

All-Something-Nothing Phase Transitions in Planted Subgraph Recovery

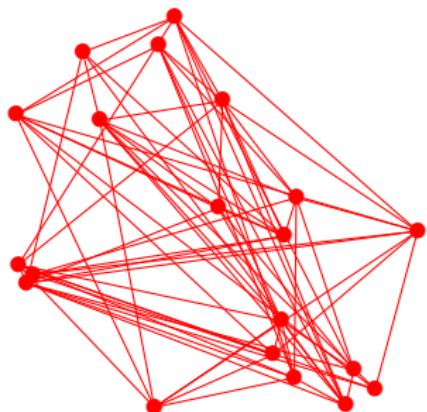
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The Fuqua School of Business
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Joint work with
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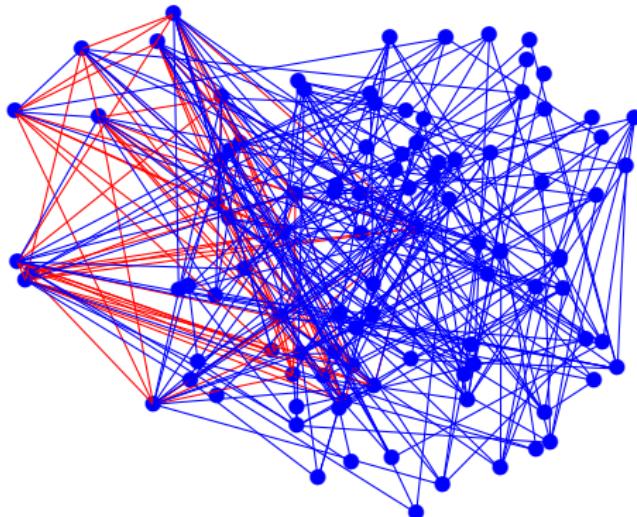
October 16, 2023
INFORMS Annual Meeting

The Planted subgraph recovery problem



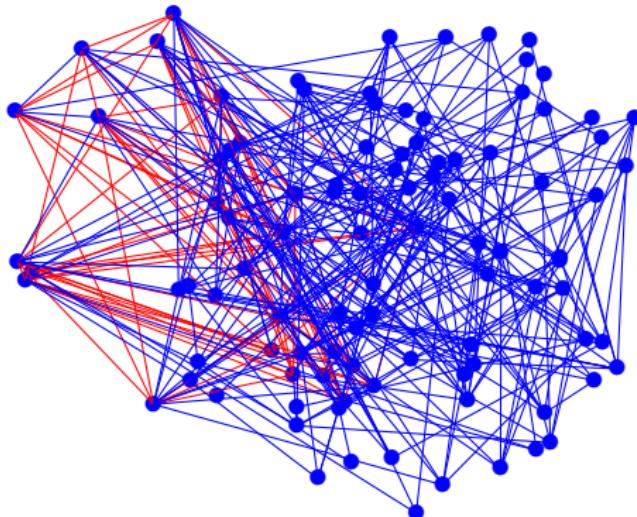
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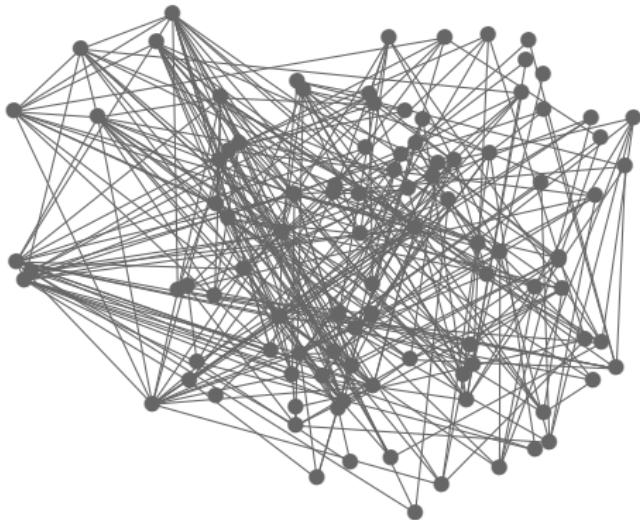
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- A background graph $G_0 \sim \mathcal{G}(n, p)$

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- A hidden subgraph H^*
- A background graph $G_0 \sim \mathcal{G}(n, p)$
- Observe union graph $G = H^* \cup G_0$
- Goal: recover H^* from G

Encompasses many planted problems...

