Information-theoretic bounds and phase transitions in clustering, sparse PCA, and submatrix localization

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- 1 Sparse, spiked Wigner model
- Extensions
- **3** Conclusions and remarks

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• 
$$v_i^{*\text{i.i.d.}} \sim (1-p)\delta_0 + \frac{p}{2}\delta_1 + \frac{p}{2}\delta_{-1}$$
 for a fixed  $p \in [0,1]$ 

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 for a fixed  $p \in [0,1]$ 

•  $||v^*||_0 \approx np$ : sparse level p



#### Of course not ordered



Sparse principal component analysis: [Johnstone-Lu 09], [Amini-Wainwright 09]...

$$Y = \frac{\lambda}{\sqrt{n}} u(v^*)^\top + W,$$

- $v^* \in \mathbb{R}^d$ : sparse principal component
- W: Gaussian random matrix with i.i.d. entres

# Motivation 2: Submatrix localization

Submatrix localization [Kolar-Balakrishnan-Rinaldo-Singh 11] [Butucea-Ingster 13] ...



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#### Row sum statistic is uninformative

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• Estimation: 
$$\mathbb{E}\left[\left(\frac{1}{n}\langle \hat{v}, v^* \rangle\right)^2\right] \geq \epsilon$$

• Detection:

$$\mathcal{H}_0: Y = W$$
 v.s.  $\mathcal{H}_1: Y = \frac{\lambda}{\sqrt{n}} v^* (v^*)^\top + W$ 

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#### Main Questions

- When is estimation or detection informationally possible?
- Is IT-limit achievable in polynomial-time?

## Prior work: Spectral phase transition [Péché 06]

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Approximate message passing algorithm: [Thouless-Anderson-Palmer 77] [Rangan-Fletcher 12], [Deshpande-Montanari 14], [Lesieur-Krzakala-Zdeborová 15]

Conjecture (Lesieur-Krzakala-Zdeborová 15)

There exists  $p^* \in (0,1)$  such that

- 1 If  $p \ge p^*$ , then the IT limit is  $\lambda p = 1$ .
- If p < p\*, then the computational limit is λp = 1, but the IT-limit is strictly lower.</li>

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IT-limit is below the spectral limit if  $p \le 0.054$ .

# Proof of upper bound: First moment method

Maximum likelihood estimation (MLE):

$$\hat{v} \in rg \max_{v} v^{\top} Y v$$
  
s.t.  $\|v\|_{0} \le np(1 + \epsilon_{n})$   
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• Estimation: show  $\frac{1}{n} |\langle \hat{v}, v^* \rangle| \ge \delta$ ; it suffices to show

$$\max_{v:|\langle v,v^*\rangle| \le n\delta} v^\top Y v < (v^*)^\top Y v^*$$

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• Detection: show

$$\max_{v} v^{\top} Y v \text{ under } \mathcal{H}_0 \quad < \quad (v^*)^{\top} Y v^* \text{ under } \mathcal{H}_1$$

Detection and estimation are information-theoretically impossible, if

$$\lambda p < \sqrt{2p \ \mathcal{W}\left(\frac{1-p}{2\sqrt{e}p}\right)}$$

where  $\mathcal{W}(y)$  is the root x of  $xe^x = y$ .

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When  $p \to 0$ 

- IT-upper limit:  $\lambda p > 2\sqrt{-p\log p + O_p(p)}$
- IT-lower limit:  $\lambda p < \sqrt{-2p \log p - O_p(p)}$
- Closed the gap of  $\sqrt{2}$  [Verzelen 16]

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- For estimation, it holds for Gaussian noise model (I-MMSE formula)
- In sparse, spiked Wigner model,

$$\mathbb{E}_{Y \sim Q}\left[\left(\frac{P(Y)}{Q(Y)}\right)^2\right] \approx \mathbb{E}\left[\exp\left(\frac{\lambda^2 R^2}{2n}\right)\right]$$

where R is a T-step, symmetric random walk, where  $T \sim \mathrm{Hyp}(n,np,p)$  [Cai-Ma-Wu 15].

