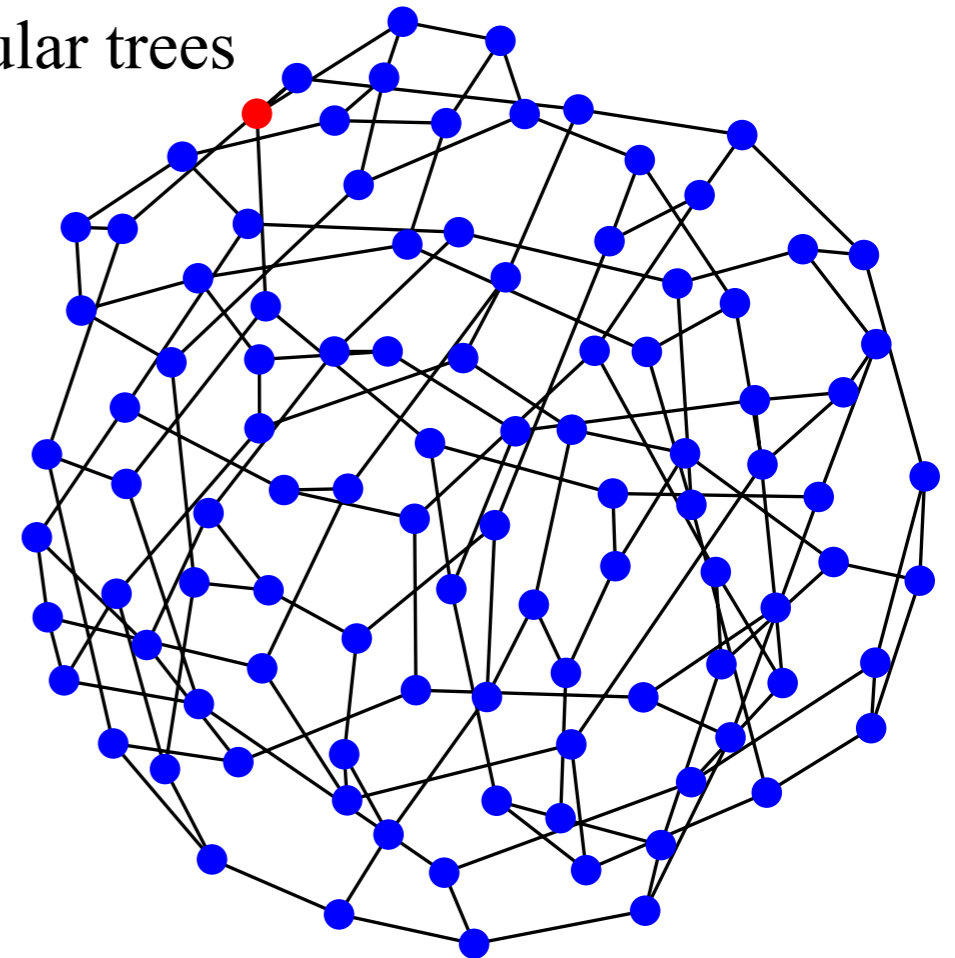
## Freedman's Theorem (2003)

For random  $d$ -regular graph with eigenvalues

$$\lambda_n \leq \dots \leq \lambda_2 \leq \lambda_1 = d,$$

$$\max\{\lambda_2, |\lambda_n|\} \leq 2\sqrt{d-1} + o(1)$$

**Optimal among all  $d$ -regular graphs**



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- Locally tree-like: local neighborhoods look like regular trees
- Spectral expansion: Almost **Ramanujan graphs**

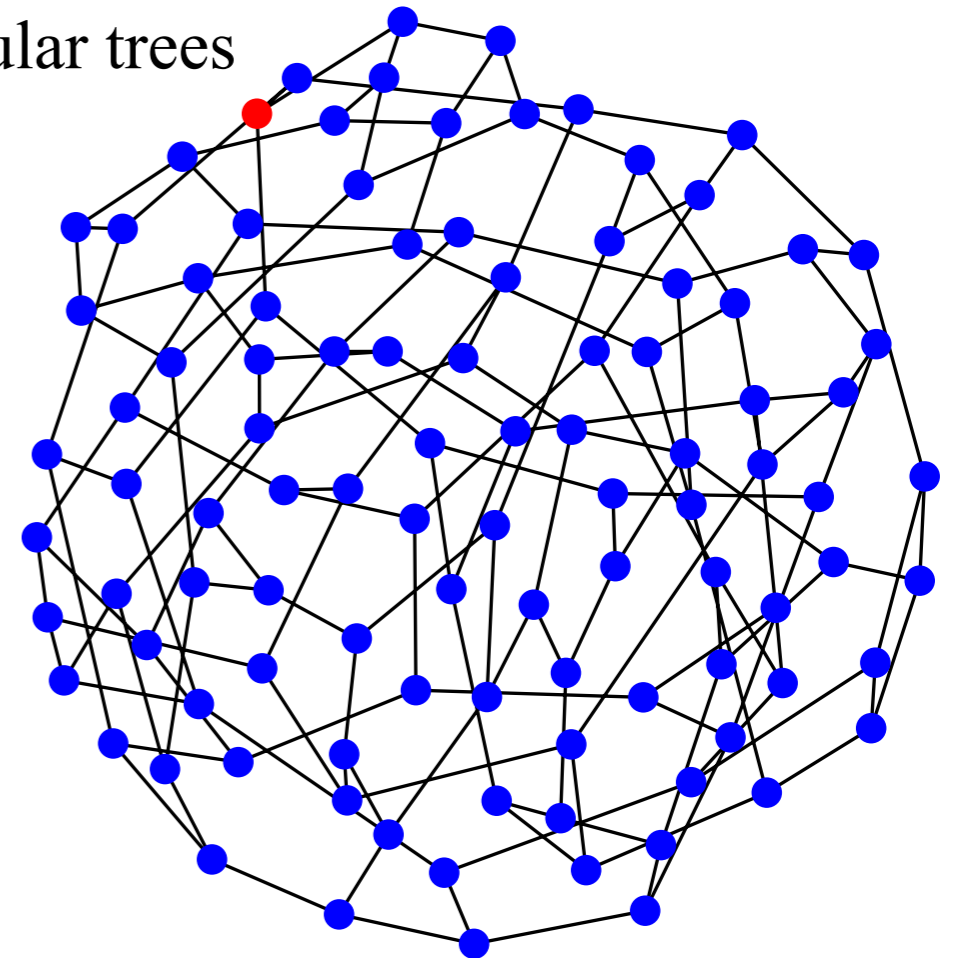
## Freedman's Theorem (2003)

For random  $d$ -regular graph with eigenvalues

$$\lambda_n \leq \dots \leq \lambda_2 \leq \lambda_1 = d,$$

$$\max\{\lambda_2, |\lambda_n|\} \leq 2\sqrt{d-1} + o(1)$$

**Optimal among all  $d$ -regular graphs**



**Question:** Do random regular graphs enjoy optimality in flexibility design?

# Process Flexibility: Random Regular Graphs Are Optimal

## Theorem [Li-Niu-Wei-Xu '25]

For any constant  $\delta > 0$ , a random  $d$ -regular bipartite graph  $G$  achieves whp:

- $\epsilon$ -fractional loss ( $\mathbb{E}_D[L(G, D)] \leq \epsilon n$ ), if

$$d \geq \frac{(1 + \delta)\log(1/\epsilon)}{\log(1/q)}$$

- Constant loss ( $\mathbb{E}_D[L(G, D)] = O(1)$ ), if

$$d \geq \frac{(1 + \delta)\log n}{\log(1/q)}$$

## Remarks

- Match the lower bounds with the sharp constant;
- Previous best-known upper bound  $d \geq \Omega(\log(1/\epsilon))$  [Chen-Zhang-Zhou'15];
- $K$ -chain needs  $d \geq \Omega(1/\epsilon)$  [Chou-Chua-Teo-Zheng'11].

# Transportation Flexibility

## Theorem [Li-Niu-Wei-Xu '25]

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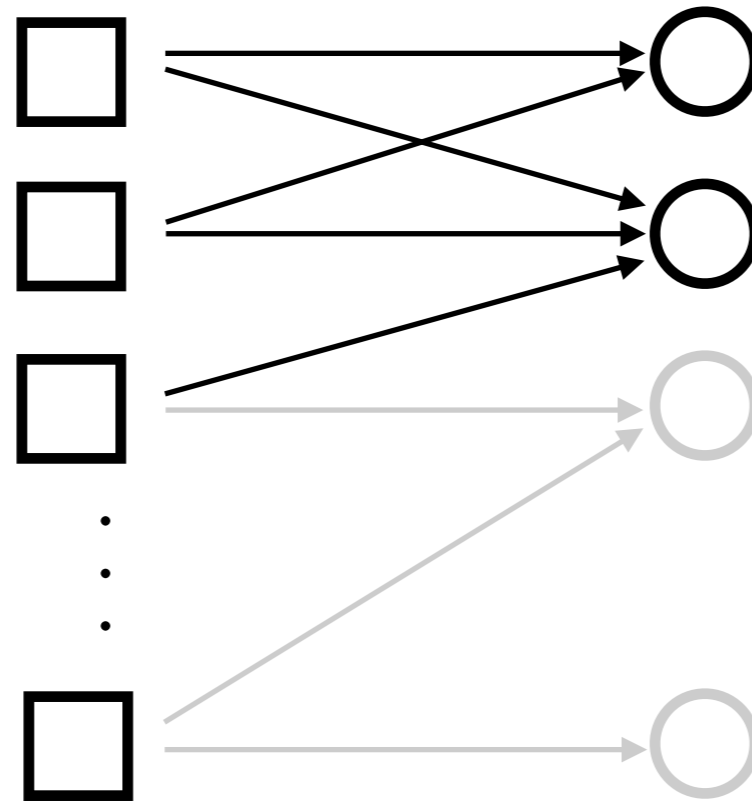
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## Remarks

- Match the lower bounds with the sharp constant;
- Erdős–Rényi random graph needs  $d > \log(1/\epsilon)/(1 - q)$  [Li-Niu-Wei-Xu'25];
- $K$ -chain needs  $d \geq 2 \log(1/\epsilon)/\log(1/q)$  [Li-Niu-Wei-Xu'25].