- Planted clique model
- Planted tree model [Massoulié-Stephan-Towsley '18]
- Planted Hamiltonian cycle (TSP) model
[Bagaria-Ding-Tse-Wu-X.'18]
- Planted k -NN graph model [Ding-Wu-X.-Yang '19]
- Planted matching [Chertkov-Kroc-Krzakala-Vergassola-Zdeborová '10]
- ...

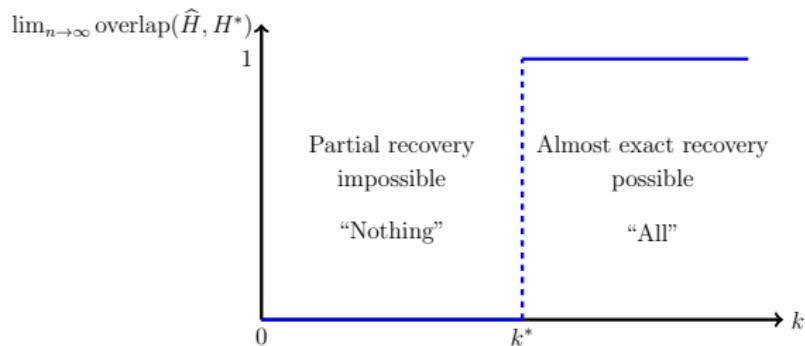
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Fruitful venue for studying statistical and computational aspects of network inference

Peculiar “All-or-Nothing” phase transitions

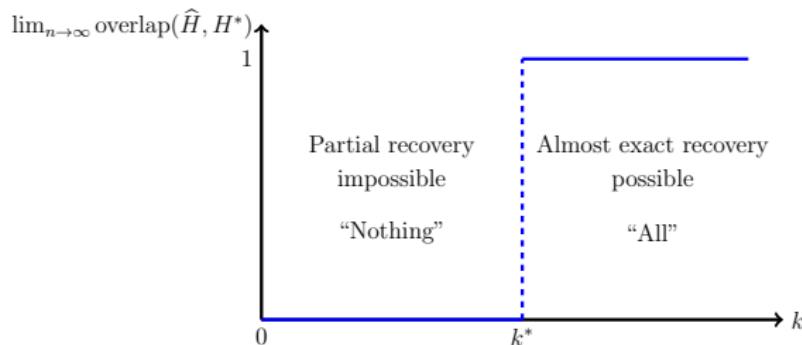
For both planted k -clique and k -tree model:



$$\text{overlap}(H, H^*) \triangleq \frac{|H \cap H^*|}{|H^*|}$$

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$$k^* = \begin{cases} 2 \log_2(n) & \text{planted clique in } G_0 \sim \mathcal{G}(n, 1/2) \\ \log_{1/\lambda}(n) & \text{planted tree in } G_0 \sim \mathcal{G}(n, \lambda/n) \end{cases}$$

coincides with the **first-moment threshold** k_{1M} in G_0 ,
at which the expected # of copies in G_0 equals 1

“All-or-Nothing” phase transitions are prevalent

Theorem (Mossel-Niles-Weed-Sohn-Sun-Zadik '23)

The planted subgraph recovery model exhibits AoN at p_{1M} , if

- *H is sufficiently dense and balanced:*

$$e(H) \gg v(H) \log v(H) \text{ and } \frac{e(H)}{v(H)} \geq \frac{e(J)}{v(J)}, \forall J \subset H$$

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- *H is sufficiently small and strictly balanced for $c > 0$:*

$$e(H) + v(H) \leq \frac{c \log n}{3 \log \log n} \text{ and } \frac{e(H) - c}{v(H)} \geq \frac{e(J) - c}{v(J)}, \forall J \subset H$$

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AoN was also established for many other models: sparse linear regression, sparse tensor PCA, group testing, graph alignment, ...