# Conjectured IT-limit

Conjecture (Lesieur-Krzakala-Zdeborová 15)

$$\lim_{n \to \infty} \frac{1}{n} I(v^*; Y) = \min_{\alpha \in [0, p]} i_{\mathrm{RS}}(\alpha; \lambda, p)$$

Moreover, let  $\alpha^*(\lambda, p)$  denote the smallest minimizer. Then the IT-limit for estimation is  $\lambda^*(p) = \inf \{\lambda : \alpha^*(\lambda, p) > 0\}.$ 

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Bethe mutual information  $i_{RS}$  (replica methods [Sherrington-Kirkpatrick 75] or cavity methods [Mezard-Parisi-Virasoro 86])

$$i_{\rm RS}(\alpha) = \frac{\lambda^2 (p^2 + \alpha^2)}{4} - \mathbb{E} \log \left( 1 - p + p e^{-\alpha \lambda^2/2} \cosh \left( \alpha \lambda^2 \eta + \sqrt{\alpha} \lambda z \right) \right)$$
  
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The corner case p = 1 is proved in [Deshpande-Abbe-Montanari 15]





IT limit falls below spectral limit if  $p \leq 0.085$ . Why?

Statistical physics picture: dense regime (p = 0.1)

 $\lambda p = 0.9$  (Below spectral limit)

0.33  $i(\alpha)$ -i(α) 0.26 0.315 0.31 0.24 0.305 0.23 0.3 0.295 0.21 0.2 0.29 0.01 0.02 0.03 0.04 0.05 0.06 0.07 0.08 0.09 0 0.01 0.02 0.03 0.04 0.05 0.06 0.07 0.08 α α  $\alpha^* = 0$  $\alpha^* > 0$ 

 $\lambda p = 1.1$  (Above spectral limit)

0.09

# Statistical physics picture: sparse regime (p = 0.01)





 $\lambda p = 0.5$  (Informative: spinodal)



 $\lambda p = 0.47$  (Uninformative: spinodal)



 $\lambda p = 1.01$  (Above spectral limit)



# Conjectured "possible but hard" regime [Lesieur-Krzakala-Zdeborová 15]



# Proof of conjectured upper bound to mutual information

#### Theorem (Krzakala-X.-Zdeborová 16)

$$\frac{1}{n}I(v^*;Y) \le \min_{\alpha \in [0,p]} i_{\rm RS}(\alpha;\lambda,p)$$

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- Upper bound holds for any finite n
- Asymptotic, matching lower bound is proved in [Barbier-Dia-Macris-Krzakala-Lesieur-Zdeborová 16] under the assumption that  $i_{\rm RS}(\alpha)$  has at most three stationary points

# Proof ideas: Interpolation method [Guerra 03]

• A simple denoising model:  $y = \sqrt{\alpha}\lambda v^* + w$ , where  $w \sim \mathcal{N}(0, \mathbf{I}_{n \times n})$ 

$$\frac{1}{n}I(v^*;y) = I(v_1^*;y_1) = i_{\rm RS}(\alpha;\lambda,p) - \frac{(p-\alpha)^2\lambda^2}{4}$$

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• Interpolating between the denoising model and the Wigner model

$$Y_t = \frac{\sqrt{t\lambda}}{\sqrt{n}} v^* (v^*)^\top + W$$
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Let  $I_t = I(v^*; Y_t, y_t)$ . Then  $I_0 = I(v^*; y)$  and  $I_1 = I(v^*; Y)$ .

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• Show that

$$\frac{1}{n}\frac{\mathrm{d}I_t}{\mathrm{d}t} \le \frac{(p-\alpha)^2\lambda^2}{4} \Longrightarrow \frac{1}{n}I_1 \le i_{\mathrm{RS}}(\alpha;\lambda,p)$$

- 1 Sparse, spiked Wigner model
- Extensions
- **3** Conclusions and remarks

## Extension 1: general channel output and prior

$$X = \frac{\lambda}{\sqrt{n}} v^* (v^*)^\top \longrightarrow p_{\text{out}}(y|x) \longrightarrow Y$$

$$v_i \stackrel{\text{i.i.d.}}{\sim} p_{\text{prior}}$$

• 
$$Y_{ij} \overset{\text{i.i.d.}}{\sim} p_{\text{out}}(\cdot|X_{ij})$$
 for  $i \leq j$ 

•  $p_{\mathrm{prior}}$  and  $p_{\mathrm{out}}$  are assumed to be independent of n

Suppose  $p_{\rm prior}$  has a finite support and  $\log p_{\rm out}(y|x)$  satisfies some mild regularity conditions. Then

$$I(X;Y) = I(X;X + \sqrt{\Delta}W) + O(\sqrt{n})$$

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•  $\Delta$  is the inverse Fisher information

$$\frac{1}{\Delta} \triangleq \mathbb{E}_{p_{\text{out}}(y|0)} \left[ \left( \frac{\partial \log p_{\text{out}}(y|x)}{\partial x} \Big|_{y,0} \right)^2 \right]$$