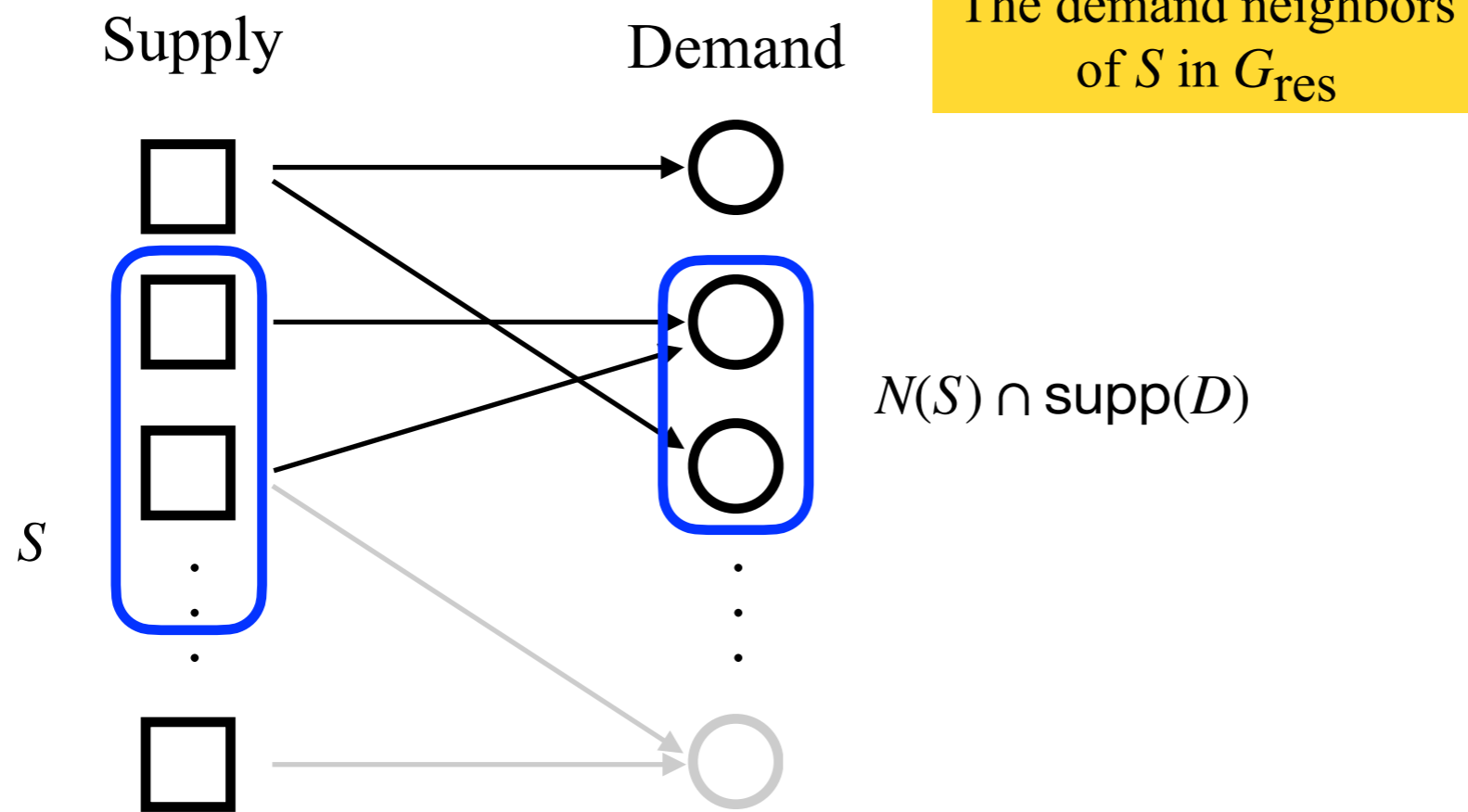
# Proof ideas for process flexibility



# Strong Connectivity Property

By max-flow min-cut theorem:

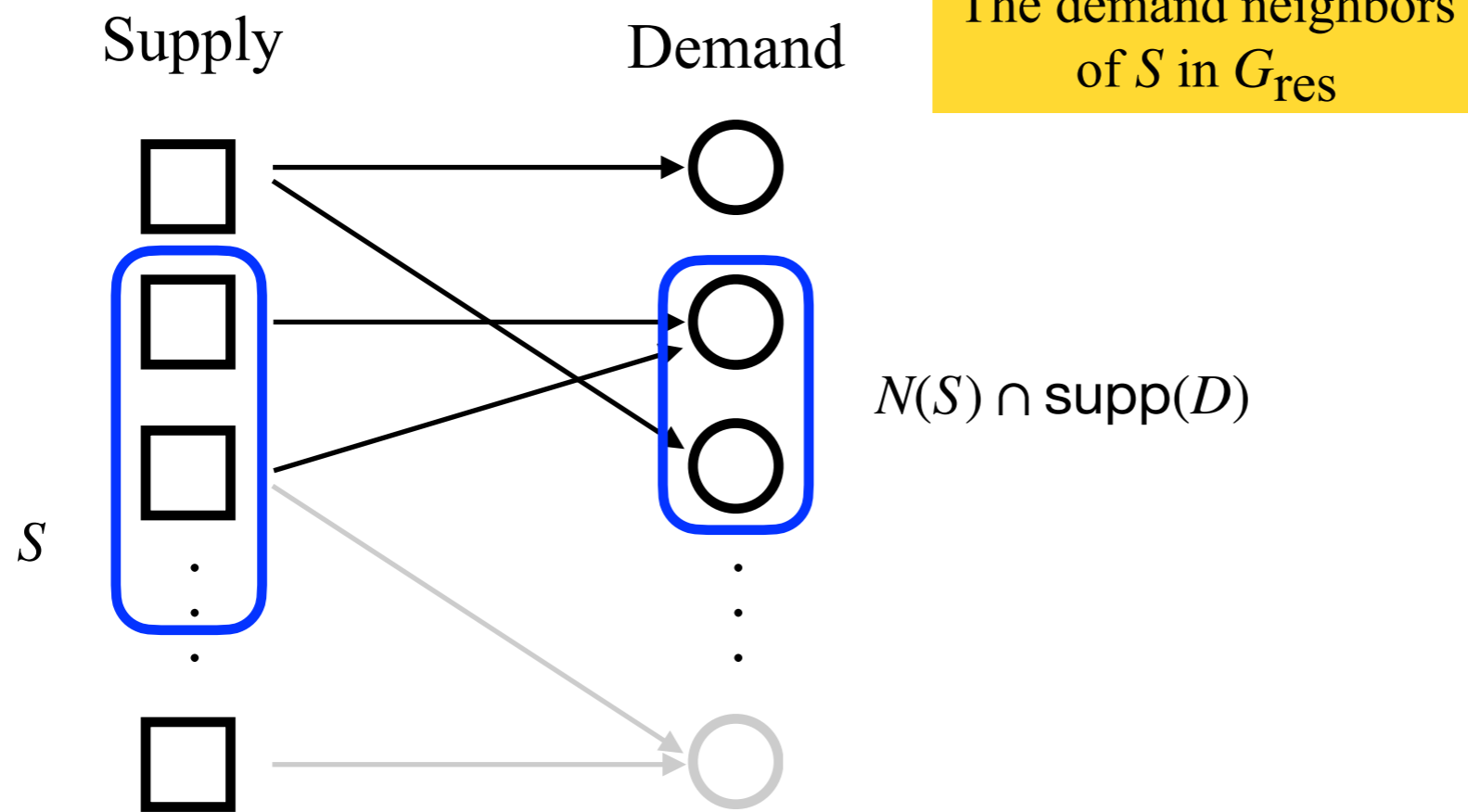
$$Z(G, D) = \min_{S \subseteq [n]} \{n - |S| + |N(S) \cap \text{supp}(D)| / p\}$$



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To ensure  $\epsilon n$ -loss:

Strong “ $\epsilon n$ -connectivity”

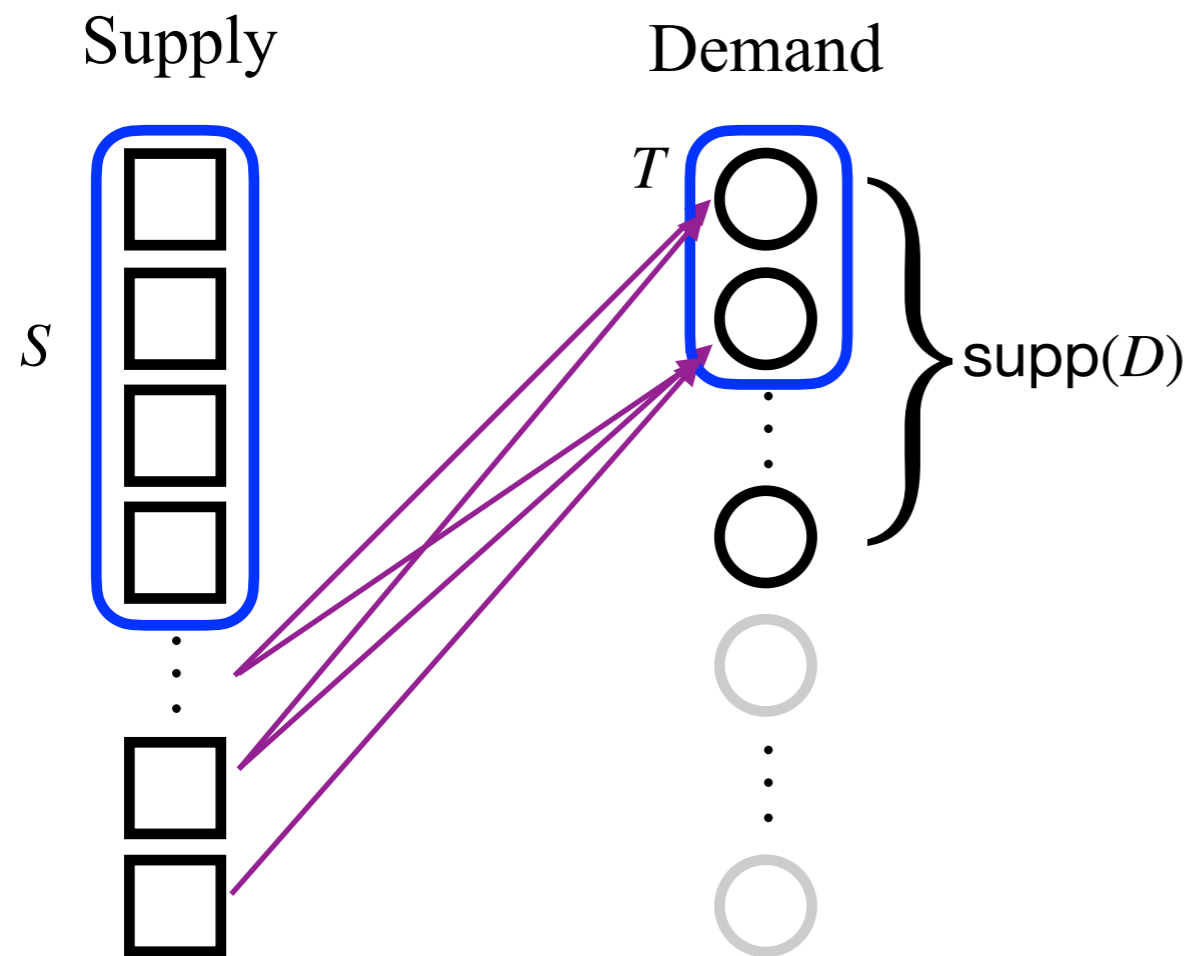
$$L(G, D) \geq (1 - \epsilon)n \iff \forall S \subset [n] : |N(S) \cap \text{supp}(D)| \geq p(|S| - \epsilon n)$$

# Ruling out Large Bottleneck $S$

- $S$  is called a bottleneck, if  $|N(S) \cap \text{supp}(D)| < p(|S| - \epsilon n)$
- A bottleneck  $S$  is called “large”, if  $|S| \geq \epsilon^c n$  for some choice of  $c \in (0,1)$