Focus of this talk

Question

Is AoN universal in planted subgraph recovery?

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Consider **large**, **sparse**, and **balanced** graphs

Planted factor model [Sicuro-Zdeborová '20]

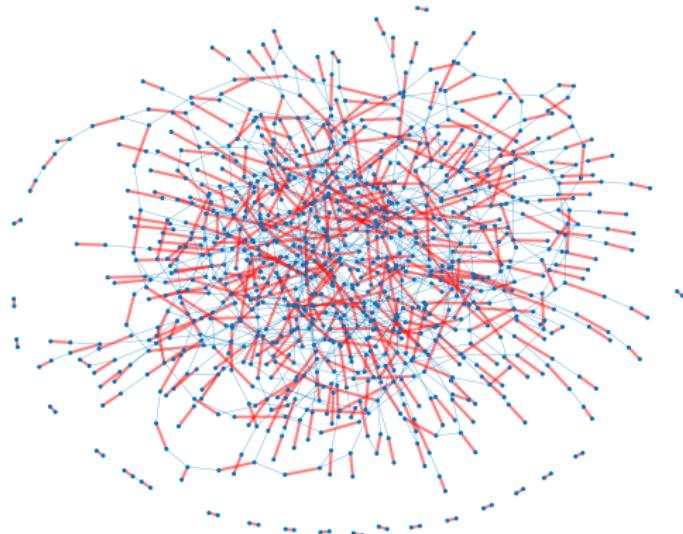
H is uniformly chosen from all labeled k -factors (spanning k -regular graphs) for a fixed constant k :

- $k = 1$: perfect matching
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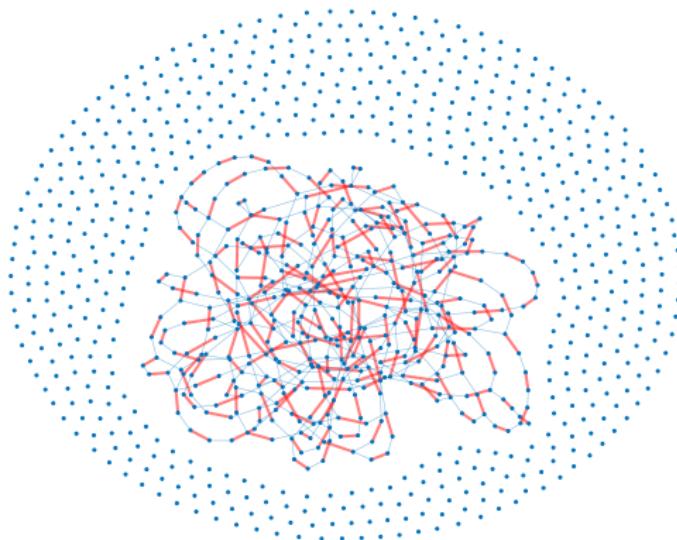


Planted matching model with $n = 1000$ and $\lambda = 1.5$

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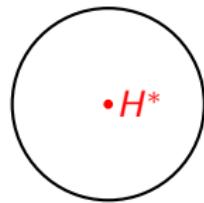
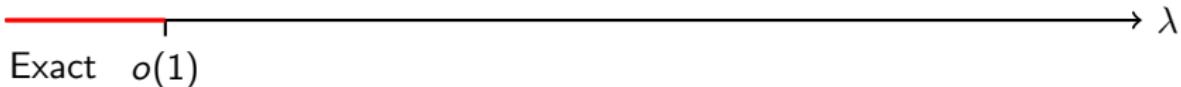
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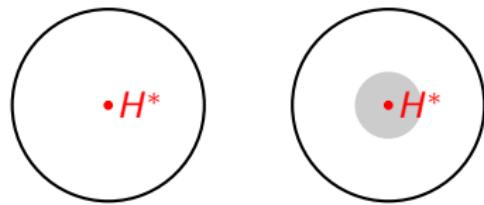
- Recall λ is the average degree in the background graph G_0
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- As λ increases, we expect to observe more k -factors in G
- But, how μ_G exactly behaves?