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- The proof relies on Lindeberg's principle

$$X = \frac{\operatorname{snr}}{\sqrt{n}} \begin{bmatrix} U_1^\top \\ U_2^\top \\ \vdots \\ U_m^\top \end{bmatrix} \begin{bmatrix} V_1 & V_2 & \cdots & V_n \end{bmatrix} \longrightarrow \begin{array}{c} p_{\operatorname{out}}(y|x) & \longrightarrow & Y \end{bmatrix}$$

• 
$$U_i \in \mathbb{R}^k \stackrel{\text{i.i.d.}}{\sim} p_{\text{prior}}$$
 and  $V_j \in \mathbb{R}^k \stackrel{\text{i.i.d.}}{\sim} q_{\text{prior}}$ 

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- Proposed in [Lesieur-Krzakala-Zdeborová 15]

## Special case 1: Submatrix localization with k blocks





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 $U_i$  is i.i.d. uniformly drawn from  $\{e_1, \ldots, e_k\}$ 

## Upper and lower bounds for submatrix localization

#### Theorem

#### Let

$$\mu^{\rm up} = 2k\sqrt{\frac{\log k}{k-1}}$$
$$\mu^{\rm low} = k\sqrt{\frac{2\log(k-1)}{k-1}}$$

Then detection and reconstruction are information-theoretically possible when  $\mu > \mu^{up}$  and impossible when  $\mu < \mu^{low}$ .

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- When k is large, upper and lower bounds differ by a factor of  $\sqrt{2}$
- When  $k \ge 11$ , IT limit is below the spectral limit  $\mu^{\text{spectral}} = k$
- When k=2,  $\mu^{\rm low}=\mu^{\rm spectral}=\mu^{\rm IT}=2$

## Special case 2: Gaussian mixture clustering with k clusters



• 
$$v_1, \ldots, v_k \overset{\text{i.i.d.}}{\sim} \mathcal{N}(0, \mathbf{I}_{n \times n})$$
 and  $\bar{v} = (1/k) \sum_s v_s$ 

## Special case 2: Gaussian mixture clustering with k clusters

$$Y_{m \times n} = \sqrt{\frac{\rho}{n}} \qquad \begin{array}{c} v_1 - \bar{v} \\ \hline v_2 - \bar{v} \\ \hline \vdots \\ \hline v_k - \bar{v} \end{array} \qquad + \quad W_{m \times n}$$

- $v_1, \ldots, v_k \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \mathbf{I}_{n \times n})$  and  $\bar{v} = (1/k) \sum_s v_s$
- Cluster center separation  $\approx \sqrt{2n\rho}$
- Let  $m = \alpha n$  for a fixed  $\alpha > 0$

# Upper and lower bounds for Gaussian mixture clustering

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$$\rho^{\rm up} = \frac{2k}{k-1} \left( \sqrt{\frac{k\log k}{\alpha}} + \log k \right)$$
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# Upper and lower bounds for Gaussian mixture clustering

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Then detection and reconstruction are possible when  $\rho > \rho^{up}$  and impossible when  $\rho < \rho^{low}$ .

- When k is large, upper and lower bounds differ by a factor of  $\sqrt{2}$
- When  $k \ge 26$ , IT limit is below the spectral limit  $\rho^{\text{spectral}} = \frac{k}{\sqrt{\alpha}}$

• When 
$$k=2$$
,  $ho^{
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 First and second moment method: powerful tools to locate IT-limit [Abbe-Sandon 15] [Banks-Moore-Neeman-Netrapalli 16]



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- Channel universality and Interpolation method



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- Channel universality and Interpolation method
- Open question: computational limit?

#### <u>References</u>

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- F. Krzakala & J. X. & L. Zdeborová (2016). Mutual Information in Rank-One Matrix Estimation. arXiv:1603.08447 (ITW '16)

# Dense regime: p = 0.1





### Dense regime: p = 0.1



Second-order phase transition: discontinuity of 2nd derivative of  $i_{RS}(\alpha^*)$ IT limit coincides with spectral limit; similar to binary symmetric SBM

# Sparse regime: p = 0.01



First-order phase transition: discontinuity of 1st derivative of  $i_{RS}(\alpha^*)$ IT limit falls below spectral limit; similar to SBM with k > 4 communities