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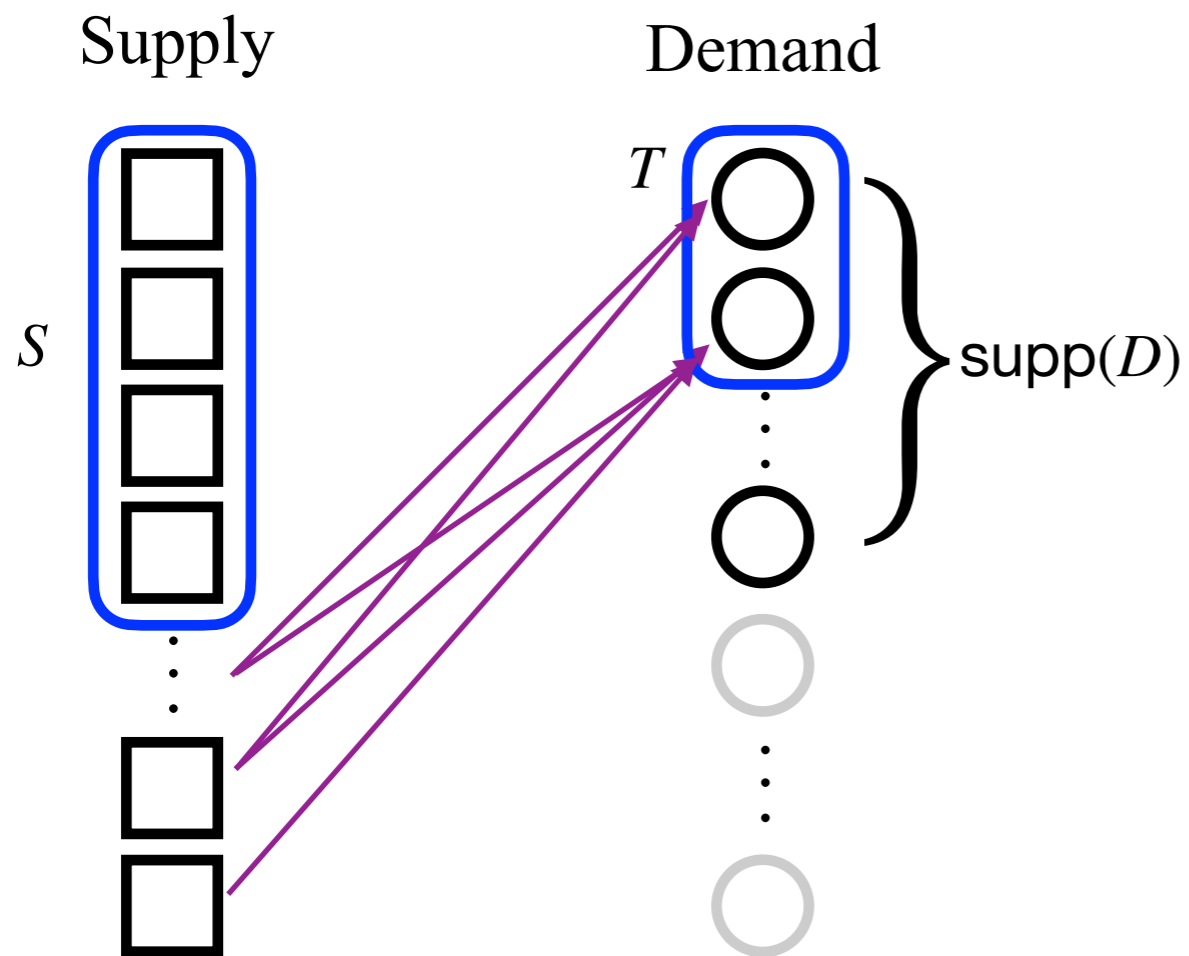


Large Bottleneck  $S$

- $S$  is a “large” bottleneck  $\implies$
- $\exists$  demand subset  $T \subset \text{supp}(D)$  with  $|T| = |\text{supp}(D)| - p(|S| - \epsilon n)$  s.t. there is no cross-edge between  $S$  and  $T$ , i.e.,  $e(S, T) = 0$

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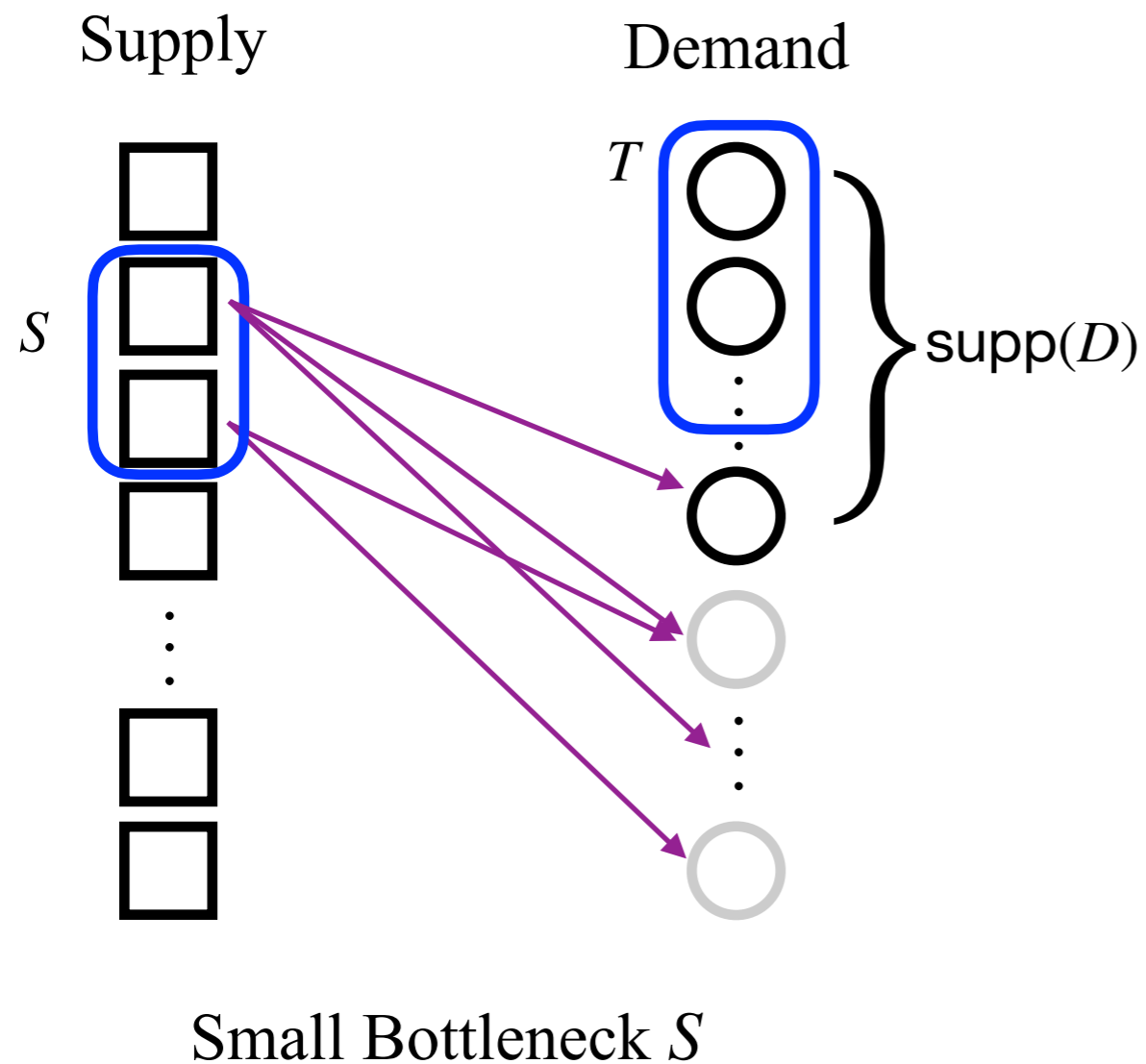


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- A simple union bound over  $S$  and  $T$  shows that there is no such big cut whp
- Regularity on the demand side and random connections are important

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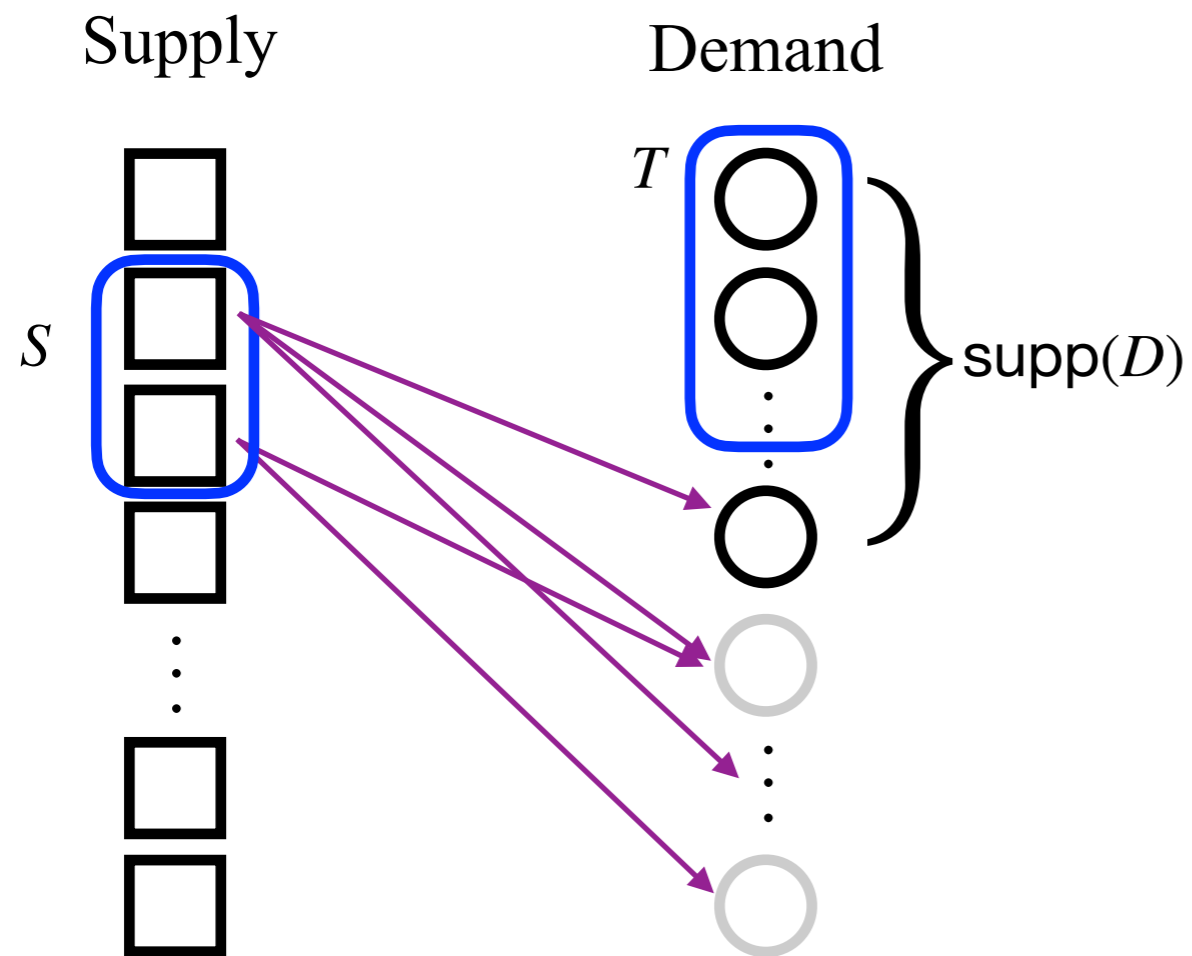


## Key challenge:

$\{e(S, T)\}$  are highly correlated across different  $T \subset \text{supp}(D)$ , so a simple union bound over  $S$  and  $T$  does not work