Our result [Gaudio-Sandon-X.-Yang '23]



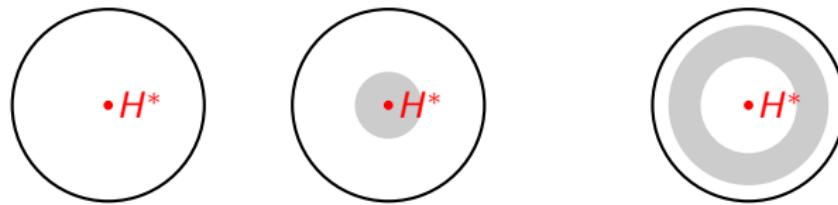
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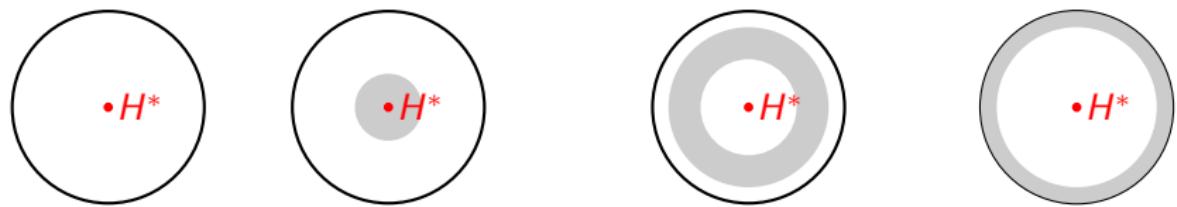
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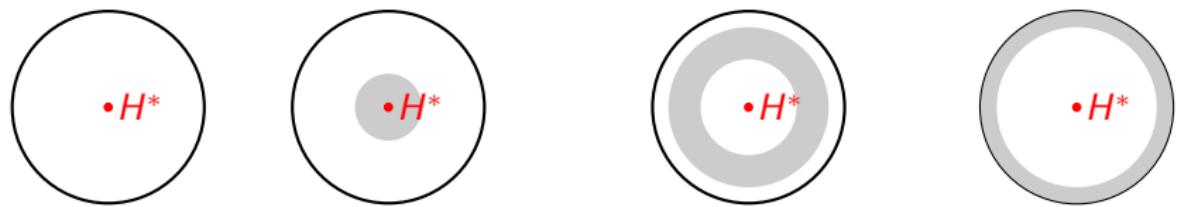
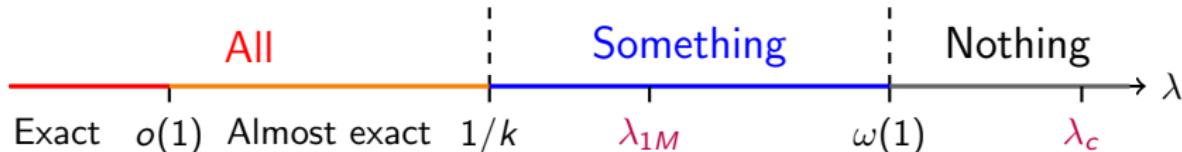
$\lambda = 1/k$ is sharp threshold for almost exact recovery: resolves conjecture in [Sicuro-Zdeborová '20]

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- 4 $\text{overlap}(H, H^*) \rightarrow 0$ for almost all $H \in \mathcal{H}(G)$

$$\lambda_{1M} = e(k!)^{2/k}/k \text{ and } \lambda_c = \log n + (k-1) \log \log n + \omega(1)$$

Proof sketch

- All phase:
 - ▶ $\lambda = o(1)$: $\text{overlap}(H, H^*) = 1$
 - ▶ $\lambda \leq 1/k$: $\text{overlap}(H, H^*) \rightarrow 1$
- Something phase: $1/k < \lambda \leq O(1)$:
 - ▶ $\text{overlap}(H, H^*) \leq 1 - \Omega(1)$
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Analyzing posterior distribution

Recall: posterior distribution is uniform over k -factors in G :

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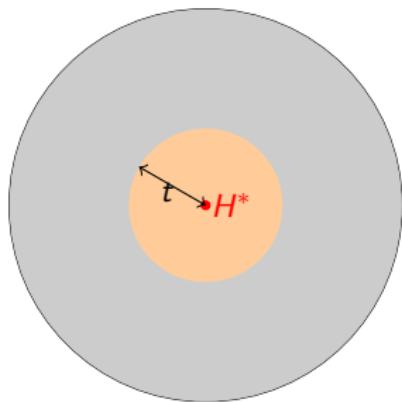
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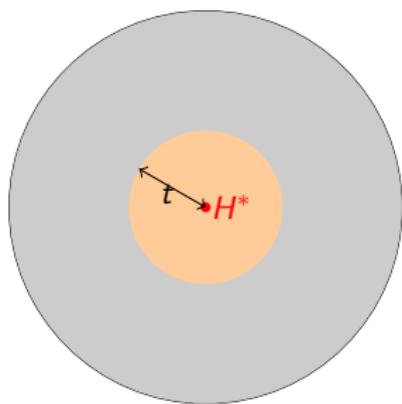


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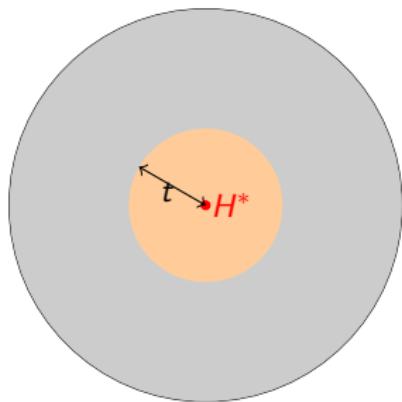
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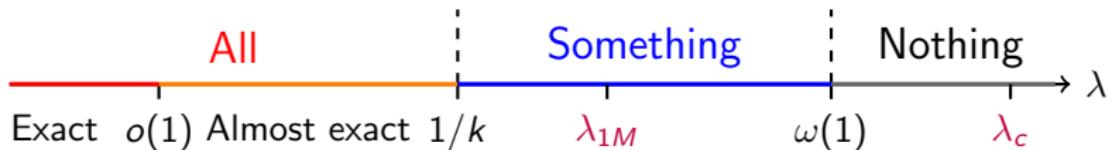
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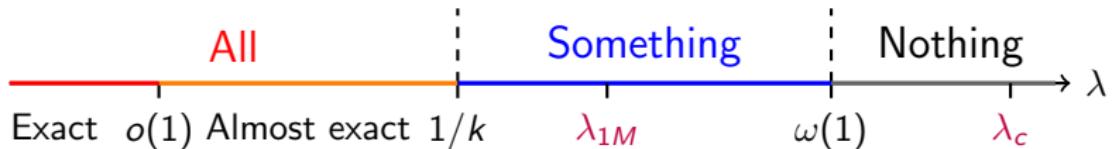


- Upper bound number of k -factors in G near H^*
- Lower bound number of k -factors in G far away from H^*
- $|\mathcal{H}_{\text{near}}(G)| \ll |\mathcal{H}_{\text{far}}(G)| \Rightarrow \text{overlap}(H, H^*) \leq 1 - t$
 - ▶ Something phase: $t = \Omega(1)$
 - ▶ Nothing phase: $t = 1 - o(1)$

Conclusion



Conclusion



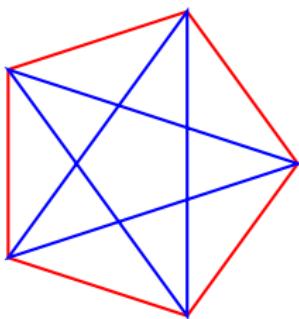
Open problems:

- ① Characterize the overlap as a function of λ in something phase
- ② Planted k -factor model for growing $k \equiv k(n)$
- ③ What causes “something” phase to emerge/disappear?
 - ▶ For dense or small subgraphs, we observe AoN
 - ▶ For sparse, large subgraphs, we observe ASN