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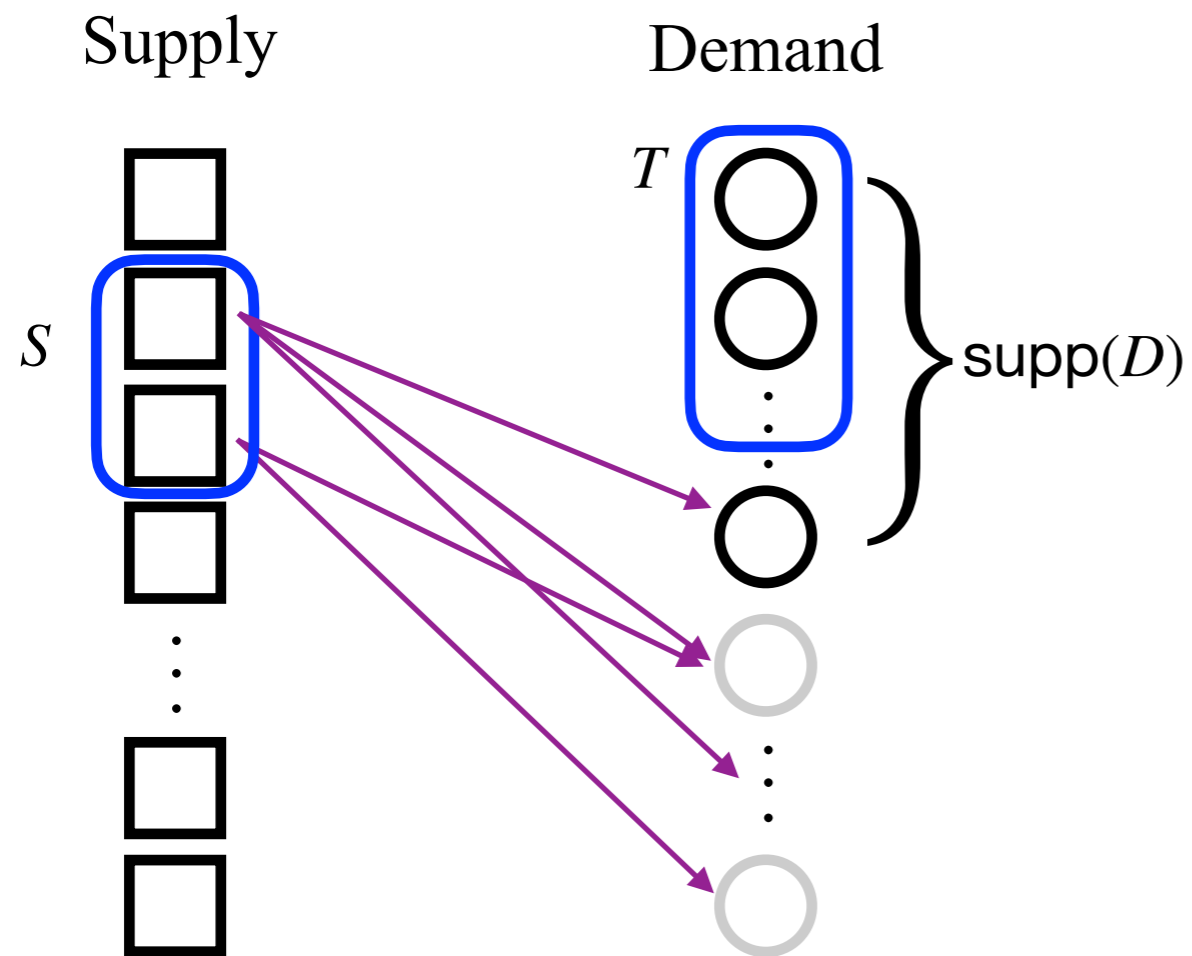
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$e(S, \text{supp}(D)) > \gamma |S|$  for all  $S$  with  $|S| \geq \epsilon n$ , for some  $\gamma > 0$

Small Bottleneck  $S$   
Rule out by (1)

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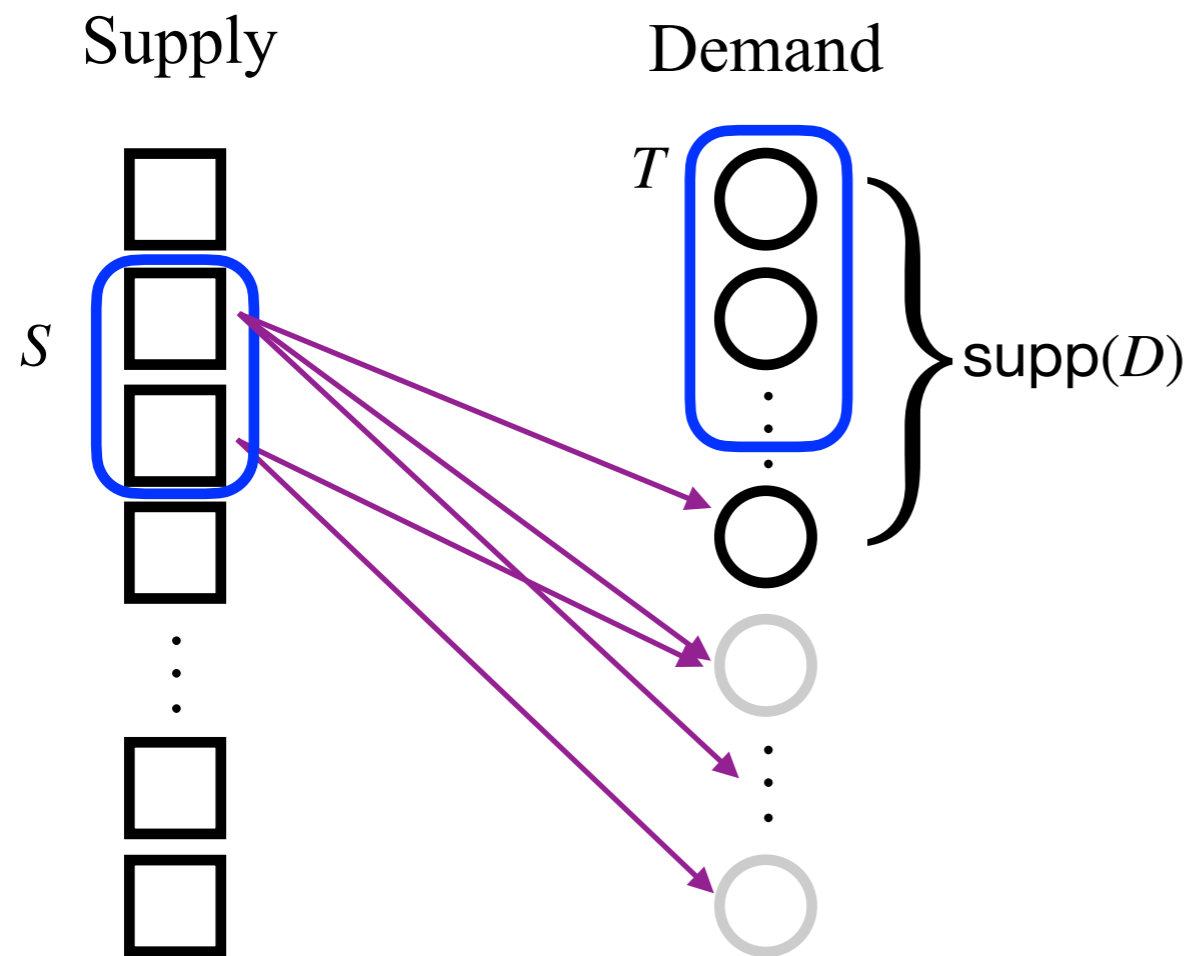
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A stronger requirement than the bound on the # isolated supplier nodes