Backup Slides

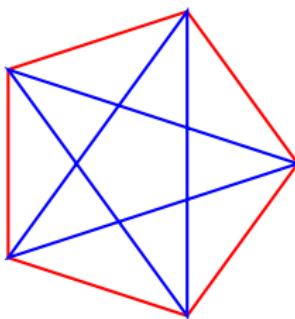
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As a consequence,

$$|\{k\text{-factor } H : |H \Delta H^*| = 2t\}| \leq \binom{kn/2}{t} (2t-1)!! \leq (kn)^t$$

$$\Rightarrow \mathbb{E}[|\{k\text{-factor } H : |H \Delta H^*| = 2t, H \subset G\}|] \leq (kn)^t \left(\frac{\lambda}{n}\right)^t = (k\lambda)^t$$

A generic, non-constructive lower bound

- Let \mathbb{P} and \mathbb{Q} denote the distribution of the planted k -factor model and $\mathcal{G}(n, \lambda/n)$, respectively
- Recall $\mathcal{H}(G)$ is the set of k -factors in G

Lemma (Mossel-Niles-Weed-Sohn-Sun-Zadik '23)

For any $\epsilon > 0$,

$$\mathbb{P} \{ |\mathcal{H}(G)| \geq \epsilon \mathbb{E}_{\mathbb{Q}} |\mathcal{H}(G)| \} \geq 1 - \epsilon$$

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- When $\lambda k = O(1)$, $\mathbb{E}_{\mathbb{Q}}|\mathcal{H}(G)| \ll |\mathcal{H}_{\text{near}}(G)|$ and falls short for proving $\text{overlap}(H, H^*) \leq 1 - \Omega(1)$ in “Something” phase

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→ need a tighter lower bound

Constructing k -factors far away from H^*

Goal: Find exponentially many long alternating Eulerian circuits (AEC) in G

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- long AEC are rare; but there are many possibilities to consider
- Natural second-moment argument doesn't work due to **excessive correlation between long AEC**.

Key idea: Sprinkling

- ① Reserve a small fraction of vertices
- ② Greedily construct many disjoint short alternating paths using non-reserved vertices
- ③ Connect the paths into long alternating cycles via reserved vertices

Inspired by [Aldous '98, Ding '13, Ding-Wu-X.-Yang '21]

Existence of many long augmenting alternating cycles

Two-stage cycle-finding scheme

Reserve a set V of γn planted edges for some small $\gamma > 0$.

- ① Stage 1 (path construction): Find $\Theta(n)$ disjoint short (constant length) alternating paths, using vertices in V^c .

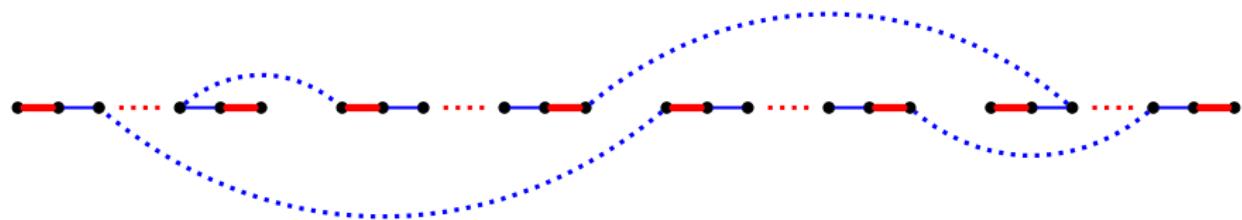


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- ② Stage 2 (sprinkling): Connect the paths into long cycles, using vertices in V .