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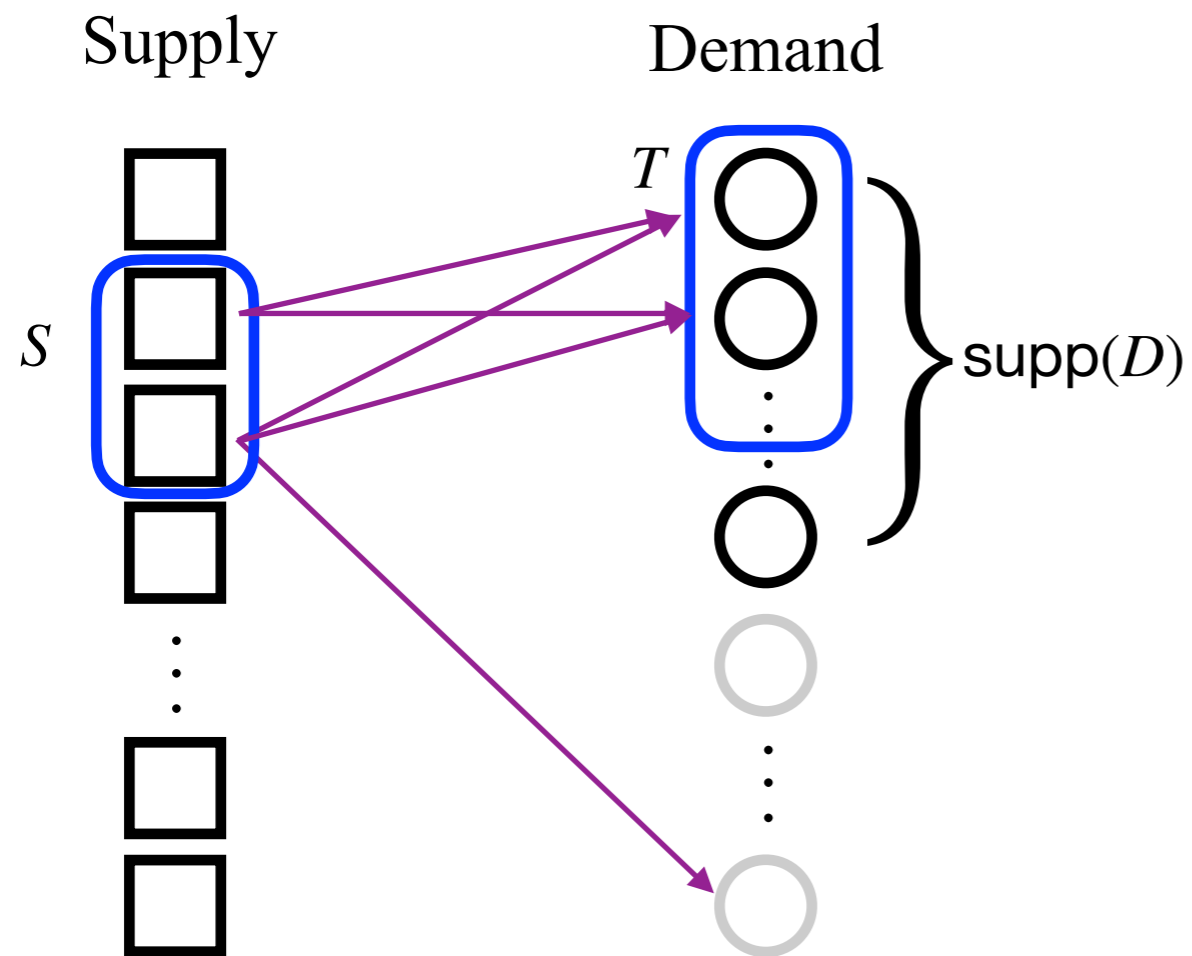
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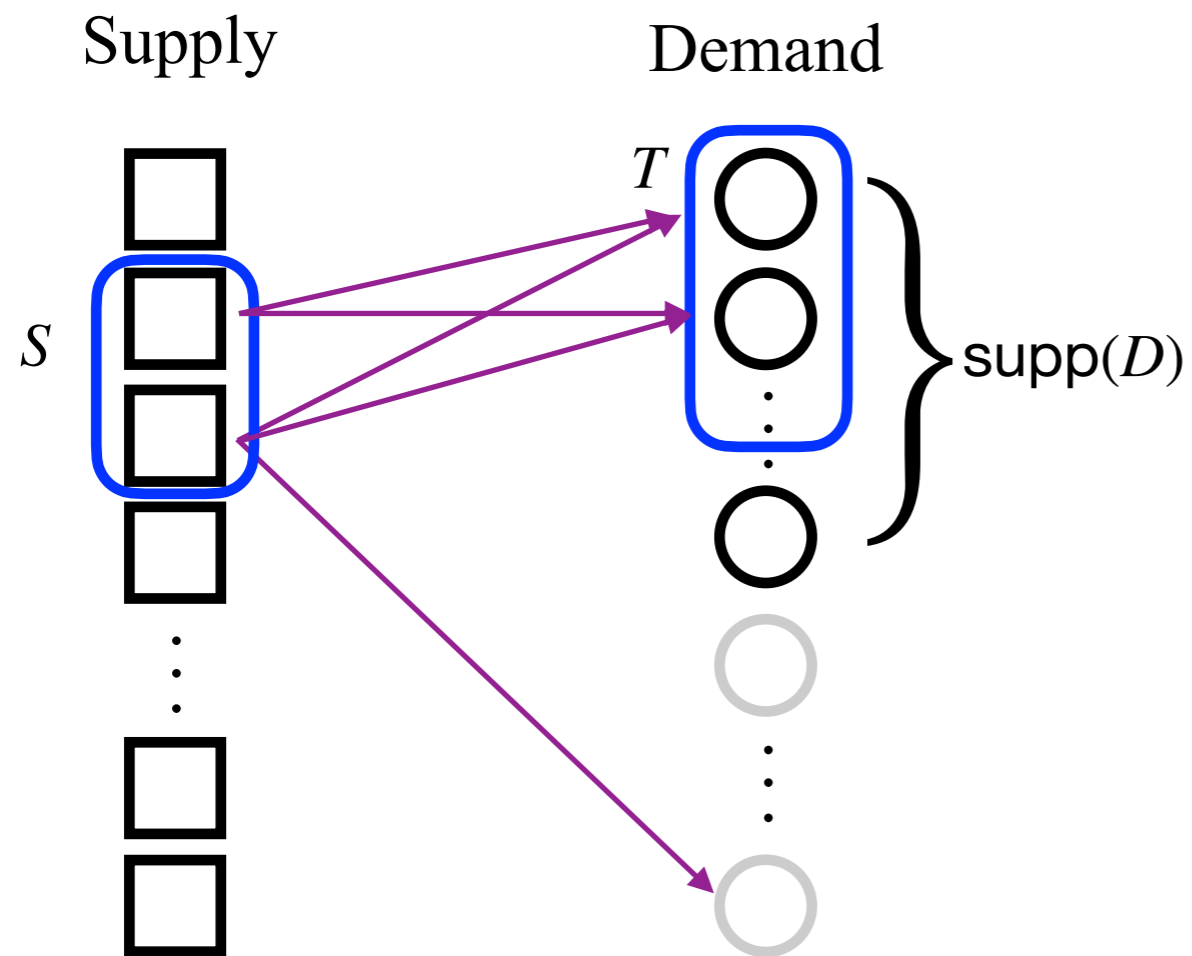
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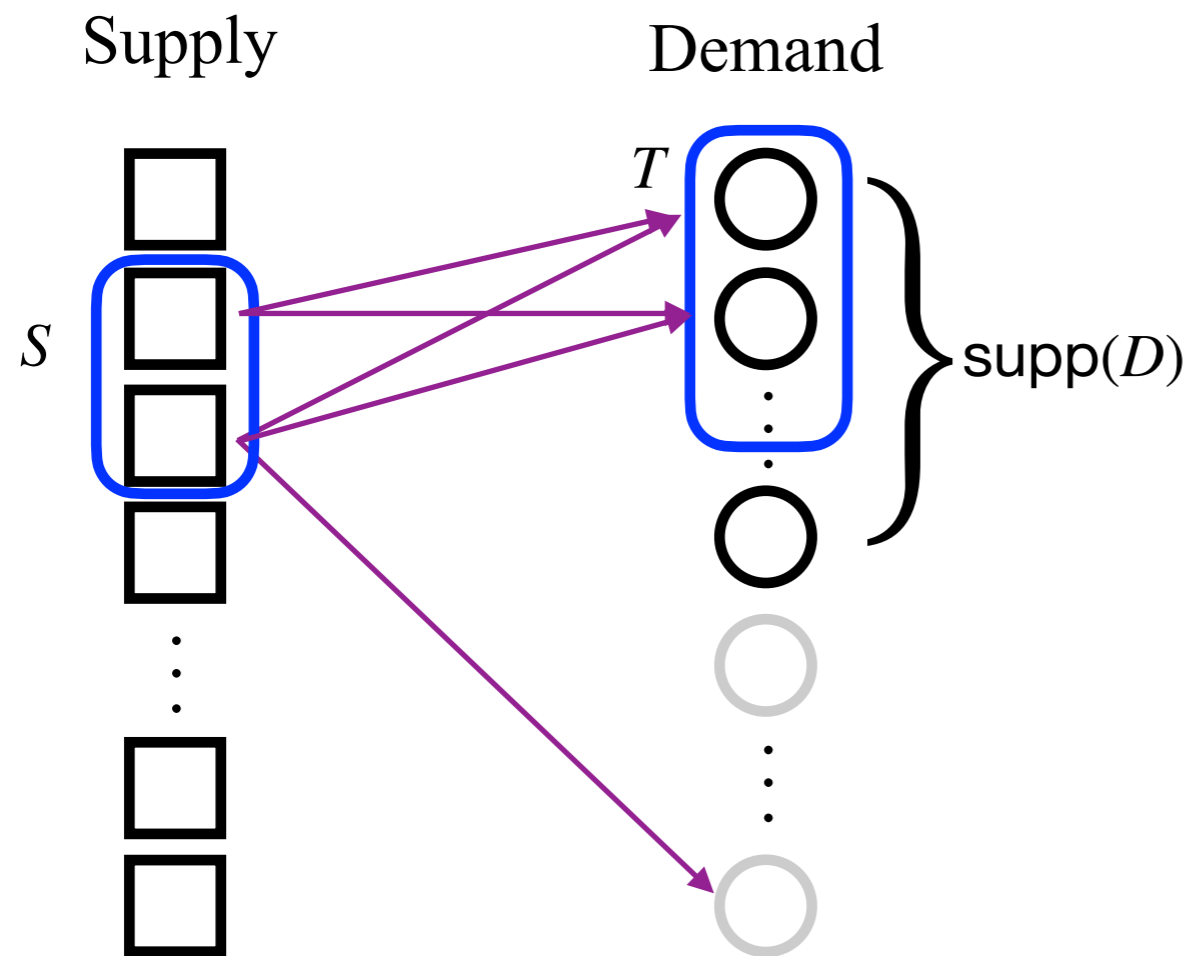


Small Bottleneck  $S$   
 Rule out by (2)

- (1) *Little waste of supply:*  
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- (2) *Little congestion:*  $e(S, T) < \gamma |S|$  for all  $S$  with  $\epsilon n \leq |S| \leq \epsilon^c n$  and all  $T \subset \text{supp}(D)$  with  $|T| \leq p(|S| - \epsilon n)$

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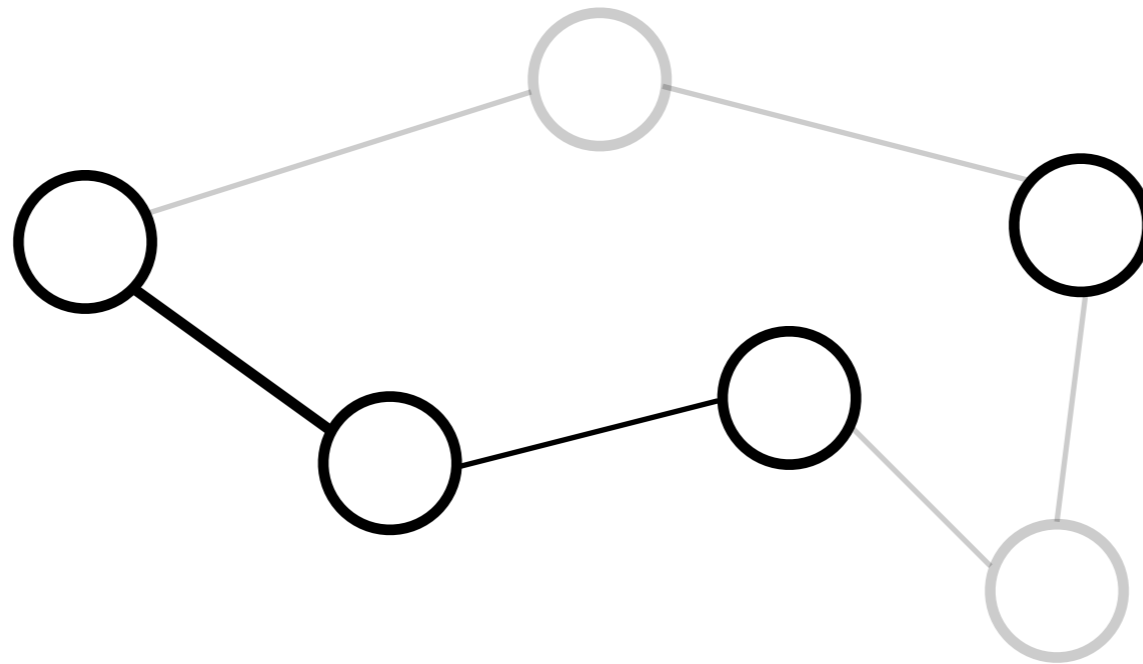
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- (1) + (2)  $\Rightarrow$  small bottleneck  $S$  cannot occur
  - Regularity on the supply side and random connections are important

# Proof ideas for transportation flexibility



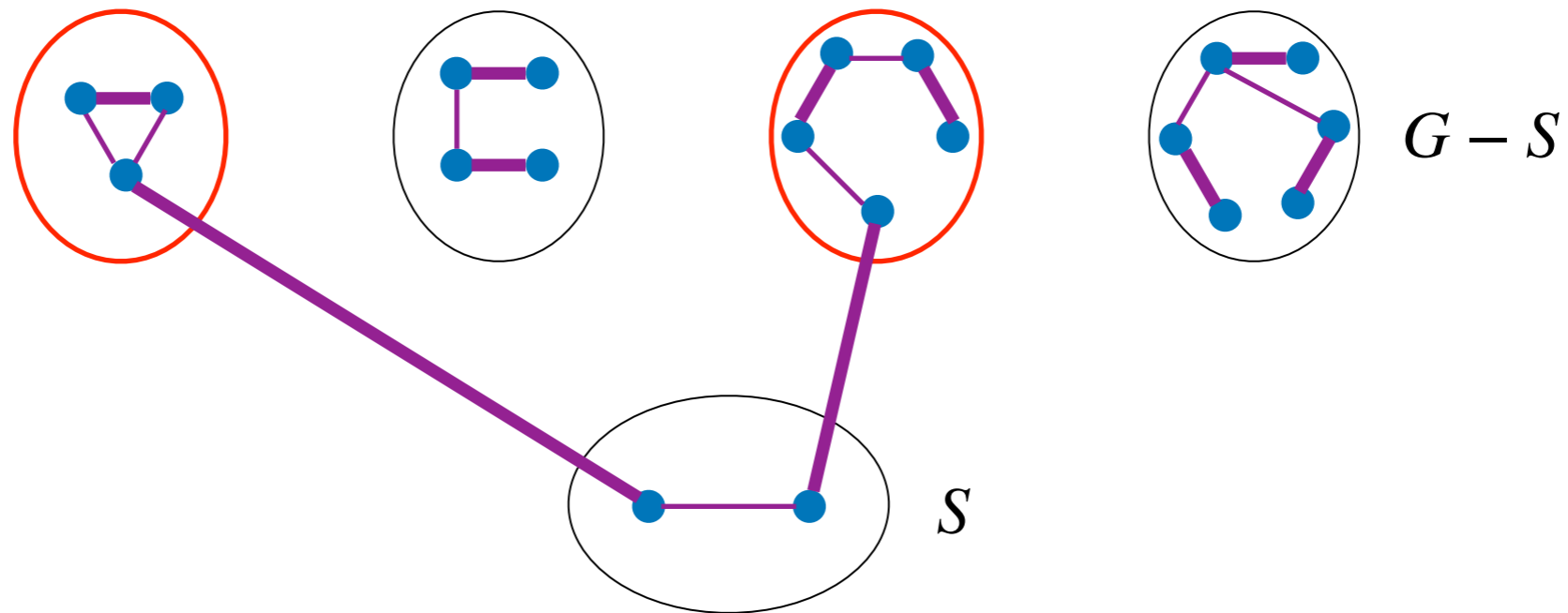
# Tutte-Berge theorem

**Theorem** [Tutte '47, Berge'58]

The number of unmatched vertices in a maximum matching of graph  $G$  is given by

$$\max_{S \subseteq V(G)} (\text{odd}(G - S) - |S|)$$

# of odd components when  $S$   
removed



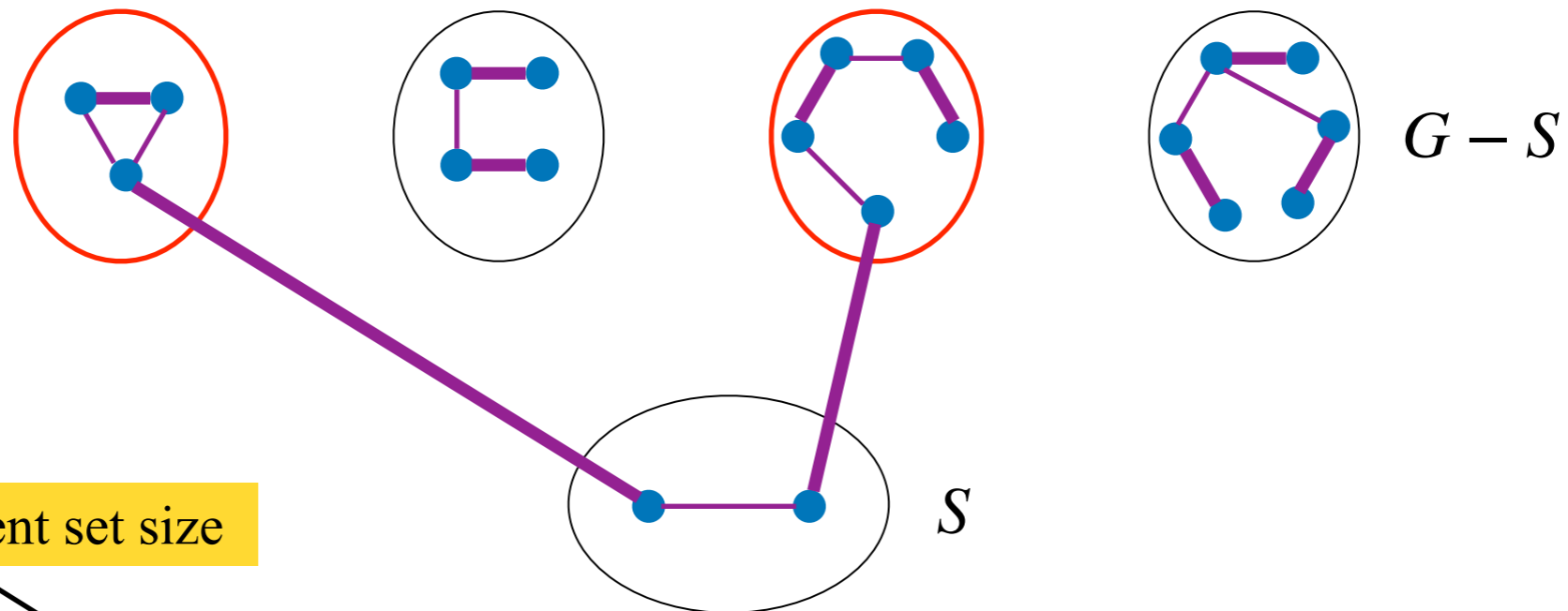
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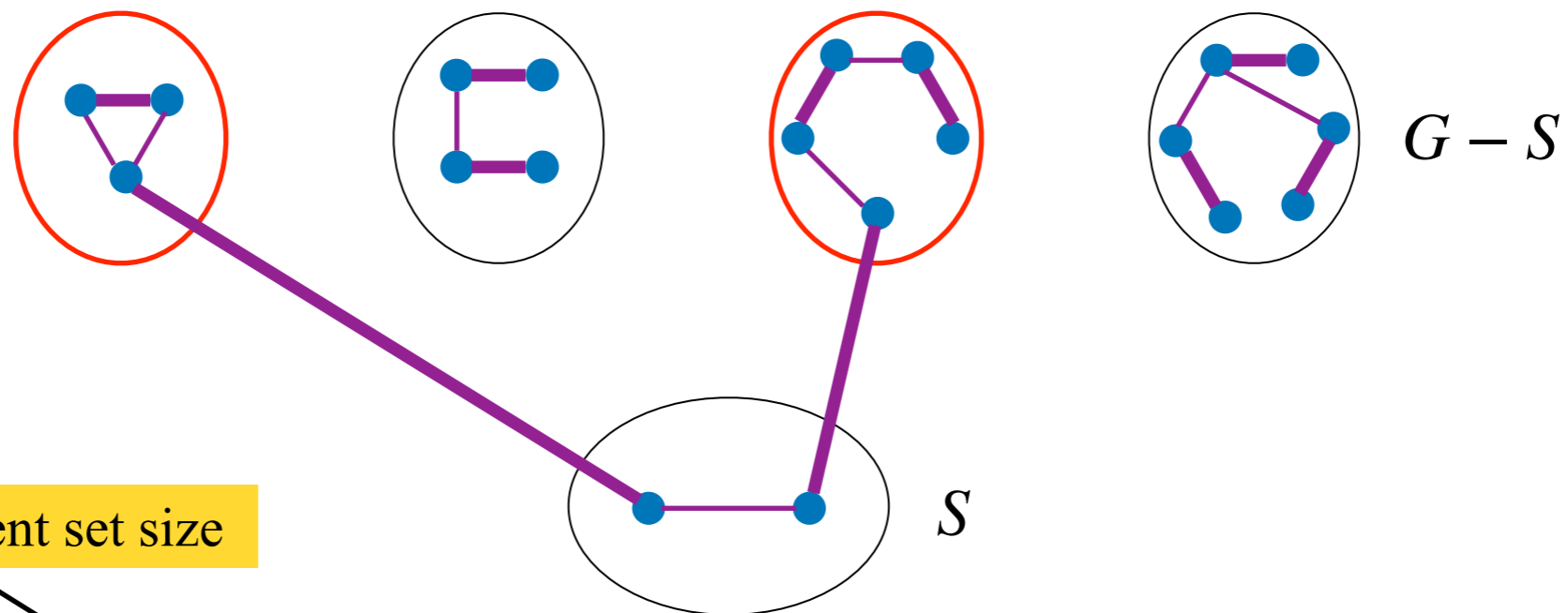
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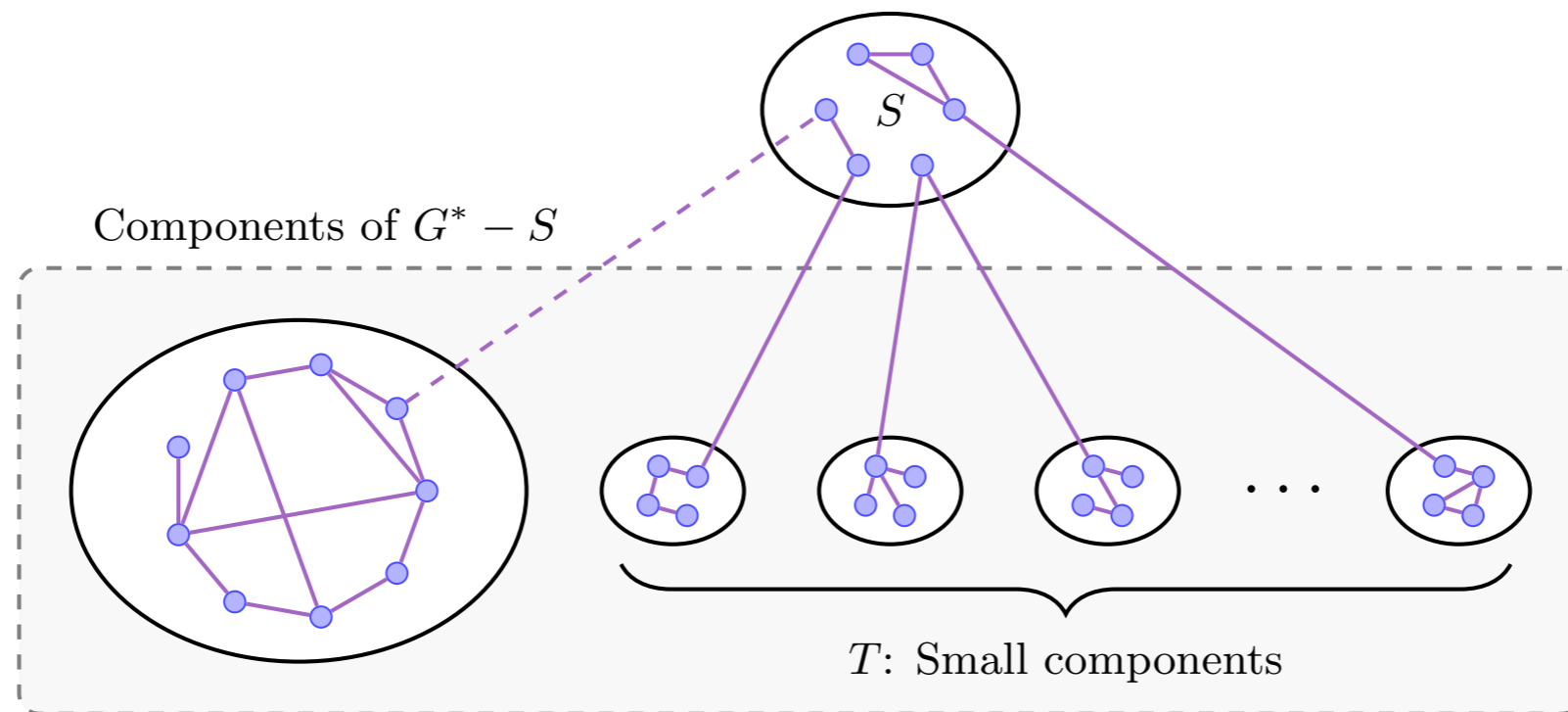


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For a random  $d$ -regular graph  $G$ ,  $\text{Ind}(G) \leq 2n \log(d)/d$