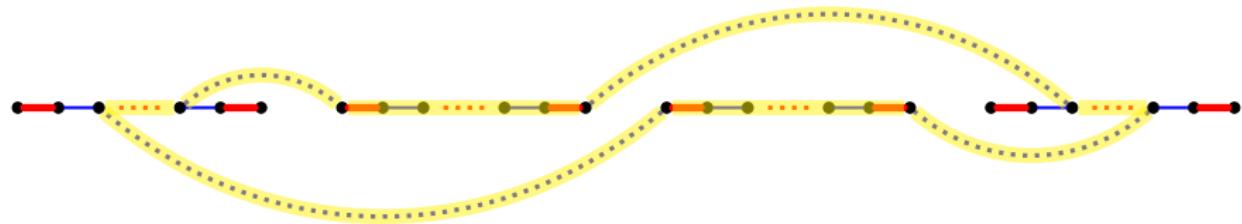


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Reserve a set V of γn planted edges for some small $\gamma > 0$.

- ① Stage 1 (path construction): Find $\Theta(n)$ disjoint short (constant length) alternating paths, using vertices in V^c .
- ② Stage 2 (sprinkling): Connect the paths into long cycles, using vertices in V .

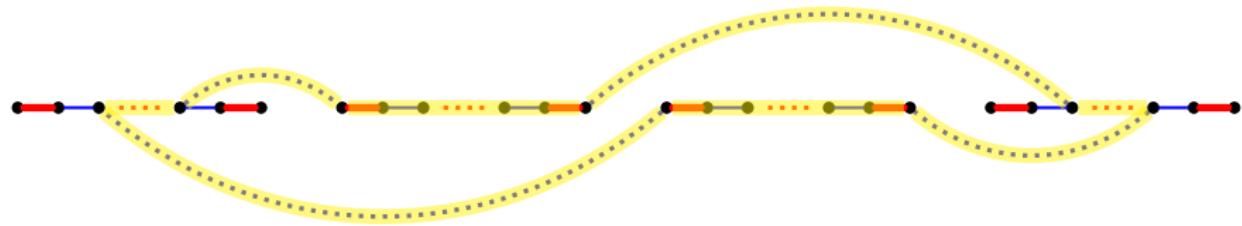


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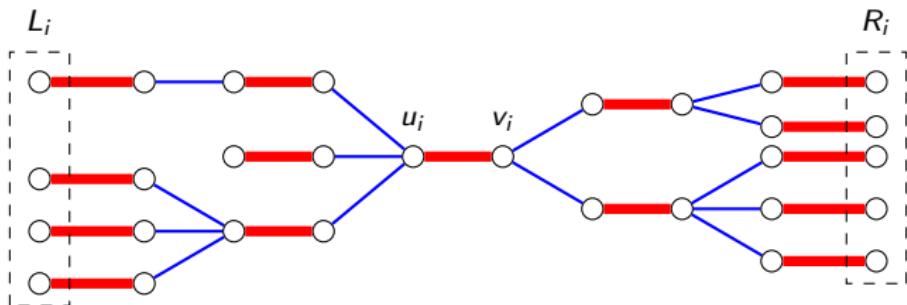
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Caution: need to ensure alternating colors in sprinkling

Path construction via neighborhood exploration process

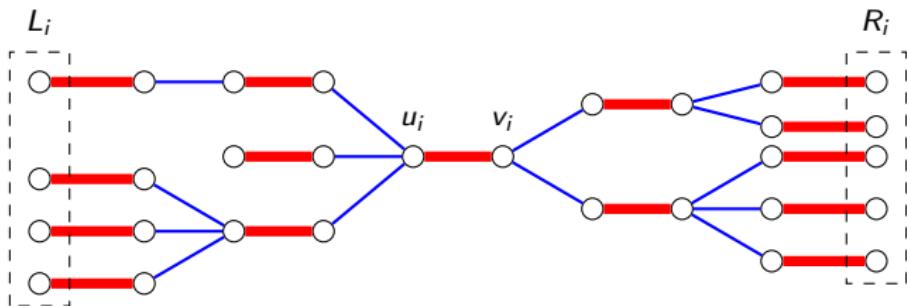
Pick a planted edge (u_i, v_i) , grow a left tree starting from u_i , remove the inspected vertices, and then grow the right tree from v_i



An illustration for $k = 1$. For $k > 1$, need to branch out all k red edges

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When $\lambda k > 1$, the branching processes survive with constant probability. Thus the BFS returns $K = \Omega(n)$ two-sided trees with many leaf nodes.