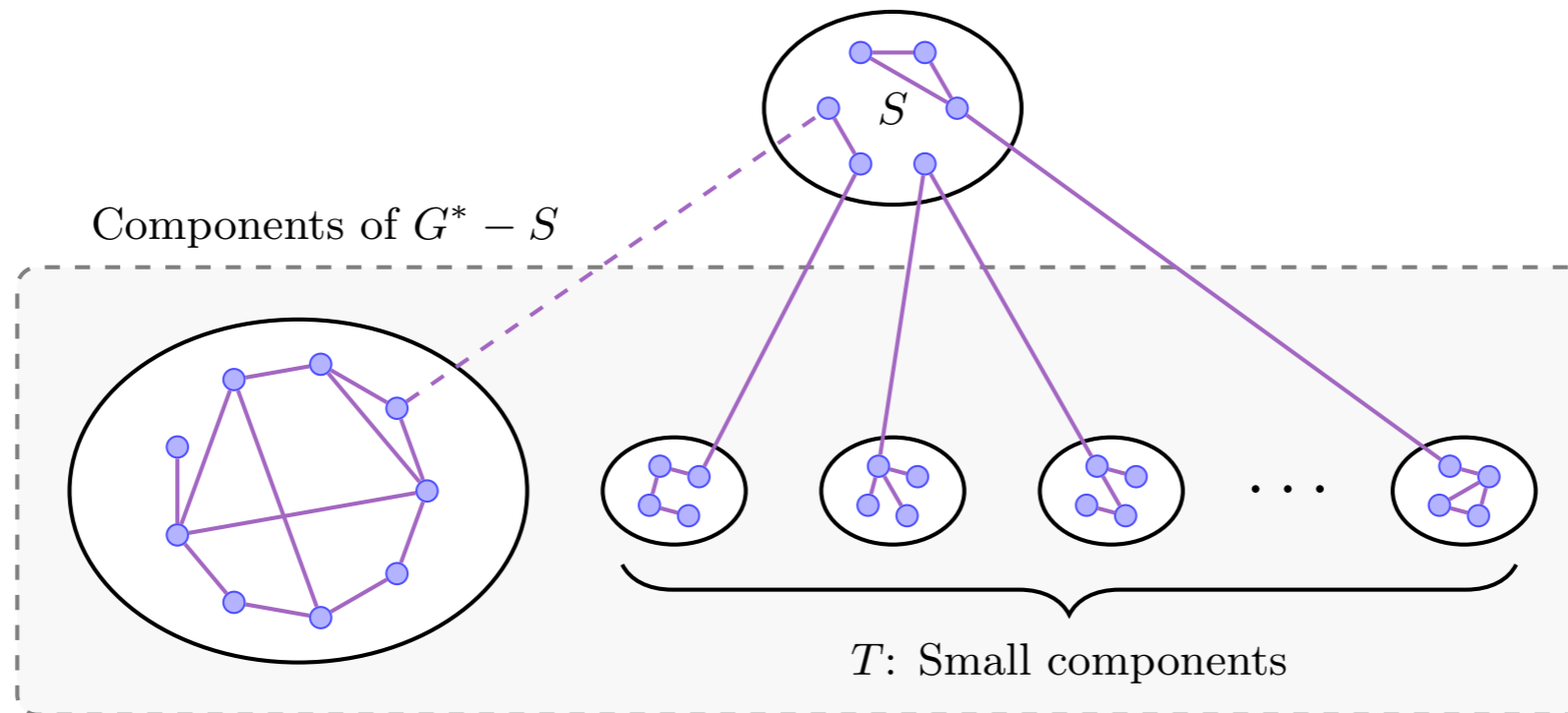
# Constant Loss Regime: Ruling out Small Bottleneck $S$

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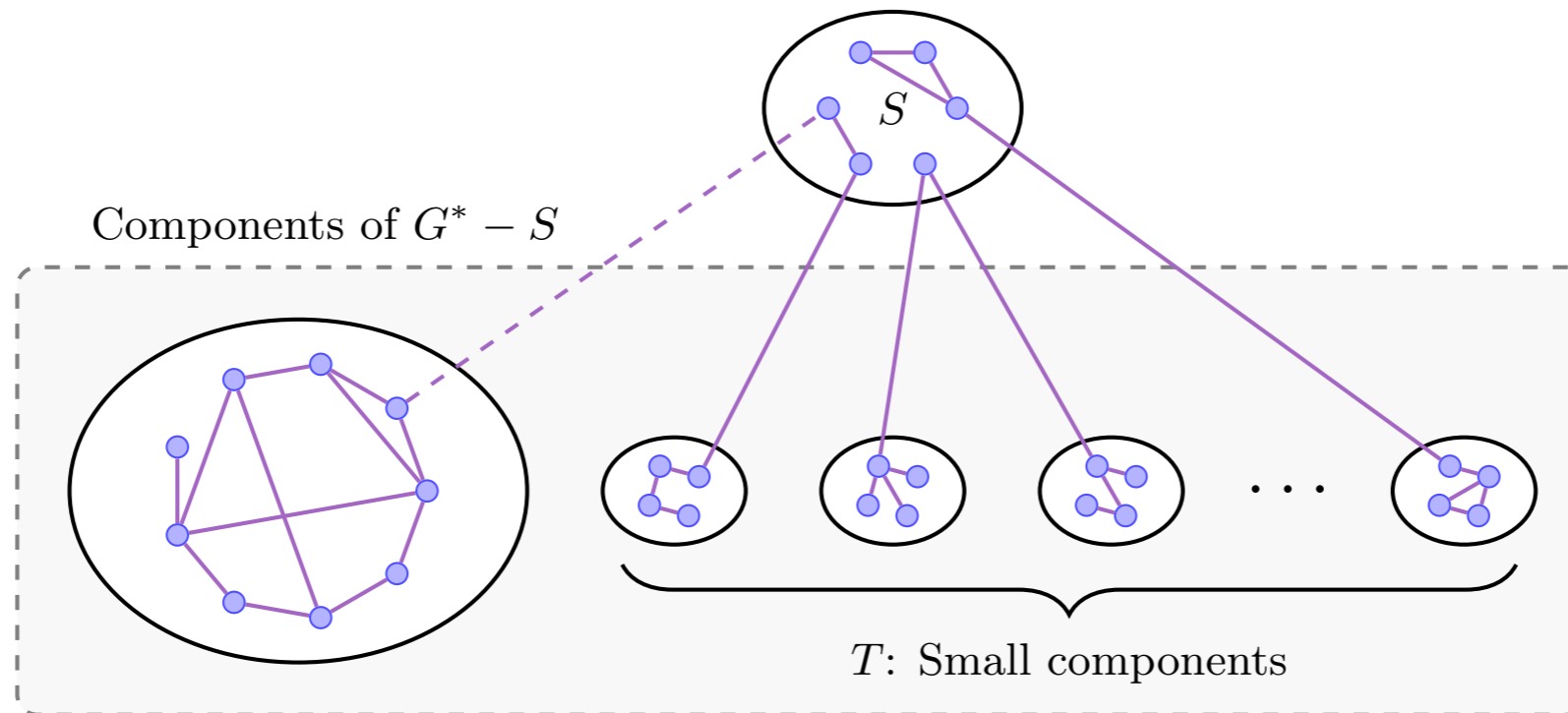
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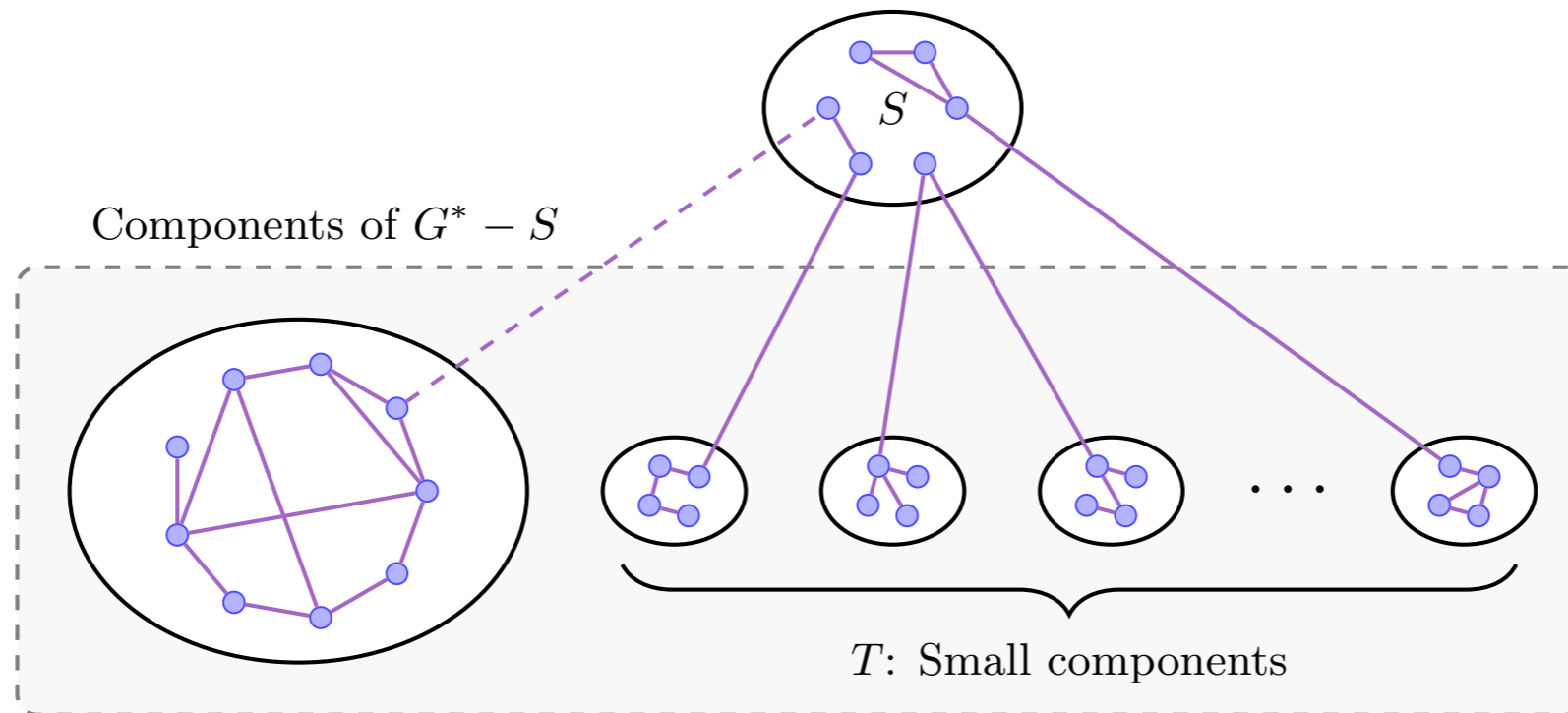
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- (Little congestion)  $\Rightarrow$  since both  $S$  and  $T$  are small,  $e(S, T) \leq |S|$  (contradiction)

# Fractional Loss Regime: Local Weak Convergence

Asymptotic size of maximum matching can be determined locally

**Theorem** [Bordenave-Lelarge-Salez '13]

Suppose  $G_n$  admits a local weak convergence to a **Galton-Watson tree** with degree distribution  $\pi$ . The **fraction of unmatched vertices** in a maximum matching

$$\alpha(G_n) \xrightarrow{\mathbb{P}} \max_{t \in [0,1]} F(t),$$

where  $F(t) = t\phi'(1-t) + \phi(1-t) + \phi\left(1 - \frac{\phi'(1-t)}{\phi'(1)}\right) - 1$  and  $\phi(t) = \sum_k \pi_k t^k$ .

# Fractional Loss Regime: Local Weak Convergence

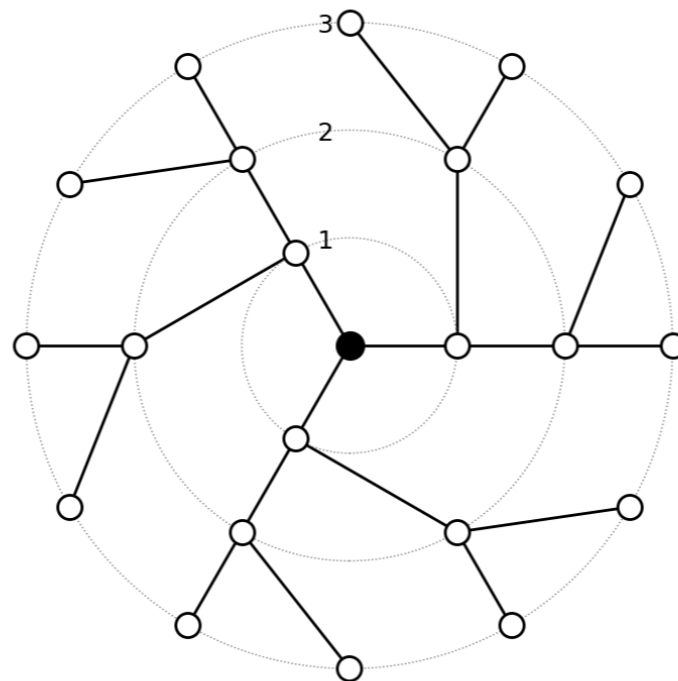
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Local neighborhood of  
3-regular graph

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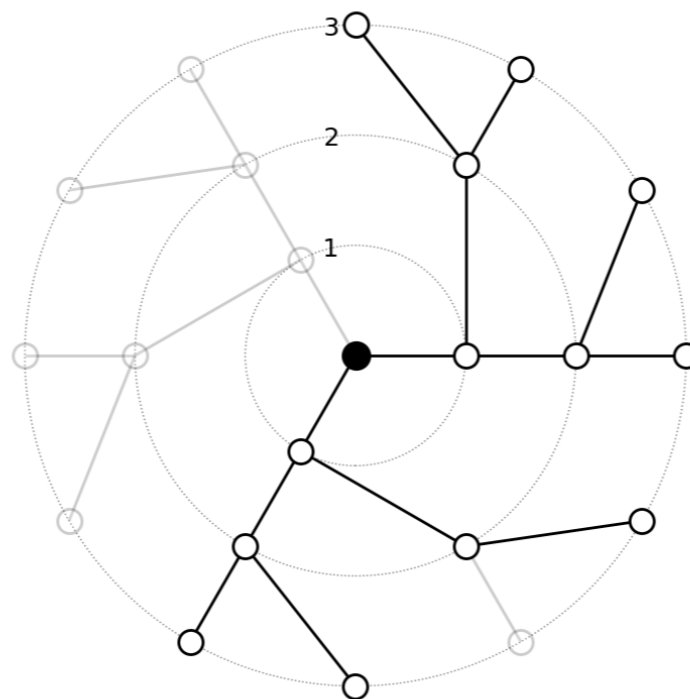
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Local neighborhood of  
3-regular graph  
after vertex deletion

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- In our setting,  $G_n$  is the random  $d$ -regular graph with random vertex removal (with probability  $q$ ). We show it converges locally to **GW tree with degree distribution  $\pi = \text{Binom}(d, p)$**  with  $p = 1 - q$

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- Thus,  $\phi(t) = (pt + 1 - p)^d$  and we show  $F(t)$  has three extremum points with the first one being the maximum and  $\max_{t \in [0,1]} F(t) = (1 + o_d(1))q^d$

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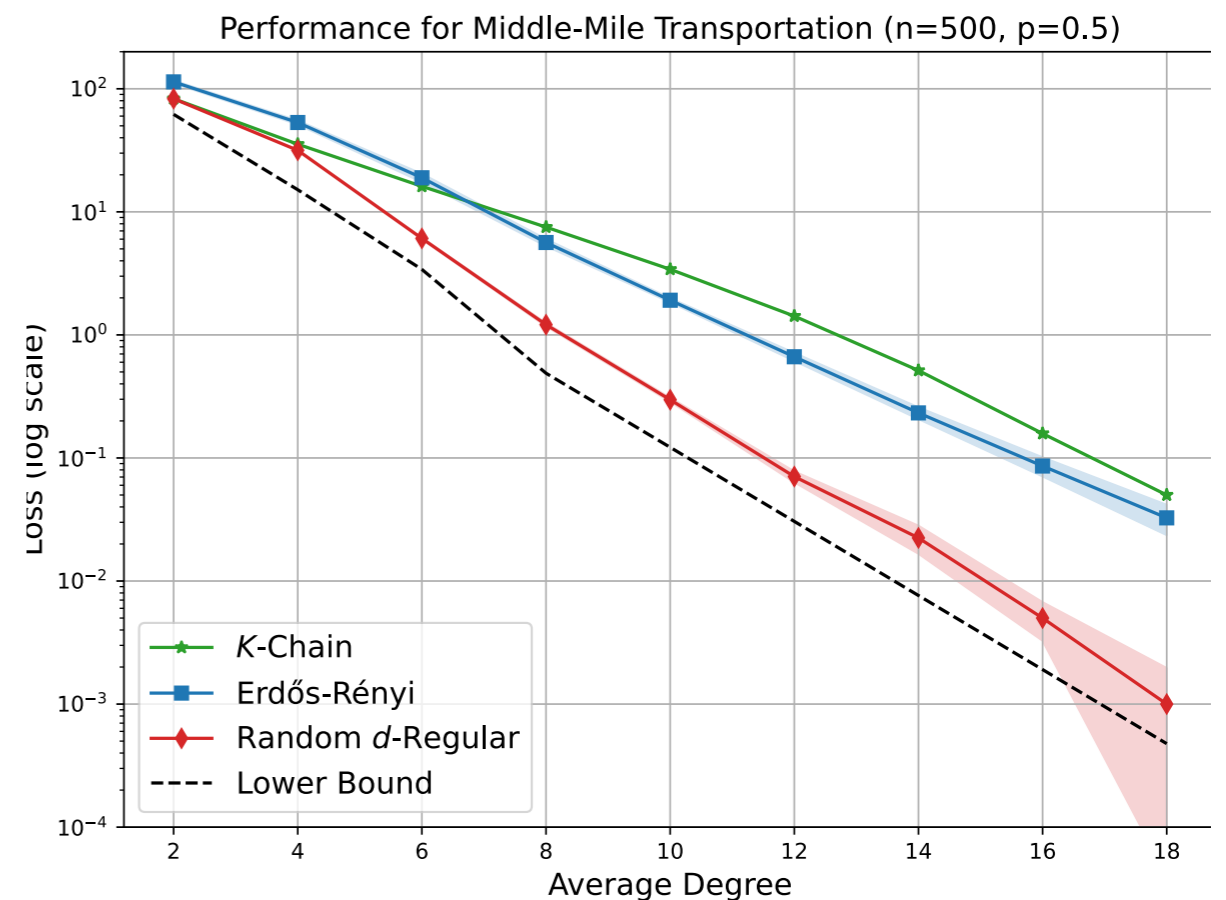
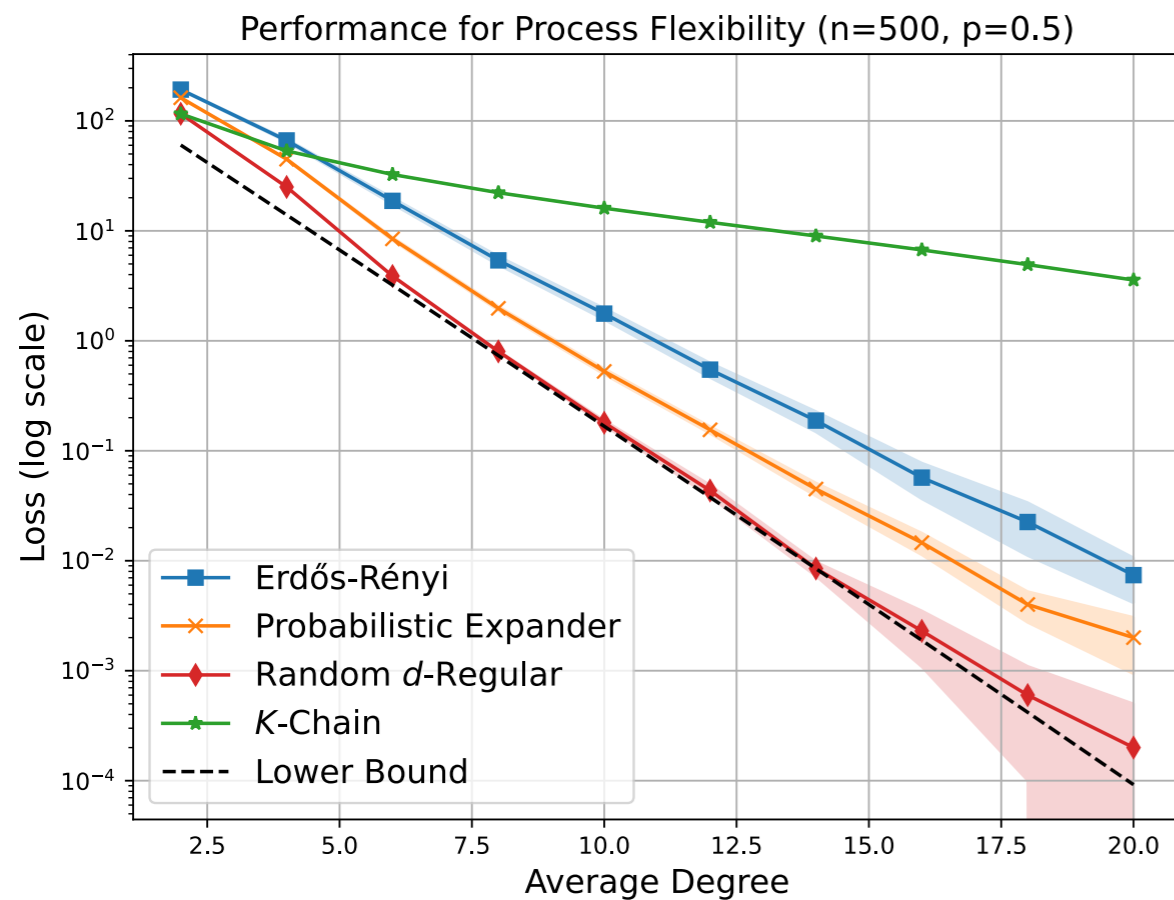
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- So, when  $d \geq (1 + \delta)\log(1/\epsilon)/\log(1/q)$ ,  $\alpha(G_n) \leq \epsilon$  and thus  $\mathbb{E}_D[L(G, D)] \leq \epsilon n$

# Numerical Experiments



**Random regular graphs** can achieve performance close to the theoretical lower bounds even for moderate graph sizes and relatively small degrees

# Summary

	Setting	Graph design	$\epsilon n$ -loss	Constant loss
Lower bound	Both	Any	$\frac{\log(1/\epsilon)}{\log(1/q)}$	$\frac{\log(n)}{\log(1/q)}$
Chou et al. (2011)	Bipartite	Chain	$\Omega(1/\epsilon)$	-
Chen et al. (2015)	Bipartite	Probabilistic Expander	$\Omega(\log(1/\epsilon))$	-
Feng et al. (2024)	Unipartite	Ring; Chain; Cluster; Erdős–Rényi	$\Omega(\log(1/\epsilon))$	$\Omega(\log(n))$
Our work	Both	Random regular	$\frac{\log(1/\epsilon)^*}{\log(1/q)}$	$\frac{\log(n)^*}{\log(1/q)}$

\*Within a factor of  $(1 + \delta)$  for arbitrarily small  $\delta > 0$ .

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Chen et al. (2015)	Bipartite	Probabilistic Expander	$\Omega(\log(1/\epsilon))$	-
Feng et al. (2024)	Unipartite	Ring; Chain; Cluster; Erdős–Rényi	$\Omega(\log(1/\epsilon))$	$\Omega(\log(n))$
Our work	Both	Random regular	$\frac{\log(1/\epsilon)^*}{\log(1/q)}$	$\frac{\log(n)^*}{\log(1/q)}$

\*Within a factor of  $(1 + \delta)$  for arbitrarily small  $\delta > 0$ .

## Future directions:

General demand distribution? Other flexibility network design problems?

# Summary

	Setting	Graph design	$\epsilon n$ -loss	Constant loss
Lower bound	Both	Any	$\frac{\log(1/\epsilon)}{\log(1/q)}$	$\frac{\log(n)}{\log(1/q)}$
Chou et al. (2011)	Bipartite	Chain	$\Omega(1/\epsilon)$	-
Chen et al. (2015)	Bipartite	Probabilistic Expander	$\Omega(\log(1/\epsilon))$	-
Feng et al. (2024)	Unipartite	Ring; Chain; Cluster; Erdős–Rényi	$\Omega(\log(1/\epsilon))$	$\Omega(\log(n))$
Our work	Both	Random regular	$\frac{\log(1/\epsilon)^*}{\log(1/q)}$	$\frac{\log(n)^*}{\log(1/q)}$

\*Within a factor of  $(1 + \delta)$  for arbitrarily small  $\delta > 0$ .

## Future directions:

General demand distribution? Other flexibility network design problems?

## Reference:

W. Li, X. Niu, Y. Wei, & J. Xu, *Optimality of Random Regular Graphs in Sparse Network Designs*, [SSRN Preprint](#), March 2026